

Retrieval on Parametric Shape Collections

Adriana Schulz¹

Ariel Shamir²

Ilya Baran³

David Levin^{1,4}

Pitchaya Sitthi-amorn^{1,5}

Wojciech Matusik¹

¹Massachusetts Institute of Technology

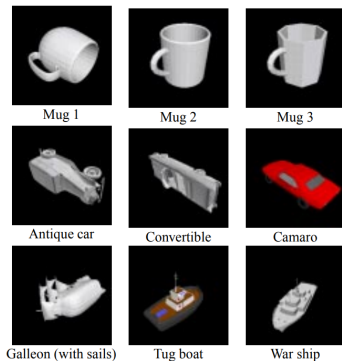
²The Interdisciplinary Center, Hertzliya

³Onshape Inc.

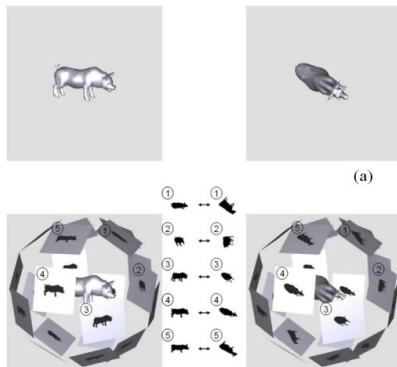
⁴University of Toronto

⁵Chulalongkorn University

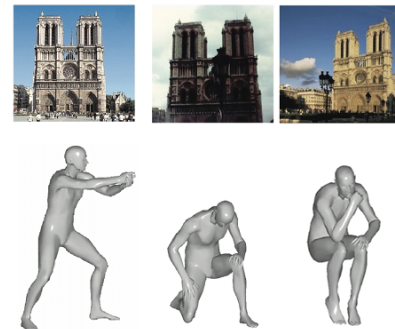
Shape Retrieval



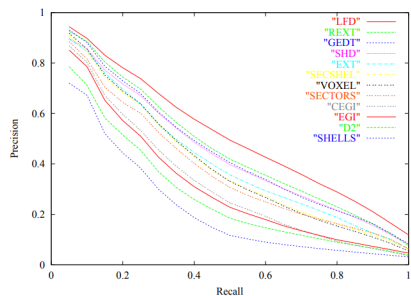
[Osada et al. 2001]



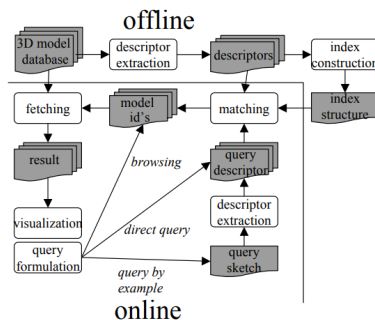
[Chen et al. 2003]



[Brownstein et al 2011]



[Shilane et al. 2004]

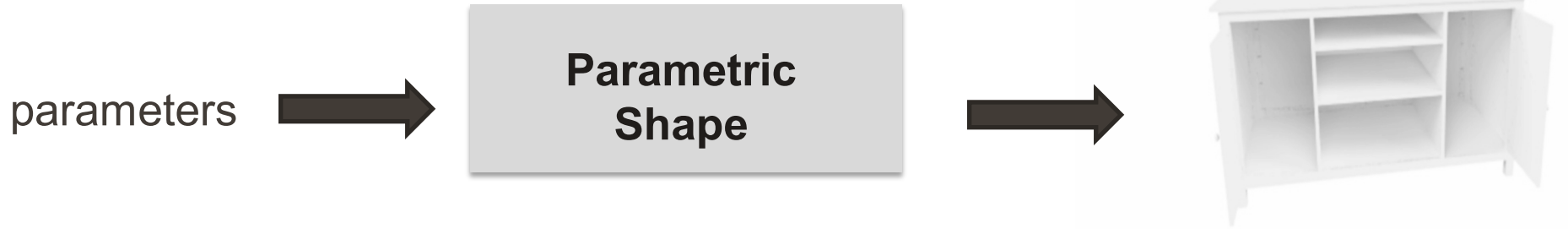


[Veltkamp et al 2008]



[SHREC 2013 - 2017]

Parametrization



Advantages:

- constrains manipulations
 - e.g., fabrication-oriented constraints
- reduces the search space

