

# Program Synthesis by Sketching

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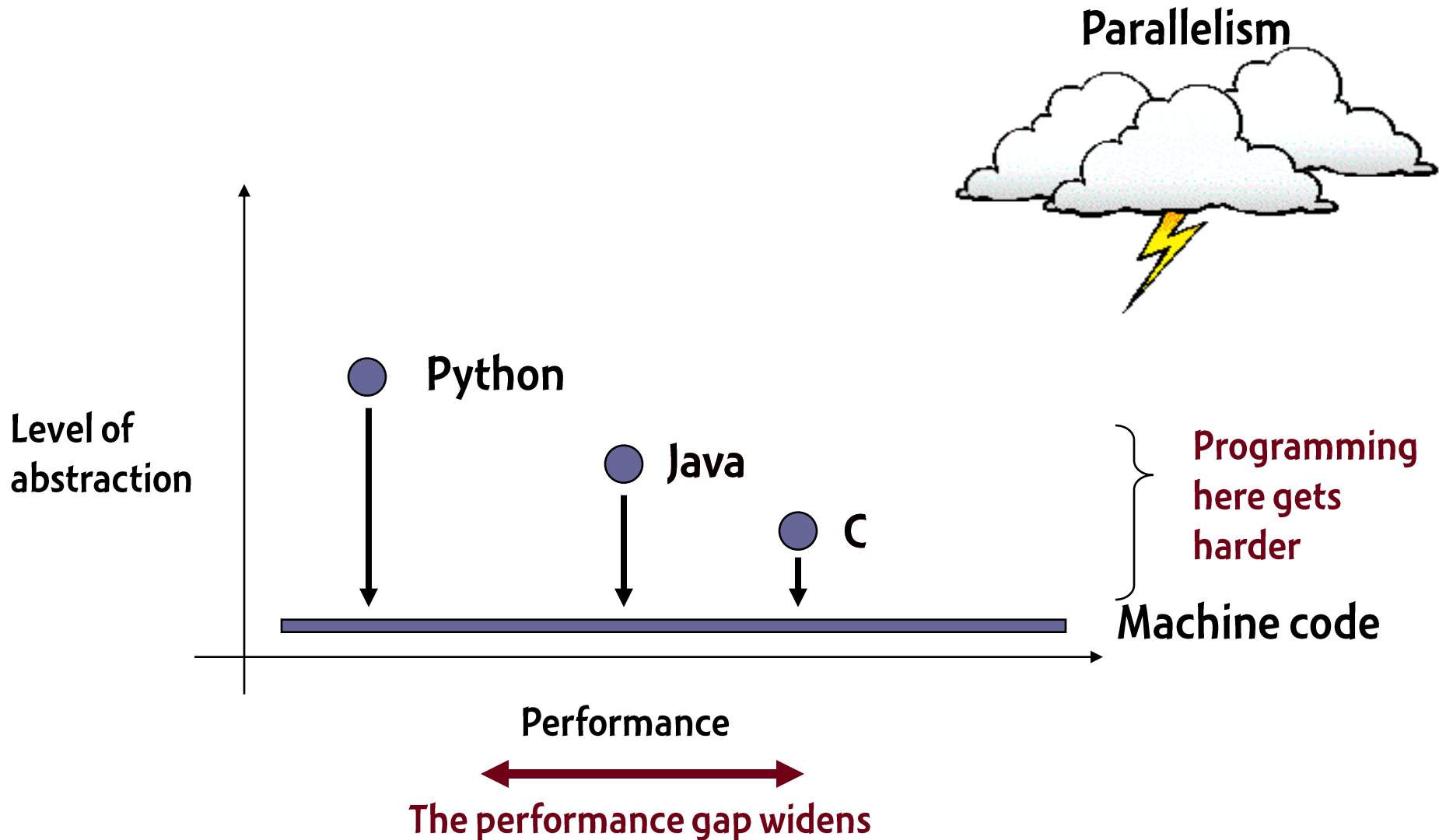
# Synthesis

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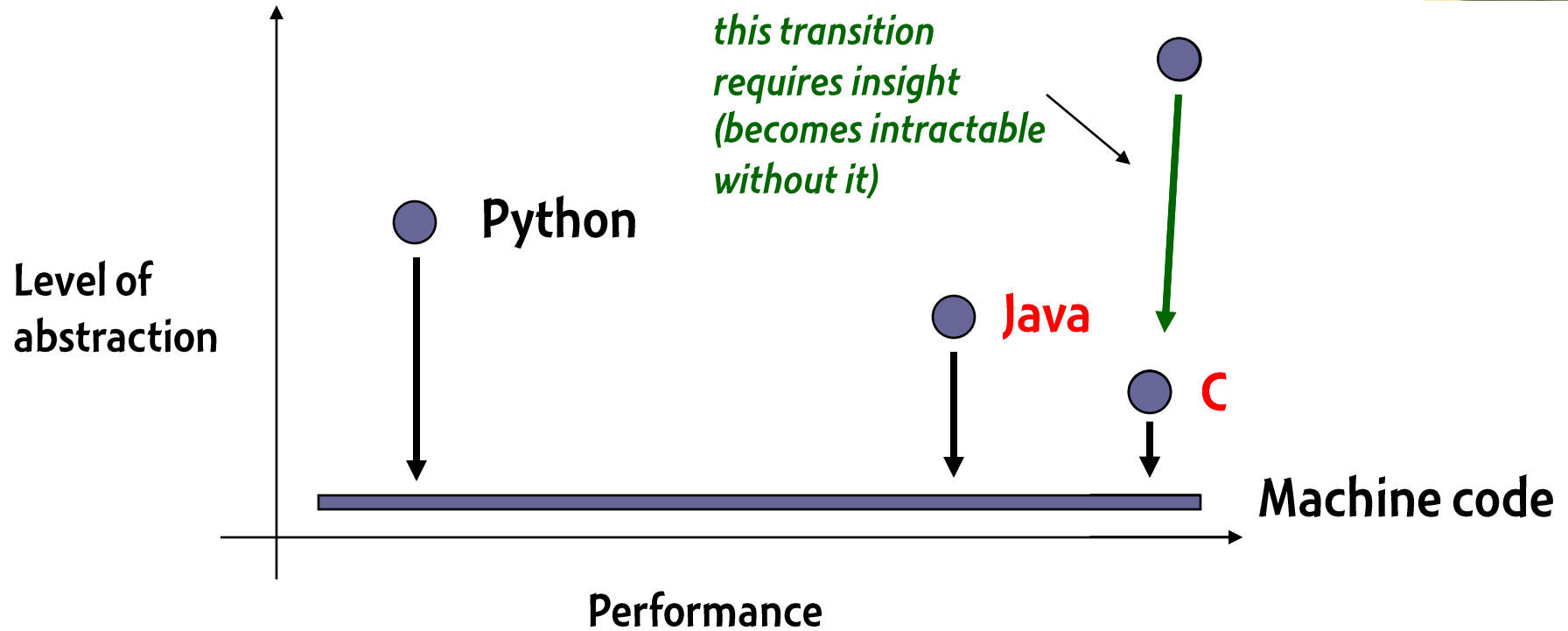
The promise: Automate program development



