## Image Stitching II

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## **RANSAC** for Homography





#### **Initial Matched Points**





## **RANSAC** for Homography





#### **Final Matched Points**





## **RANSAC** for Homography







## Image Blending



## Feathering



## Effect of window (ramp-width) size









## Effect of window size









## Good window size





What can we do instead?

"Optimal" window: smooth but not ghosted

• Doesn't always work...

## Pyramid blending



#### Create a Laplacian pyramid, blend each level

 Burt, P. J. and Adelson, E. H., A Multiresolution Spline with Application to Image Mosaics, ACM Transactions on Graphics, 42(4), October 1983, 217-236. http://persci.mit.edu/pub\_pdfs/spline83.pdf

## Blending comparison (IJCV 2007)



(a) Linear blending



(b) Multi-band blending

## Alpha Blending



Encoding blend weights:  $I(x,y) = (\alpha R, \alpha G, \alpha B, \alpha)$ 

color at p =  $\frac{(\alpha_1 R_1, \ \alpha_1 G_1, \ \alpha_1 B_1) + (\alpha_2 R_2, \ \alpha_2 G_2, \ \alpha_2 B_2) + (\alpha_3 R_3, \ \alpha_3 G_3, \ \alpha_3 B_3)}{\alpha_1 + \alpha_2 + \alpha_3}$ 

Implement this in two steps:

- 1. accumulate: add up the ( $\alpha$  premultiplied) RGB values at each pixel
- 2. normalize: divide each pixel's accumulated RGB by its  $\alpha$  value

Gain Compensation: Getting rid of artifacts

- Simple gain adjustment
  - Compute average RGB intensity of each image in overlapping region
  - Normalize intensities by ratio of averages







## **Blending Comparison**



(b) Without gain compensation



(c) With gain compensation



(d) With gain compensation and multi-band blending

## **Recognizing Panoramas**





Some of following material from Brown and Lowe 2003 talk

Brown and Lowe 2003, 2007

## **Recognizing Panoramas**

Input: N images

- 1. Extract SIFT points, descriptors from all images
- Find K-nearest neighbors for each point (K=4) (from the OTHER images)
- 3. For each image
  - a) Select M candidate matching images by counting matched keypoints in other images (m=6)
  - b) Solve homography  $\mathbf{H}_{ij}$  for each matched image



#### What else matches?

## **Recognizing Panoramas**

Input: N images

- 1. Extract SIFT points, descriptors from all images
- 2. Find K-nearest neighbors for each point (K=4)
- 3. For each image
  - a) Select M candidate matching images by counting matched keypoints (m=6)
  - b) Solve homography  $\mathbf{H}_{ij}$  for each matched image
  - c) Decide if match is valid  $(n_i > 8 + 0.3_n_f)$

# inliers

# keypoints in overlapping area

# Recognizing Panoramas (cont.)

(now we have matched pairs of images)

Make a graph of matched pairs
Find connected components of the graph



#### Finding the panoramas



## Finding the panoramas











# Recognizing Panoramas (cont.)

(now we have matched pairs of images)

- 4. Find connected components
- 5. For each connected component
  - a) Solve for rotation and f
  - b) Project to a surface (plane, cylinder, or sphere)
  - c) Render with multiband blending

#### Finding the panoramas