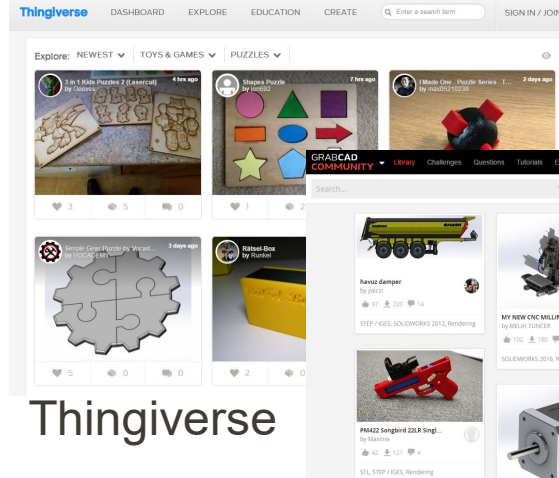
Available Collections



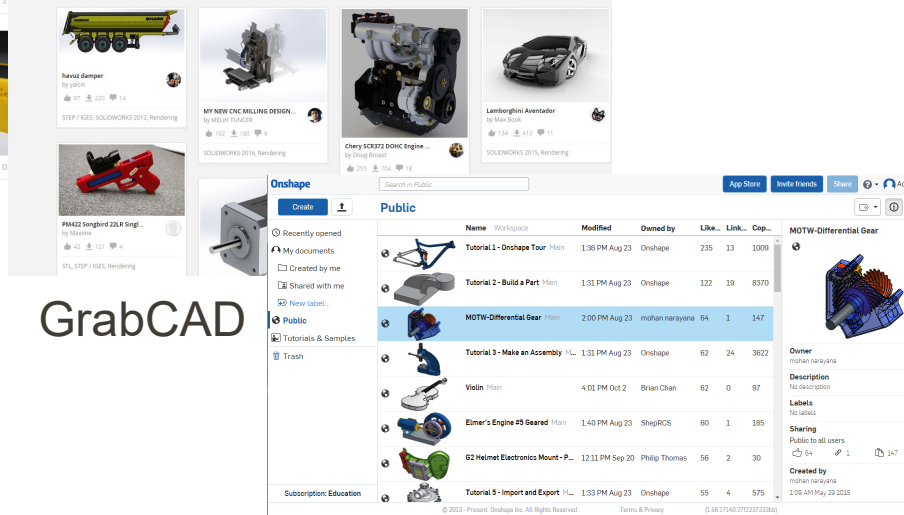
creo™ 1.0



Onshape



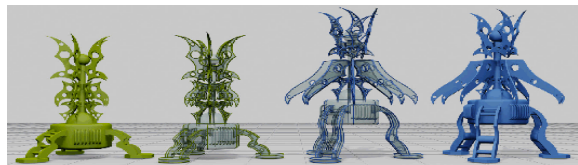
Thingiverse



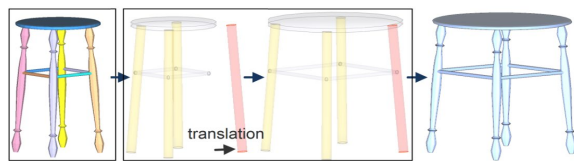
GrabCAD

Onshape's Repository

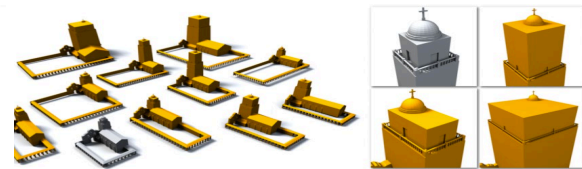
Parametrization Techniques



[Gal et al 2009]



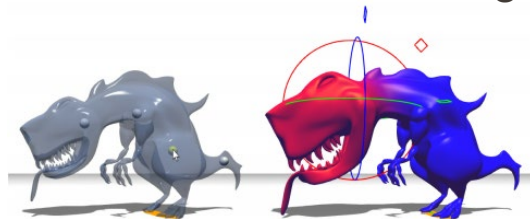
[Zeng et al 2011]



[Bokeloh et al 2012]

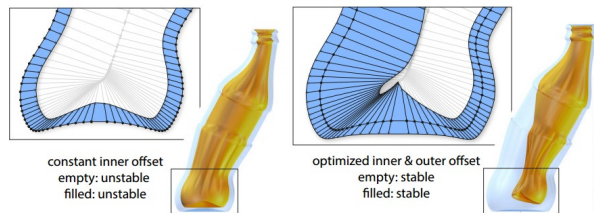
Application Examples:

Linear Blend Skinning



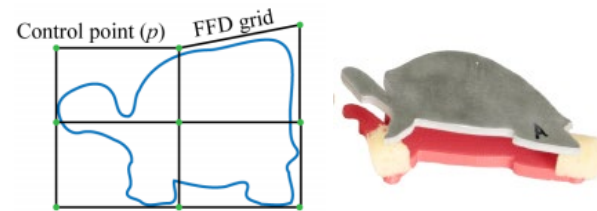
[Prevost et al. 2014]

Offset Surfaces



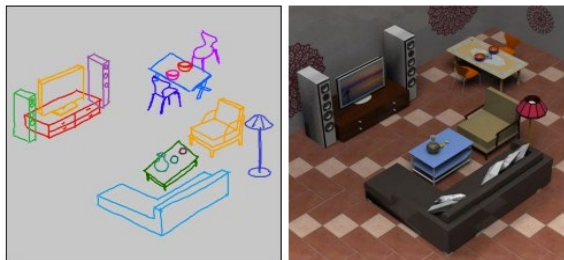
[Musialski et al. 2015]

Cages



[Bharaj et al. 2015]

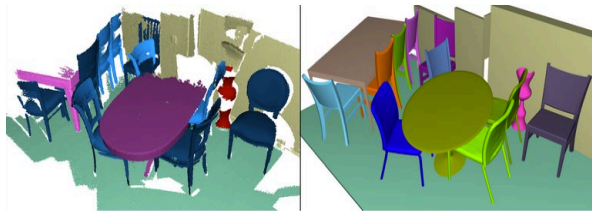
Data-Driven Modeling



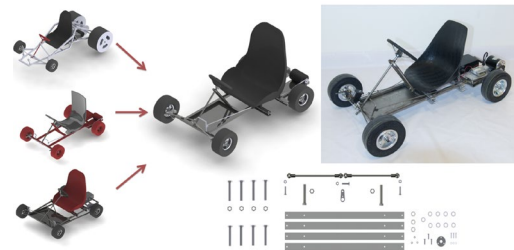
[Xu et al 2013]



[Xu et al 2011]



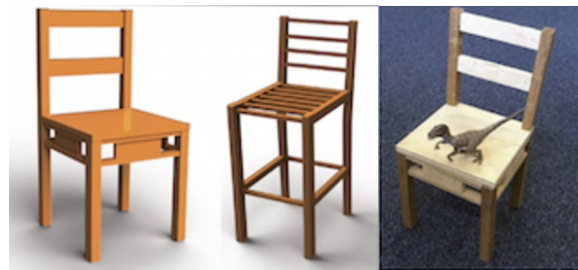
[Nan et al 2012]