# Abstraction Vs. Performance tradeoff



# Software synthesis could help



# Software synthesis could help

DSLs:

- StreamIt
- AutoBayes

Generators

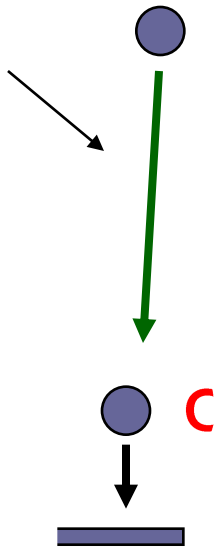
- FFTW

Synthesizers

- PRL
- KIDS

- hard-coded heuristics
- domain specific transformations

- interactive proofs
- domain theories



Axiomatic definitions of Types and functions that may be used in the solution

Ex:  $\text{merge}(c, d, b) \Leftrightarrow (\text{ordered}(c) \wedge \text{ordered}(d)) \Rightarrow (\text{perm}(c \cdot d, b) \wedge \text{ordered}(b))$

# Software synthesis could help

DSLs:

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- AutoBayes

Generators

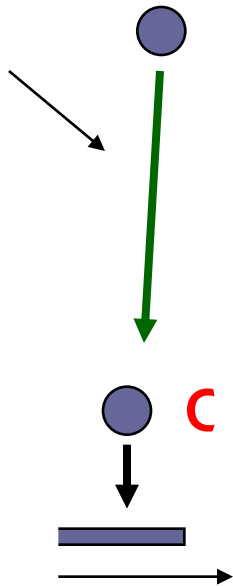
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Synthesizers

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- interactive proofs
- domain theories

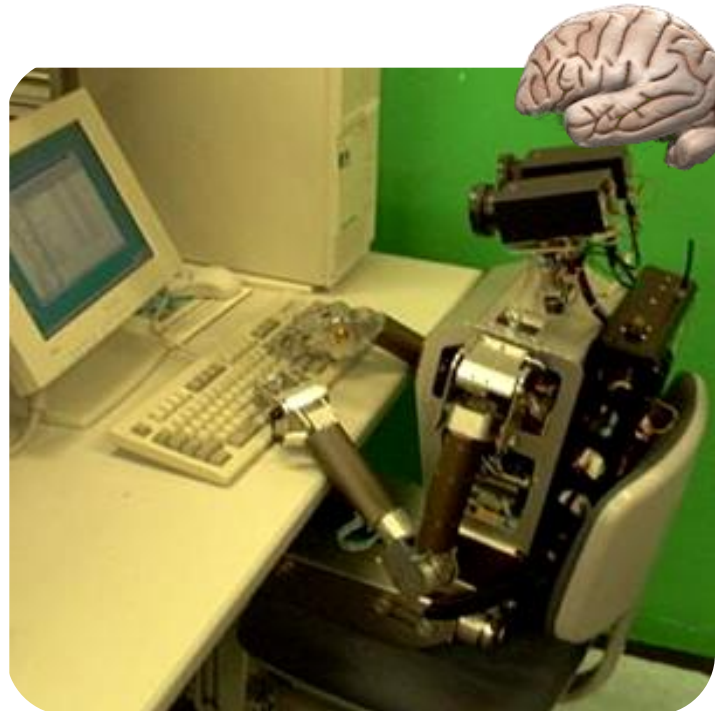


It's hard for users to help

- hacking the synthesizer is very hard
- writing domain theories is very hard

# The Challenge

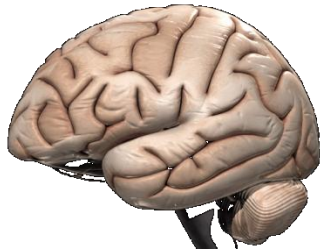
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# Challenge

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**Establish a synergy between synthesizer and user**



**Insight**  
**Big picture**  
**Strategy**



**Exhaustive exploration**  
**Details**  
**Tactics**



# Research problems

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Programmers must be able to contribute **expertise**

- How can the programmer contribute insights?
- How can we use these insights to make synthesis scalable?

Programmers want **control** over the implementation

- Can we avoid exposing programmers to synthesizer's internals?

