

Memory Management

Arvind Krishnamurthy
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Memory Management

To support multiprogramming, we need "Protection"

- How to implement an address space?

Physical memory	Abstraction: virtual memory
No protection	Each program isolated from all others and from the OS
Limited size	Illusion of infinite memory
Sharing visible to programs	Transparent --- can't tell if memory is shared
Easy to share data between programs	Controlled sharing of data

OS Evolutionary Path

- Uniprogramming without protection
- Multiprogramming without protection: linker-loader
- Multiprogrammed OS with protection:
 - hardware-based approach
 - address translation (support of address space)
 - dual mode operation: kernel vs. user mode
 - software-based approach
 - type-safe languages
 - software fault isolation

Uniprogramming (no protection)

- Application runs at the same place in physical memory
 - load application into low memory
 - load OS into high memory
 - application can address any physical memory location
 - application can corrupt OS and even the disk

Multiprogramming

- Multiple programs share physical memory
 - when copying a program into memory, use the **linker-loader** to change the addresses for all load/store/jump instructions

Linker-loader Approach

- How the linker-loader works?
 - Compiler generates .o file with code starting at location 0.
 - Also record all the re-locatable addresses
 - Linker (ld in Unix) scans through each .o, changing addresses to point to where each module goes in larger program
 - Loader loads the executable (a.out) to the memory and program runs

Linker-Loader example

```
int y;
extern int z;

int foo() {
  int x;

  bar();
  y = 1;
  z = 1;
}
[foo.c]
```

```
int z;

void bar() {
  z = 99;
}

main() {
  foo();
}
[bar.c]
```

Link: Need to patch references to "bar", "foo", and "z"

Load: Need to relocate all addresses based on what programs are running

- Problem of linker-loader --- still no protection: bugs in any program can cause other programs to crash, even OS
- Goal: how to support protection?

Incorporating Protection

- Goal of protection
 - keep user programs from crashing/corrupting OS
 - keep user programs from crashing/corrupting each other

How is protection implemented?

- Almost all OS today use hardware-based approach
 - address translation
 - dual mode operation: kernel vs. user mode
- Other approaches: software-based solutions
 - type safe languages
 - software fault isolation

Address translation (1)

- **Address space:** state of an active program
 - Hardware translates every memory reference from virtual addresses to physical addresses
 - Software sets up and manages the mapping in the translation box

```

graph LR
    CPU((CPU)) -- virtual address --> MMU[Translation Box (MMU)]
    MMU -- physical address --> PM[physical memory]
    CPU <--> |Data read or write| PM
  
```

- Protection: there is no way for programs to talk about other program's addresses

Why dual mode operation ?

- If application can modify its own translation tables --- then it can access all of physical memory --- protection is lost!
- Solution: use "dual-mode" operation
 - when in the OS, can do anything (**kernel-mode**)
 - when in a user program, restricted to only touching that program's memory (**user-mode**)

HW can require CPU to be in kernel-mode to modify address translation table

- In Nachos (as well as most OS's):
 - OS runs in kernel mode (untranslated addresses)
 - User programs run in user mode (translated addresses)
- How does one switch between kernel and user modes?

Kernel → user

- The most basic of kernel-to-user transitions occur when a new user program is started by the system
- In a traditional OS, what steps are involved in starting a new user program?

User → kernel

How does the user program get back into the kernel ?

- **Hardware interrupt** (involuntarily)
 - timer interrupt, IO interrupt, etc.
- **Program exception** (involuntarily)
 - bus error (bad address --- e.g., unaligned access)
 - segmentation fault (out of range address)
 - page fault (important for providing illusion of infinite memory)
- **System call** (voluntarily)
 - special instruction to jump to a specific OS handler – just like doing a procedure call into the OS kernel
 - on MIPS, it is called "OP_SYSCALL"

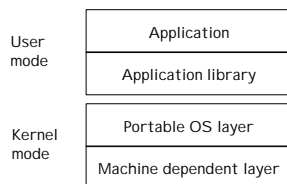
Issues with system call

- Can the user program call any routine in the OS ?
 - No. Only the specific ones that the OS says are ok.
- How to pass arguments on a system call?
 - via registers
 - write data into user memory, kernel copies into its memory
 - except: user addresses --- translated
 - kernel addresses --- untranslated
 - **main problem:** addresses the kernel sees are not the same addresses as what the user sees
- What if user programs does a system call with bad arguments? OS must check everything

User → kernel: how to switch

- On system call, interrupt exception and the system
 - sets processor status to kernel mode
 - changes execution stack to an OS kernel stack
 - saves current program counter
 - jumps to handler routine in OS kernel
 - handler saves previous state of any register it uses
- Context switches between programs:
 - same as with threads, except
 - also save and restore pointer to translation table
 - to resume a program: reload registers, change PSW, and jump to old PC.

OS Structure



- How does Nachos's structure fit into this model?
 - Nachos is the portable OS layer – it simulates the hardware and machine-dependent layer, and it simulates the execution of user programs running on top
 - Can still use debugger, printf, etc.
 - Can run normal UNIX programs concurrently with Nachos
 - Could run Nachos on real hardware by writing a machine-dependent layer