[Schulz et al. 2014]



[Shen et al 2012]

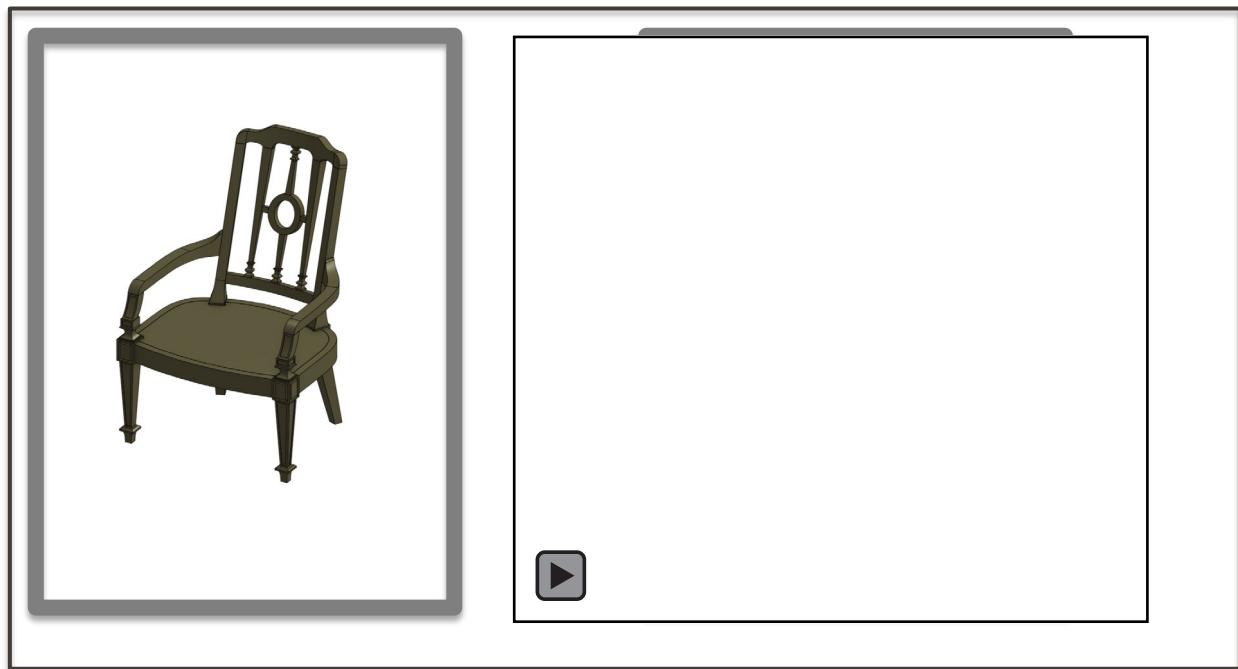


[Yang et al. 2015]