Programmers **insight** will sometimes be **wrong**

- How can we support debugging

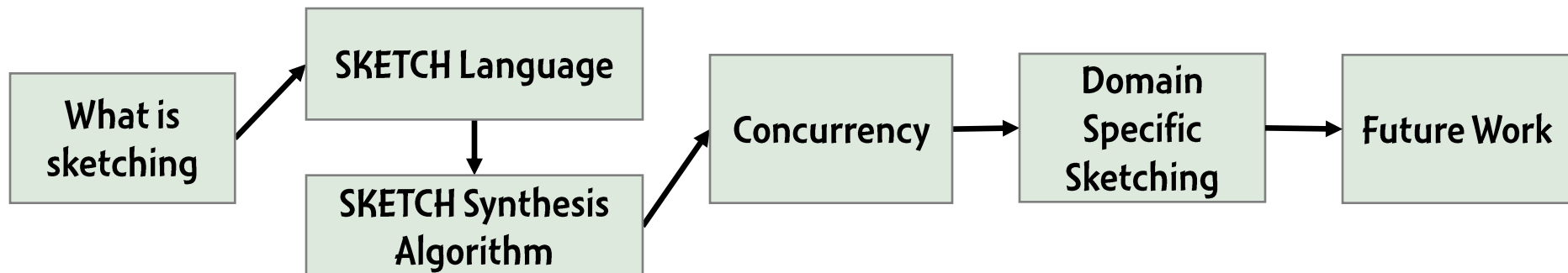
# Sketching

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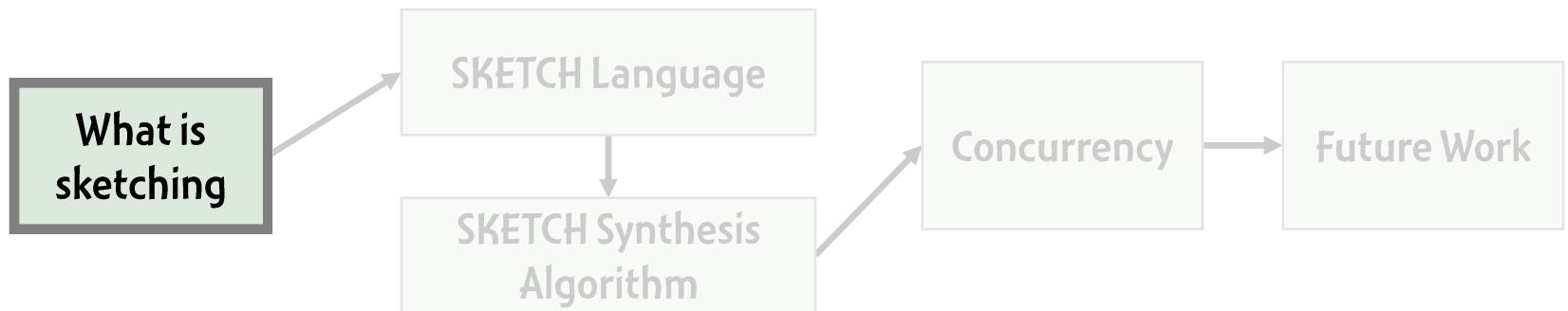
Our answer to the challenges of practical synthesis

Key Contributions:

- Synthesis from partial programs PLDI 05
- Design of the SKETCH language ASPLOS 06
- SKETCH Synthesis algorithm ASPLOS 06
- Generalization to Concurrent Programs PLDI 08
- Domain Specific Sketching through Program Reduction PLDI 07



# The Sketching Approach



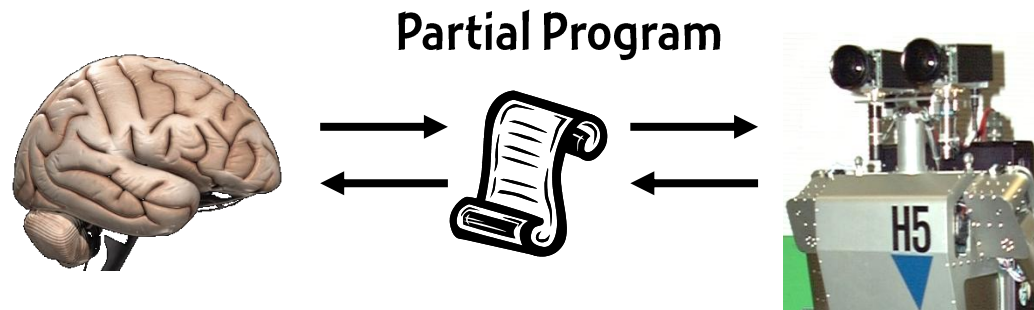
# Key Observation

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**Insight and Mechanics are both reflected in the source code**

## The Sketch solution:

- Write only the code corresponding to insight
- Let the synthesizer derive the mechanics



# Merge sort: first, by hand

---

```
int[] mergeSort (int[] input, int n) {
    if ( n == 1 ) return input;
    return merge(    mergeSort (input[0:n/2-1], n/2),
                    mergeSort (input[n/2:n-1], n-n/2), n);
}

int[] merge (int[] a, int b[], int n) {
    int j=0; int k=0;
    for (int i = 0; i < n; i++)
        if ( a[j] < b[k] )
            result[i] = a[j++];
        else
            result[i] = b[k++];
    return result;
}
```

**looks simple to code,  
but there is a bug**

# Merge sort: **corrected**, by hand

---

```
int[] mergeSort (int[] input, int n) {
    if ( n == 1 ) return input;
    return merge(      mergeSort (input[0:n/2-1], n/2),
                      mergeSort (input[n/2:n-1], n-n/2), n);
}

int[] merge (int[] a, int b[], int n) {
    int j=0; int k=0;
    for (int i = 0; i < n; i++)
        if ( j<n/2 && ( !(k<n-n/2) || a[j]<b[k]) ) )
            result[i] = a[j++];
        else
            result[i] = b[k++];
    return result;
}
```

# Merge sort: **sketched**

```
int[] mergeSort (int[] input, int n) {  
    if ( n == 1 ) return input;  
    return merge(    mergeSort (input[0:n/2-1], n/2),  
                    mergeSort (input[n/2:n-1], n-n/2), n);  
}  
  
int[] merge (int[] a, int b[], int n) {  
    int j=0; int k=0;  
    for (int i = 0; i < n; i++)  
        if ( hole )  
            result[i] = a[j++];  
        else  
            result[i] = b[k++];  
    return result;  
}
```



# Which would a programmer prefer?

```
int[] mergeSort (int[] input, int n) {
  if ( n == 1 )
    return input;
  return merge(
    mergeSort (input[0:n/2-1], n),
    mergeSort (input[n/2:n-1], n-n/2)
    , n);
}

int[] merge (int[] a, int b[], int n) {
  int j=0; int k=0;
  for (int i = 0; i < n; i++)
    if ( hole )
      result[i] = a[j++];
    else
      result[i] = b[k++];
  return result;
}
```

```
int[] sort (int[] input, int n) {
  for (int i=0; i<n; ++i)
    for (int j=i+1; j<n; ++j)
      if (input[j] < input[i])
        swap(input, j, i);
  return input;
}
```