Parametric Shape Collections



Retrieval in Parametric Shape Collections

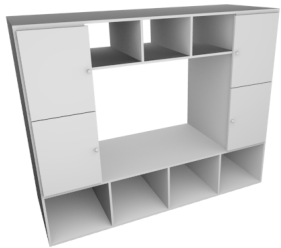


Parametric Shape Collection

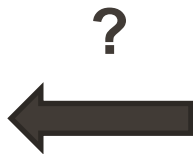


Query

Typical Pipeline

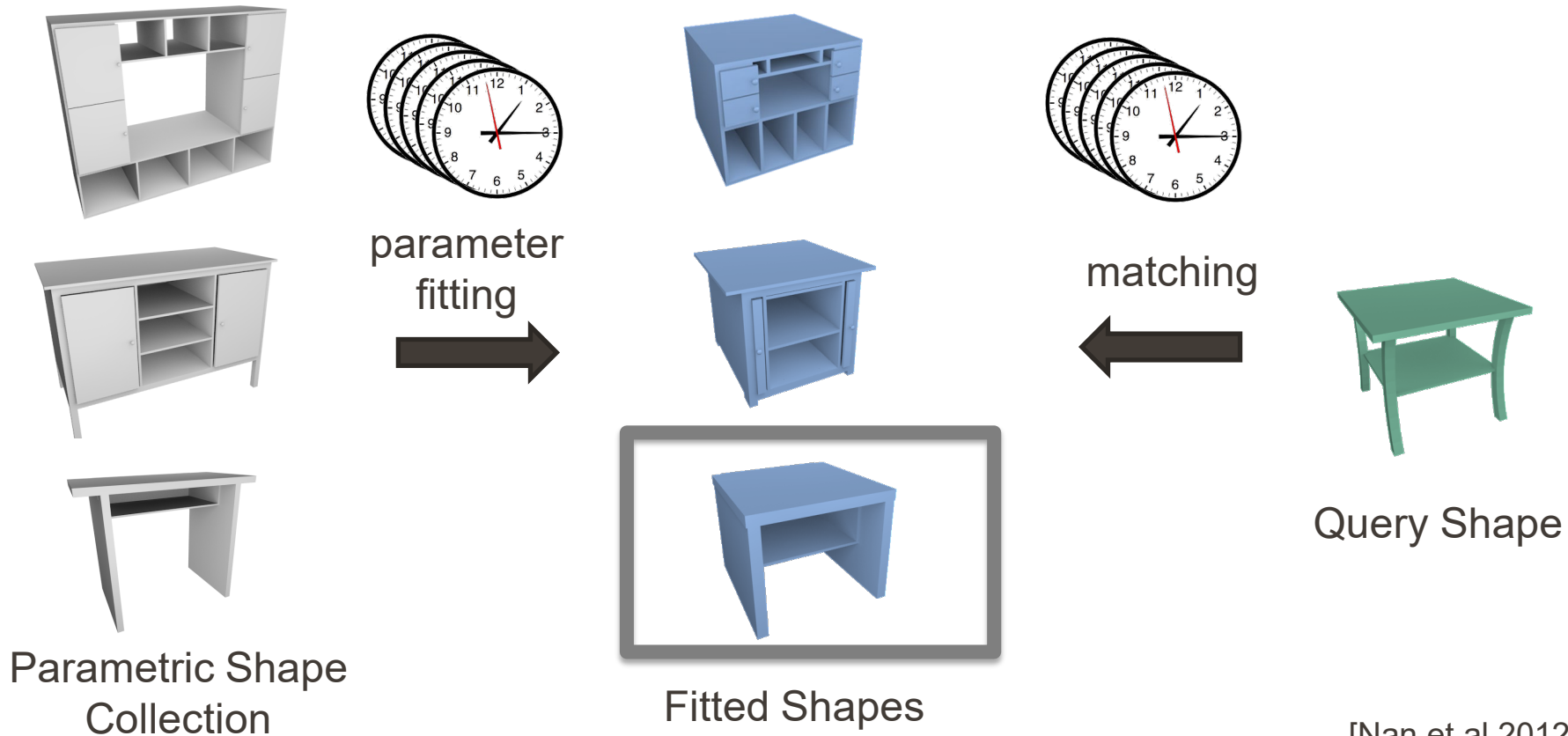


Parametric Shape
Collection

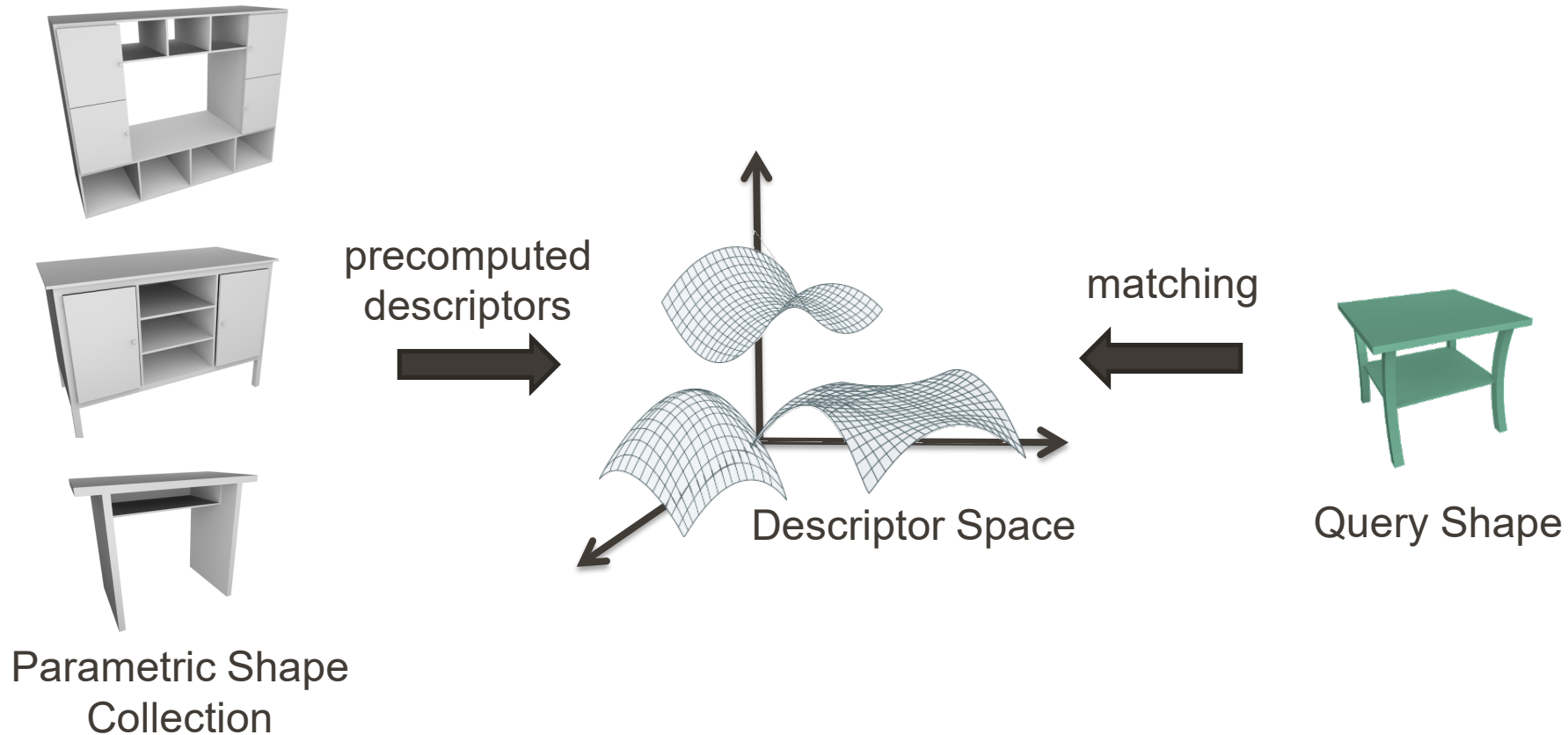


Query Shape

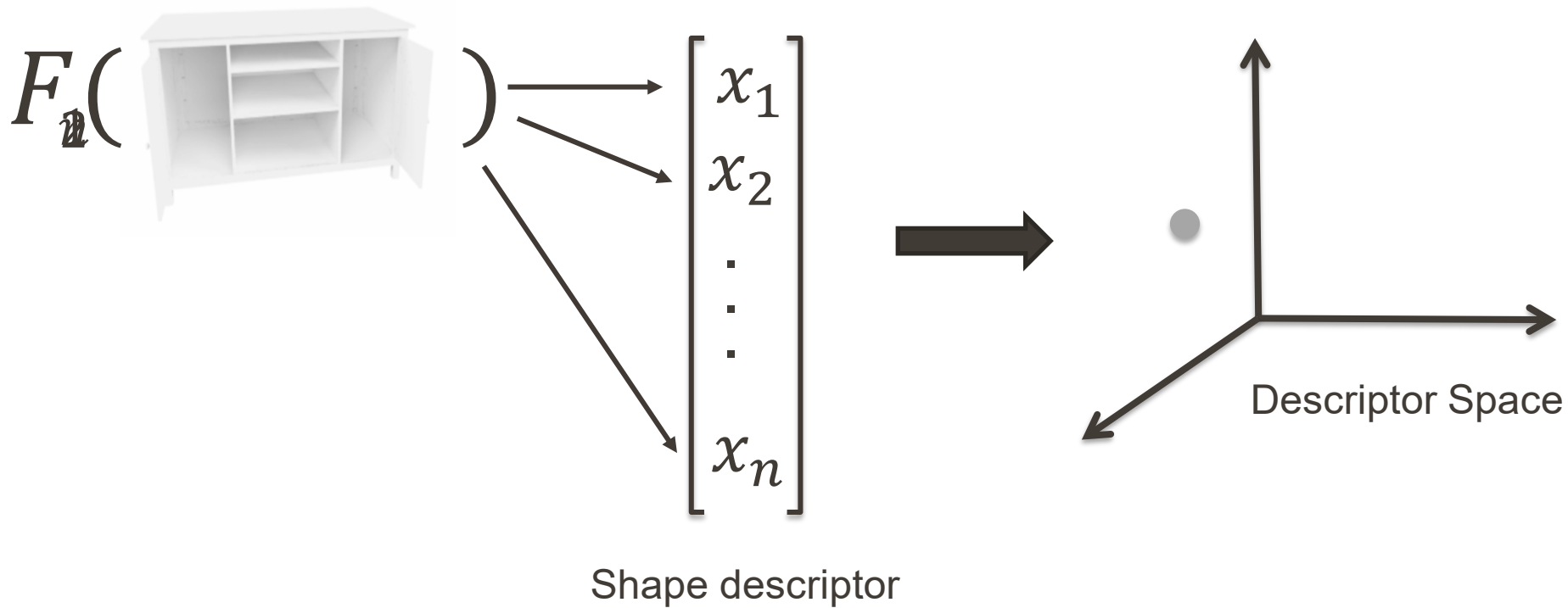