**Theory** *Sorting*( $\{\alpha, \leq\}$  : linear - order)

**Imports** *integer*, *bag*( $\alpha$ ), *seq*( $\alpha$ )

**Operations**

*Ordered* : *seq*( $\alpha$ )  $\rightarrow$  *Boolean*

**Axioms**

$\forall(S : seq(\alpha)) (Ordered(S) \Leftrightarrow \forall(i)(i \in \{1..length(S) - 1\} \implies S(i) \leq S(i + 1)))$

**Theorems**

*Ordered*([]) = *true*

$\forall(a : \alpha) (Ordered([a]) = true)$

$\forall(y_1 : seq(\alpha), y_2 : seq(\alpha))$

$(Ordered(y_1 + y_2) \Leftrightarrow Ordered(y_1)$

$\wedge Seq\text{-to-bag}(y_1) \leq Seq\text{-to-bag}(y_2)$

$\wedge Ordered(y_2))$

**end-theory**

**Theory** *Divide-and-Conquer*

**Sorts** *D*, *R*

**Operations**

*I* : *D*  $\rightarrow$  *Boolean*

*O* : *D*  $\times$  *R*  $\rightarrow$  *Boolean*

*primitive* : *D*  $\rightarrow$  *Boolean*

*O*<sub>Decompose</sub> : *D*  $\times$  *D*  $\times$  *D*  $\rightarrow$  *Boolean*

*O*<sub>Compose</sub> : *R*  $\times$  *R*  $\times$  *R*  $\rightarrow$  *Boolean*

$\succ$  : *D*  $\times$  *D*  $\rightarrow$  *Boolean*

**Soundness Axiom**

$O_{Decompose}(x_0, x_1, x_2)$

$\wedge O(x_1, z_1) \wedge O(x_2, z_2)$

$\wedge O_{Compose}(z_0, z_1, z_2)$

$\implies O(x_0, z_0)$

...

**end-theory**

*Seq-to-bag*([]) = {}

$\forall(a : \alpha) Seq\text{-to-bag}([a]) = \{a\}$

$\forall(y_1 : seq(\alpha), y_2 : seq(\alpha))$

$Seq\text{-to-bag}(y_1 + y_2) = Seq\text{-to-bag}(y_1) \text{ d } Seq\text{-to-bag}(y_2)$

$\forall(y_1 : seq(\alpha), y_2 : seq(\alpha))$

$Seq\text{-to-bag}(y_1 \text{ ilv } y_2) = Seq\text{-to-bag}(y_1) \text{ d } Seq\text{-to-bag}(y_2)$

*O*<sub>Decompose</sub>  $\mapsto \lambda(b_0, b_1, b_2) b_0 = b_1 \text{ d } b_2$

*O*  $\mapsto \lambda(b, z) b = Seq\text{-to-bag}(z) \wedge Ordered(z)$

...

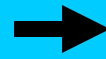


# The sketching experience

---

*spec*

+



specification

sketch

implementation  
(completed sketch)

# The spec: bubble sort

---

```
int[] sort (int[] input, int n) {
    for (int i=0; i<n; ++i)
        for (int j=i+1; j<n; ++j)
            if (input[j] < input[i])
                swap(input, j, i);
    return input;
}
```

# Merge sort: **sketched**

```
int[] mergeSort (int[] input, int n) {  
    if ( n == 1 ) return input;  
    return merge(    mergeSort (input[0:n/2-1], n/2),  
                    mergeSort (input[n/2:n-1], n-n/2), n);  
}  
  
int[] merge (int[] a, int b[], int n) {  
    int j=0; int k=0;  
    for (int i = 0; i < n; i++)  
        if (                 hole                 )  
            result[i] = a[j++];  
        else  
            result[i] = b[k++];  
    return result;  
}
```



# Merge sort: **sketched**

```
int[] mergeSort (int[] input, int n) {  
    if ( n == 1 )  
        return mergeSort (input, n);  
    mergeSort (input, n/2);  
    mergeSort (input, n/2);  
}
```

Challenge: how to help **scalability**?

```
int[] merge (int[] a, int[] b, int n) {  
    int j=0; int k=0;  
    for (int i = 0; i < n; i++)  
        if ( expr(<,&&,||,!,-,[])(a, b, j, k, n, n/2 ) )  
            result[i] = a[j++];  
        else  
            result[i] = b[k++];  
    return result;  
}
```

Challenge: **control** over synthesized code



# Merge sort: synthesized

---

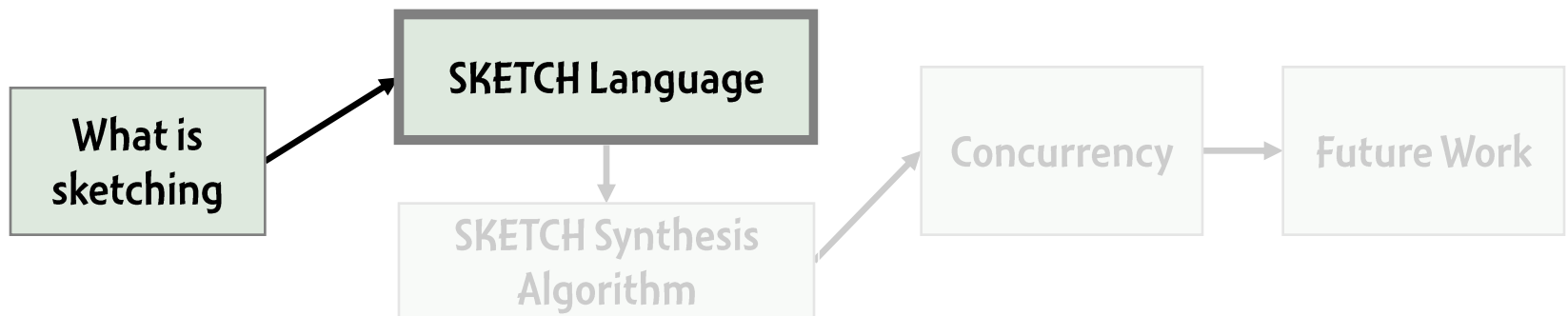
```
int[] mergeSort (int[] input, int n) {
    if ( n == 1 ) return input;
    return merge(    mergeSort (input[0:n/2-1], n),
                    mergeSort (input[n/2:n-1], n-n/2), n);
}

int[] merge (int[] a, int b[], int n) {
    int j=0; int k=0;
    for (int i = 0; i < n; i++)
        if ( j<n/2 && ( !(k<n-n/2) || a[j]<b[k]) )
            result[i] = a[j++];
        else
            result[i] = b[k++];
    return result;
}
```



# The SKETCH Language

## PLDI 05, ASPLOS 06



# Language design goals

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## Learnable

- Embed easily into a known language

## Expressive

- allow programmer to express different insights about holes

## Induces a simple synthesis problem

- ideally, domain independent

# SKETCH: two simple constructs

---

*spec:*

```
int foo (int x)
{
    return x + x;
}
```

*sketch:*

```
int bar (int x) implements foo
{
    return x << ??;
}
```

*result:*

```
int bar (int x) implements foo
{
    return x << 1;
}
```

Assertions can also be used to define behavior



# Case study 1: Silver Medal in a SKETCH contest

---

## The 4x4-matrix transpose, the specification:

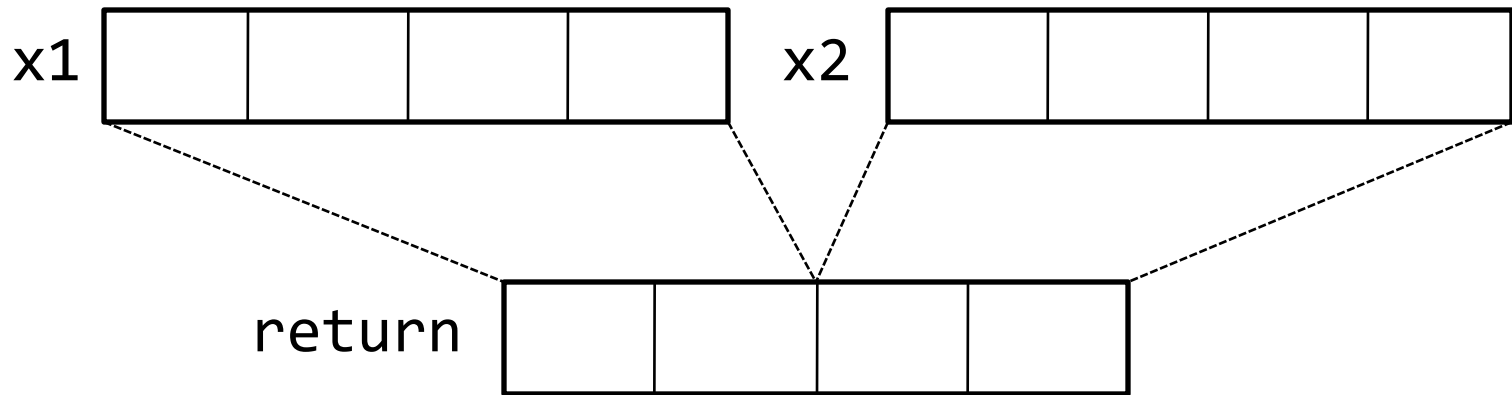
```
int[16] trans(int[16] M) {  
    int[16] T = 0;  
    for (int i = 0; i < 4; i++)  
        for (int j = 0; j < 4; j++)  
            T[4 * i + j] = M[4 * j + i];  
    return T;  
}
```

**Implementation idea: parallelize with SIMD**

# Intel shufps SIMD instruction

---

**SHUFP** (shuffle parallel scalars) expressed in **SKETCH**:



# The SIMD matrix transpose, sketched

```
int[16] trans_sse(int[16] M) implements trans {  
    int[16] S = 0, T = 0;  
    repeat (??) S[??:4] = shufps(M[??:4], M[??:4], ??);  
    repeat (??) T[??:4] = shufps(S[??:4], S[??:4], ??);  
    return T;  
}  
  
int[16] trans_sse(int[16] M) implements trans { // synthesized code  
    S[4::4] = shufps(M[6::4], M[2::4], 11001000b);  
    S[0::4] = shufps(M[11::4], M[6::4], 10010110b);  
    S[12::4] = shufps(M[0::4], M[2::4], 10001101b);  
    S[8::4] = shufps(M[8::4], M[12::4], 11010111b);  
    T[4::4] = shufps(S[11::4], S[1::4], 10111100b);  
    T[12::4] = shufps(S[4::4], S[8::4], 11001000b);  
    T[8::4] = shufps(S[0::4], S[12::4], 10010110b);  
    T[0::4] = shufps(S[12::4], S[8::4], 10111100b);  
}
```

**From the contestant email:** Over the summer, I spent about 1/2 a day manually figuring it out. Synthesis time: 30 minutes.

# Beyond synthesis of constants

---

Sometimes the insight is “I want to complete the hole with an of particular syntactic form.”

- Array index expressions:  $A[ ??*i+??*j+?? ]$
- Polynomial of degree 2 over  $x$ :  $??*x*x + ??*x + ??$

Primitive holes can be used synthesize arbitrary expressions, statements, ...

- we also can make these “generators” reusable

# Reusable expression generators

---

Following function synthesizes to one of  $a$ ,  $b$ ,  $a+b$ ,  $a-b$ ,  $a+b+a$ ,

...

```
inline int expr(int a, int b){ // generator
    switch(??) {
        case 0: return a;
        case 1: return b;
        case 2: return expr(a,b) + expr(a,b);
        case 3: return expr(a,b) - expr(a,b);
    }
}
```

# Synthesizing polynomials

---

```
int spec (int x) {  
    return 2*x*x*x*x + 3*x*x*x + 7*x*x + 10;  
}
```

```
int p (int x) implements spec {  
    return (x+1)*(x+2)*poly(3,x);  
}
```

```
inline int poly(int n, int x) {  
    if (n==0) return ??;  
    else return x * poly(n-1, x) + ??;  
}
```

Notice the absence of any meta-variables. The generator `poly()` is an ordinary function.