Typical Pipeline *Fit-First*



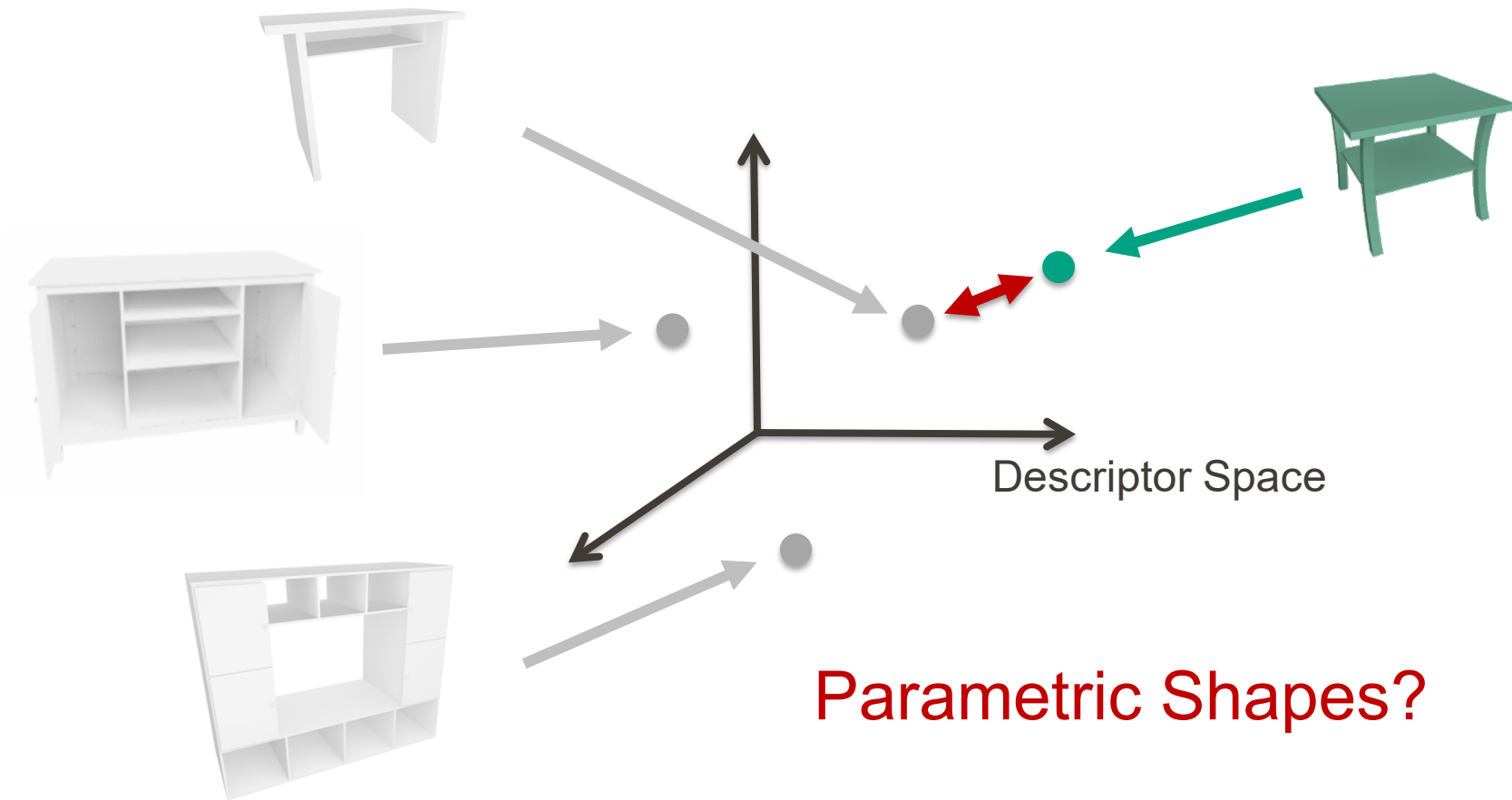
Our Approach



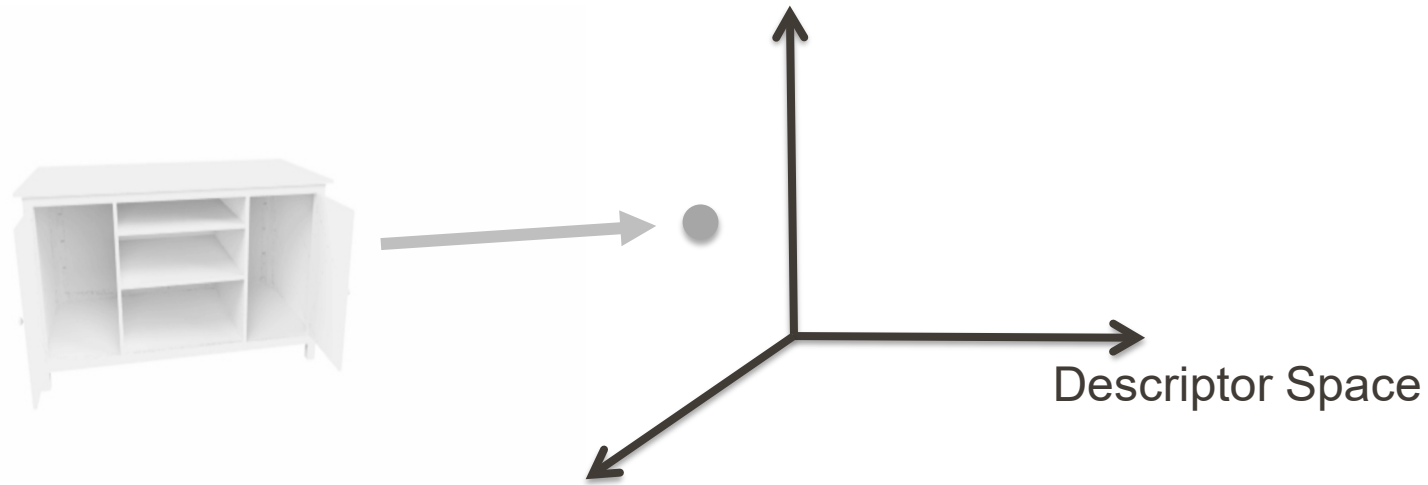
Retrieval Using Descriptors



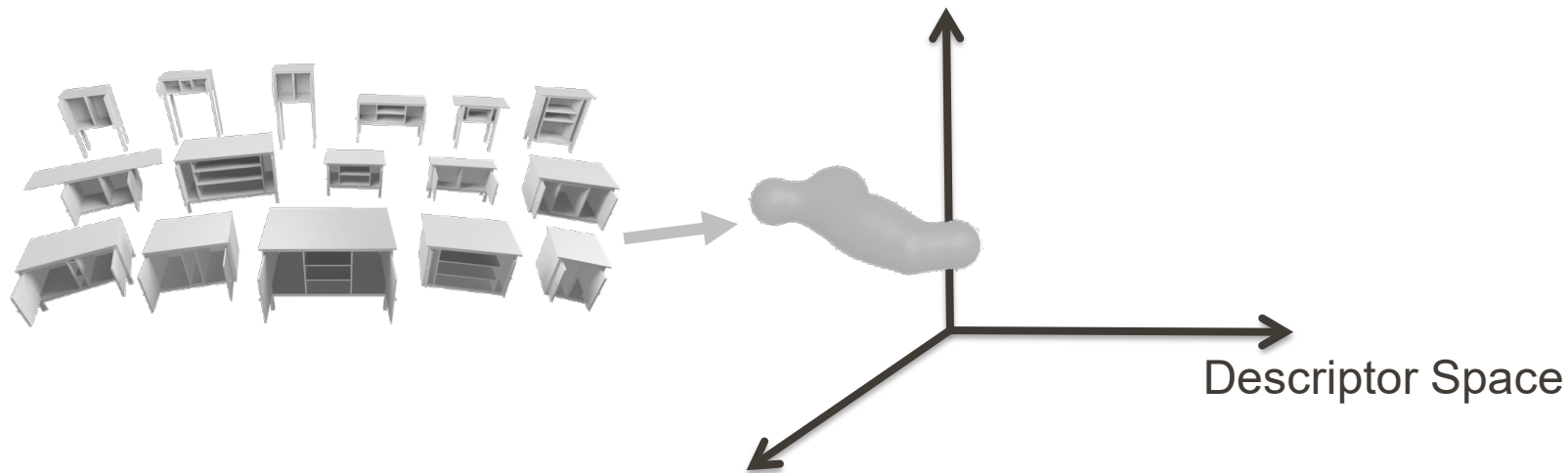