*Here, SKETCH performs polynomial division. Result of division is what `poly(3,x)` is synthesized into.*

# Syntactic Sugar

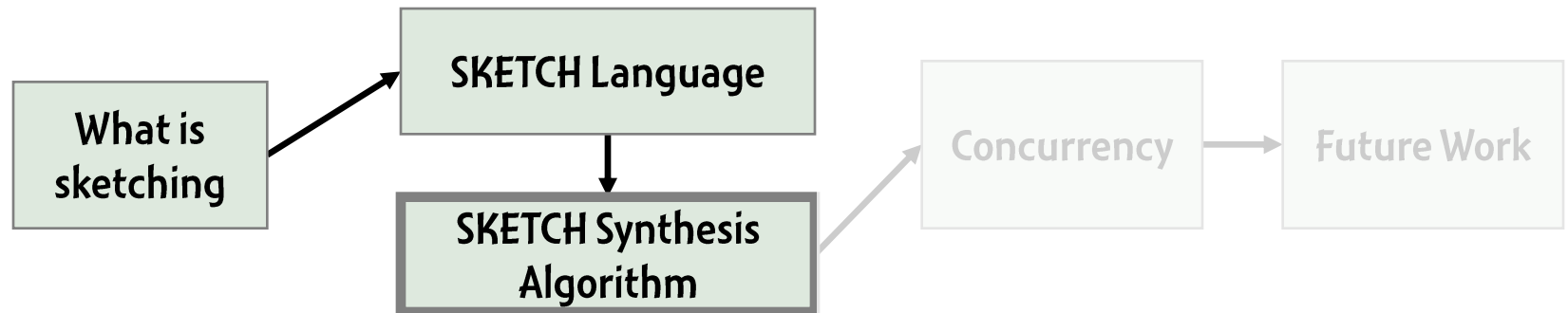
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Easy to add new constructs as syntactic sugar

- `reorder{ s1; s2; ... ; sn; }`

- `x = { | (a | b | c)(.next)? | }`

# The SKETCH Synthesis Algorithm





# Sketch is a set of programs

---

A sketch syntactically describes a set of candidate programs.

- The ?? operator is modeled as a special input, called **control**:

```
bit[W] iso1Sk(bit[W] x) {  
    return ~(x+??) & (x+??);  
}
```

```
bit[W] iso1Sk(bit[W] x, int c1, c2) {  
    return ~(x+c1) & (x+c2);  
}
```

The set is defined in terms of the values of the controls

$S = \{ Sk(c) \text{ where } c \text{ is an assignment to the holes} \}$

# Sketch synthesis = Search

---

Synthesis reduces to a search for the correct candidate

- Search for control values satisfying the following equation:

$$\exists c. \quad \forall x. \quad \text{Spec}(x) = \text{Sk}(x,c)$$

Adding additional insight reduces the search space

for the user, adding insight reduces to writing more code  
programmers know how to do that

# Inductive Synthesis

---

Synthesize from a set of observations

## A little history

- Algorithmic debugging (Shapiro 1982)
- Inductive logic programming (Muggleton 1991)
- Programming by example (e.g. Lau 1999)

## Two big issues

- Convergence: How do you know your solution generalizes
- Efficiency: Deriving a candidate from observations is hard

# Convergence

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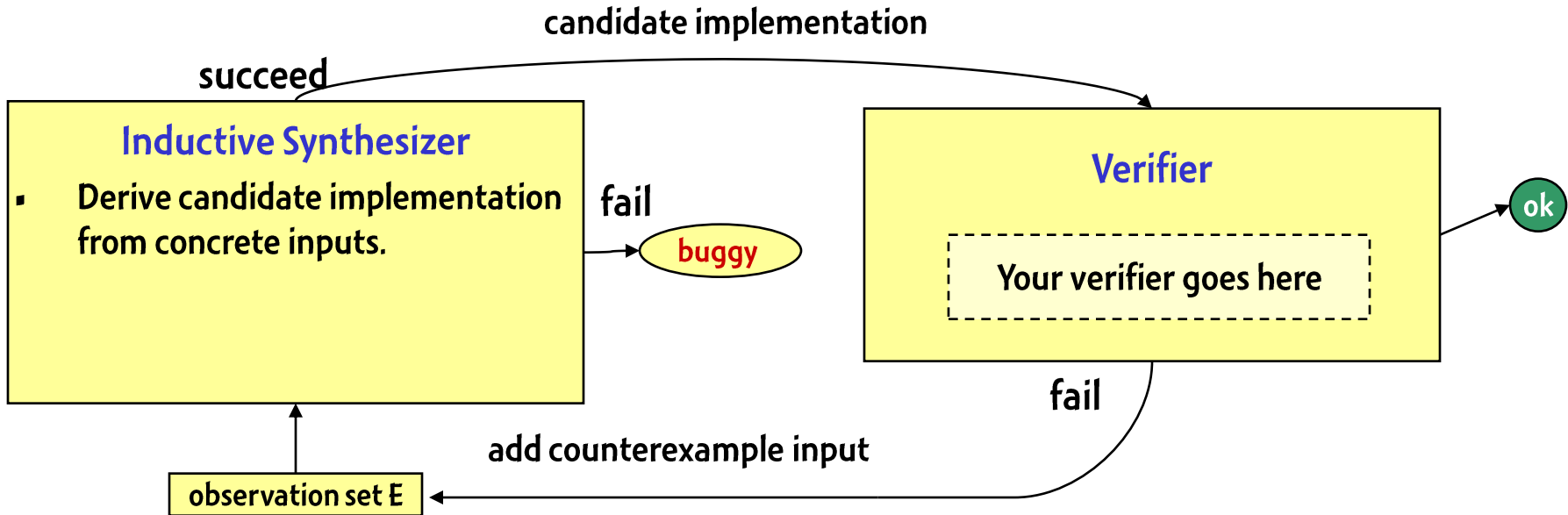
**Idea: Couple Inductive synthesizer with a verifier**

- Verifier is charged with detecting convergence

**Counterexamples make great empirical observations**

- new counterexample → new information

# Convergence



# Convergence

---

**Example: remove an element from a doubly linked list.**

```
void remove(list l, node n){  
    if (cond(l,n)) { assign(l, n); }  
    if (cond(l,n)) { assign(l, n); }  
    if (cond(l,n)) { assign(l, n); }  
    if (cond(l,n)) { assign(l, n); }  
}
```

```
int N = 6;  
void test(int p){  
    nodes[N] nodes;  
    list l;  
    initialize(l, nodes);    //... add N nodes to list  
    remove(l, nodes[p]);  
    checkList(nodes, l, p);  
}
```

# Ex: Doubly Linked List Remove

---

```
void remove(list l, node n)
{
    if(n.prev != l.head)
        n.next.prev = n.prev;

    if(n.prev != n.next)
        n.prev.next = n.next;
}
```

Counterexamples
p = 3

# Ex: Doubly Linked List Remove

---

```
void remove(list l, node n)
{
    if(n.prev != null)
        n.next.prev = n.prev;

    if(l.head == n)
        l.head = n.next;

    l.tail = l.tail;

    if(l.head != n.next)
        n.prev.next = n.next;
}
```

Counterexamples
$p = 3$
$p = 0$



# Ex: Doubly Linked List Remove

---

```
void remove(list l, node n)
{
    if(n.prev == null)
        l.head = n.next;

    if(n.next == null)
        l.tail = n.prev;

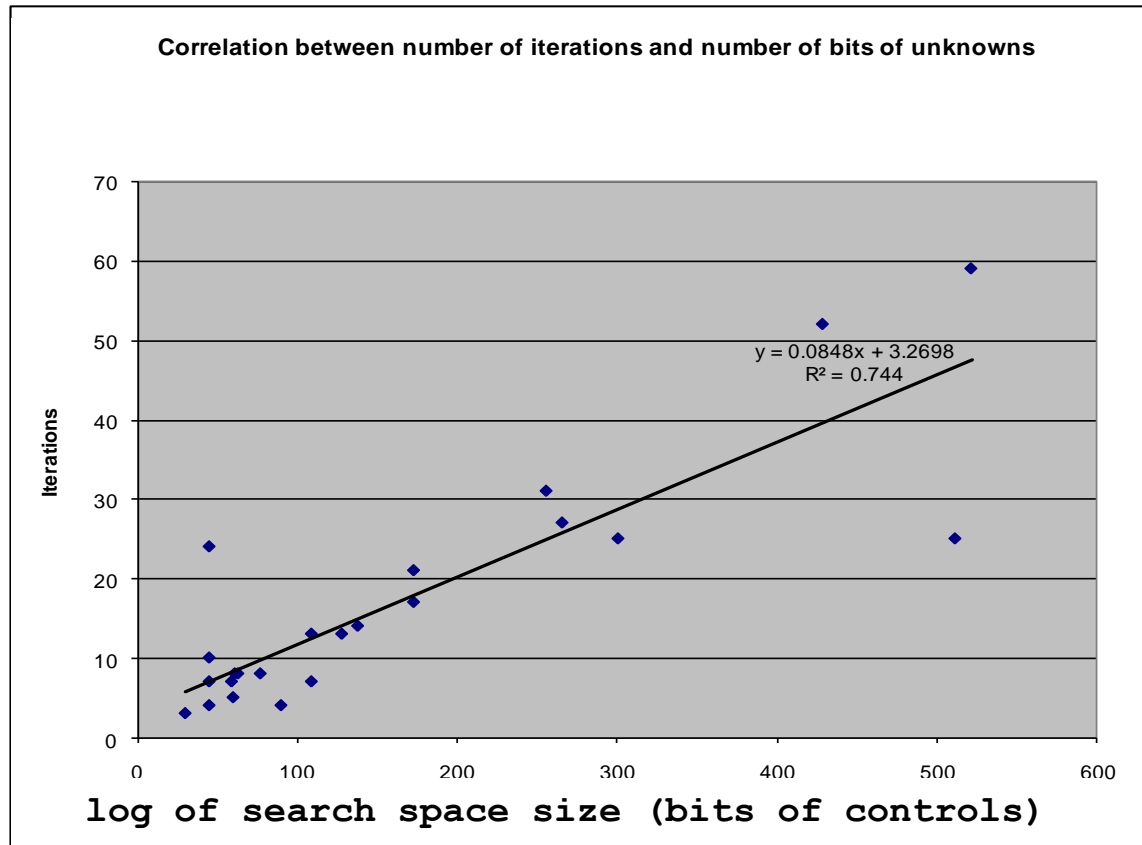
    if(n.next != l.head)
        n.prev.next = n.next;

    if(n.next != null)
        n.next.prev = n.prev;
}
```