Shape Retrieval with Descriptors



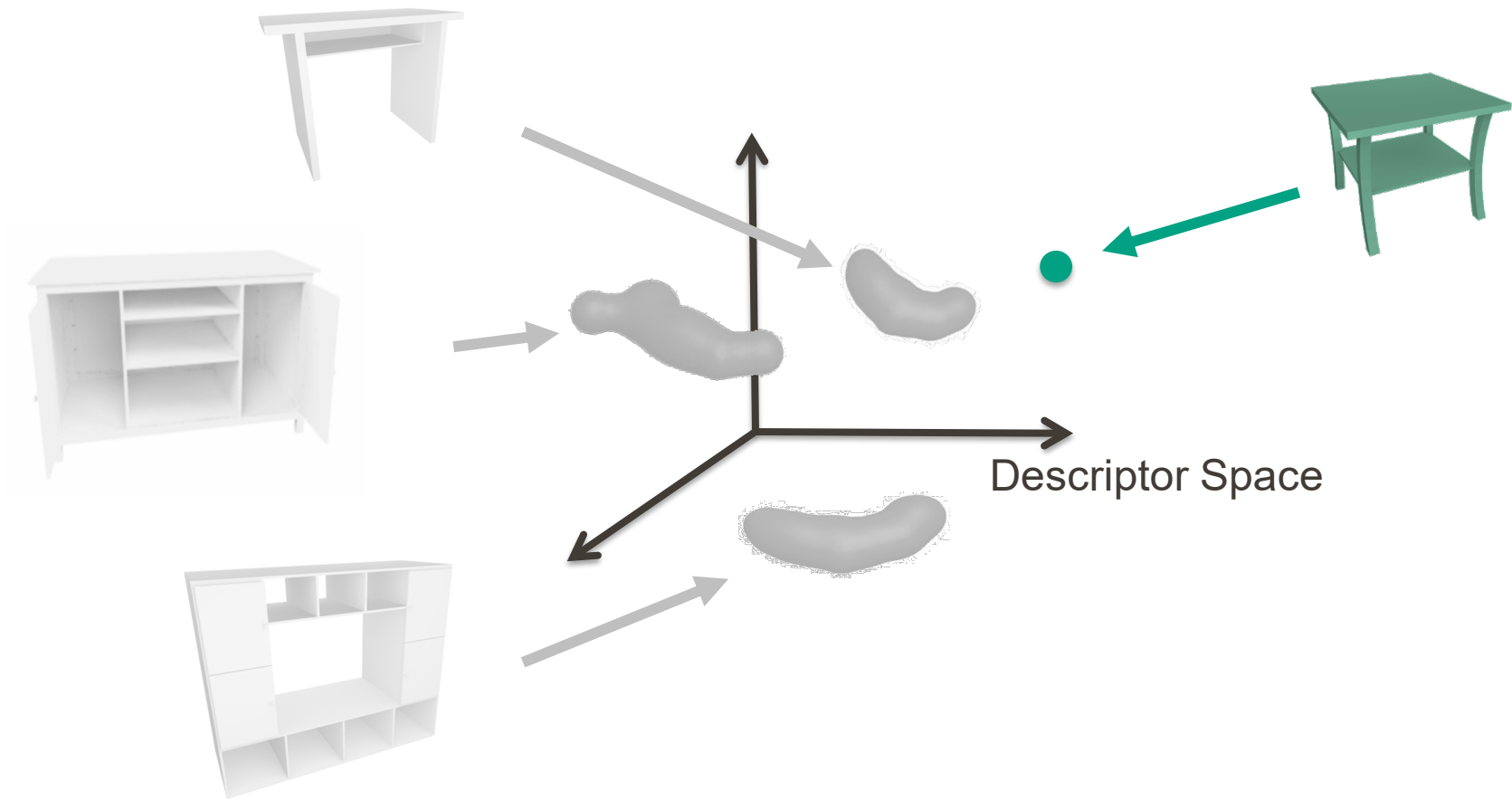
Parametric Shape Retrieval with Descriptors



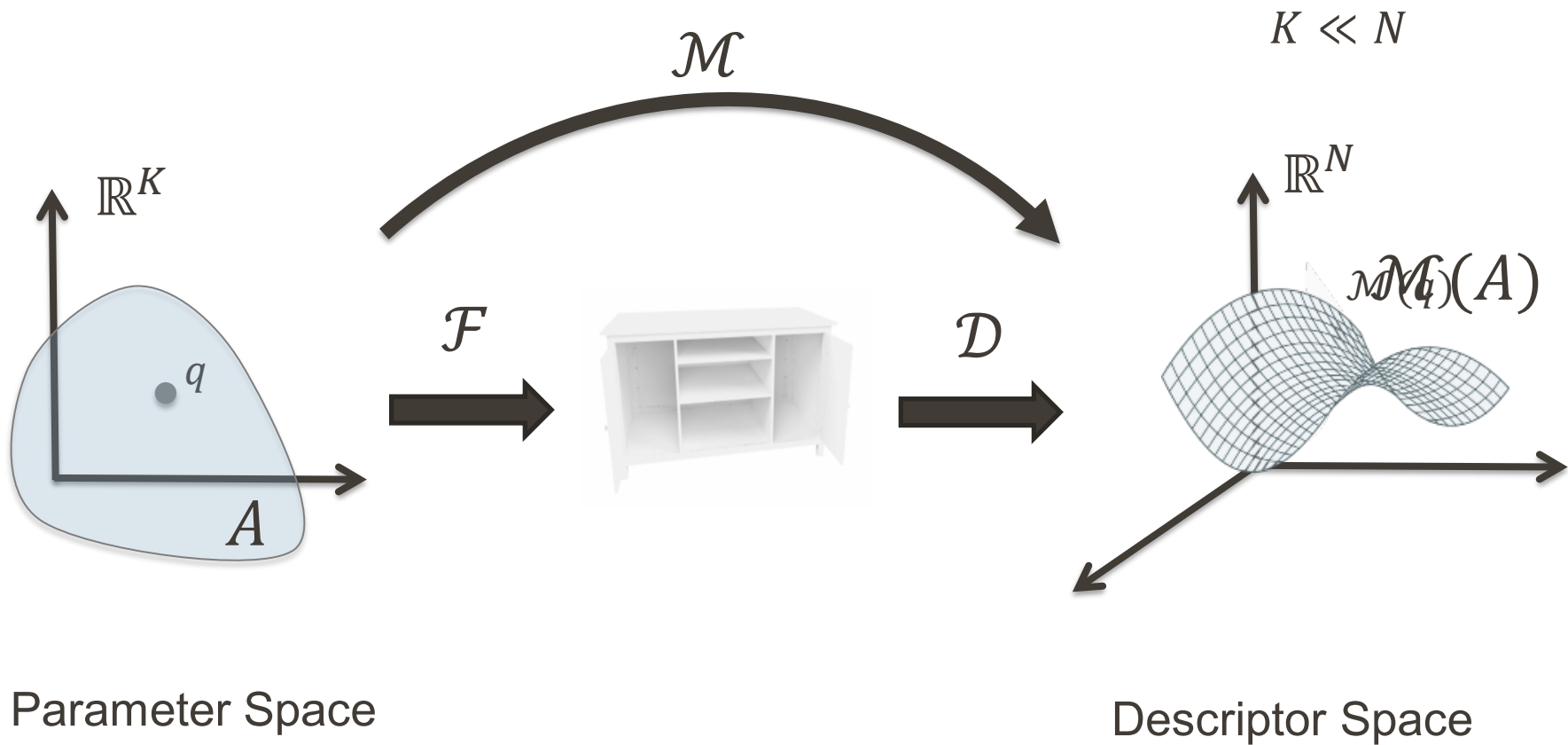
Parametric Shape Retrieval with Descriptors