Counterexamples
p = 3
p = 0
p = 5

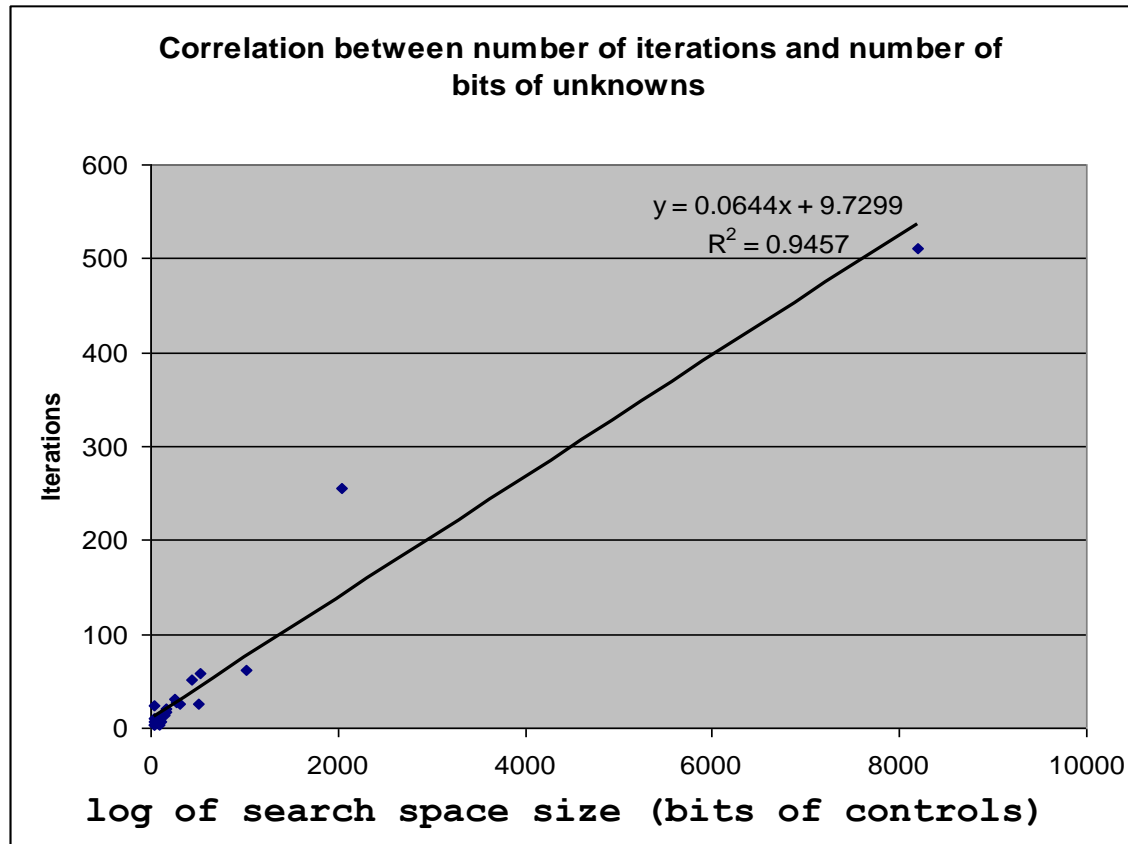
**Process takes < 1 second**

# The number of counterexample inputs is small



# The number of counterexample inputs is small

---



# Inductive Synthesis

---

Deriving a candidate from a set of observations

Key:

- Frame as a constraint satisfaction problem
- Avoid enumeration; use algebraic techniques instead

Encode candidate space as a bit-vector

- Natural encoding given the integer holes

Encode synthesis as boolean constraints on bit-vector

$$\exists \mathbf{c}. \quad \forall x \text{ in } E. \text{Spec}(x) = \text{Sk}(x, \mathbf{c})$$

where  $E = \{x_1, x_2, \dots, x_k\}$

Solve constraints using SAT solver

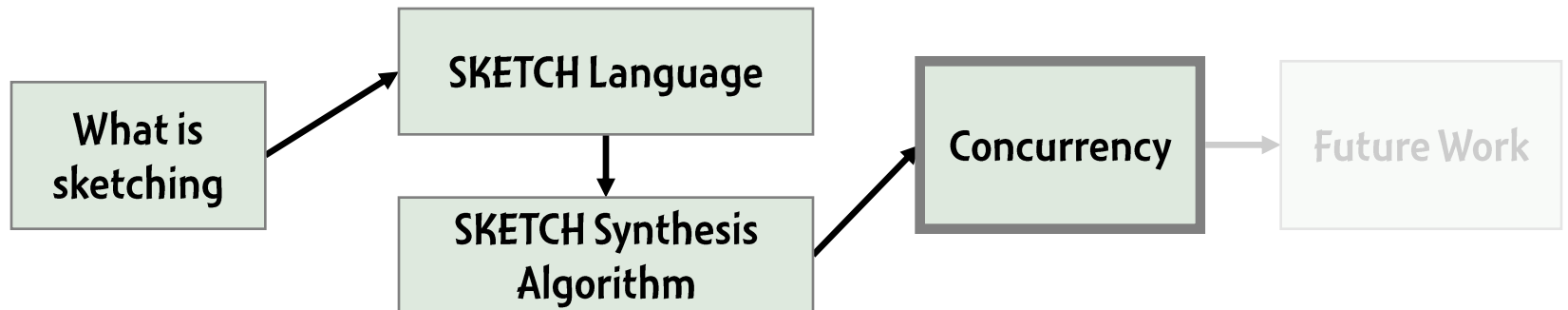
# Interesting Benchmarks

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Benchmark	Unknowns	Solution Time
AES	32769 bits	78.8 min
SSE Matrix Transpose	24 integers + 64 bits	30 min
CRC	8192 bits	13.5 min
Doubly Linked List Remove	60 bits	< 1 sec
Enqueue	271 int & bit	1 min
16 bit Morton Numbers	332 int & bit	20 min
32 bit fast parity	45 bits	11 sec
Sort (bounded)	363 int & bit	3.5 min

---

# Concurrency

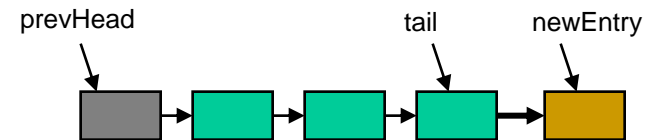


# Concurrent programs

## Ex: Concurrent Enqueue using AtomicSwap

```
class Queue {  
    QueueEntry prevHead =  
        new QueueEntry(null);  
    QueueEntry tail = prevHead;  
  
    void Enqueue(Object newobject) {  
        Node tmp = null;  
        newEntry = new QueueEntry(newobject);  
  
        tmp = AtomicSwap(tail , newEntry );  
        tmp.next = newEntry ;  
  
    }  
}
```

```
Object AtomicSwap(ref Object loc, Object entry)  
atomic {  
    Object old = loc;  
    loc = entry;  
    return old;  
}
```



# Generalization to Parallelism

---

## Output now dependent on thread interleaving

- Make interleaving schedule part of the observations
- Most verifiers can provide a counterexample trace

## Using the observations becomes harder

- Schedule generated as witness for a given candidate
- How do we use it to rule out other incorrect candidates?