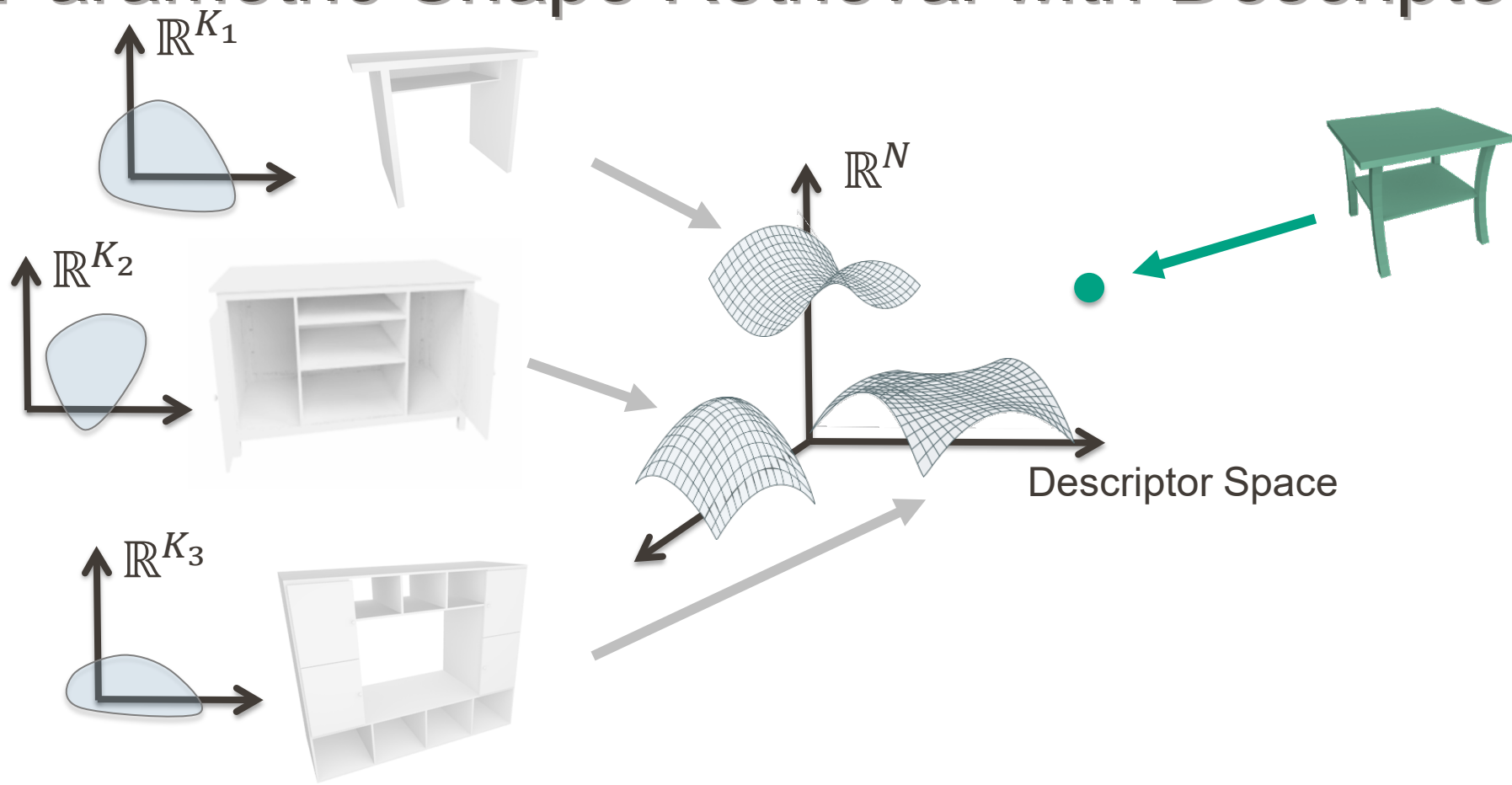
Parametric Shape Retrieval with Descriptors



Regions in Descriptor Space



Parametric Shape Retrieval with Descriptors

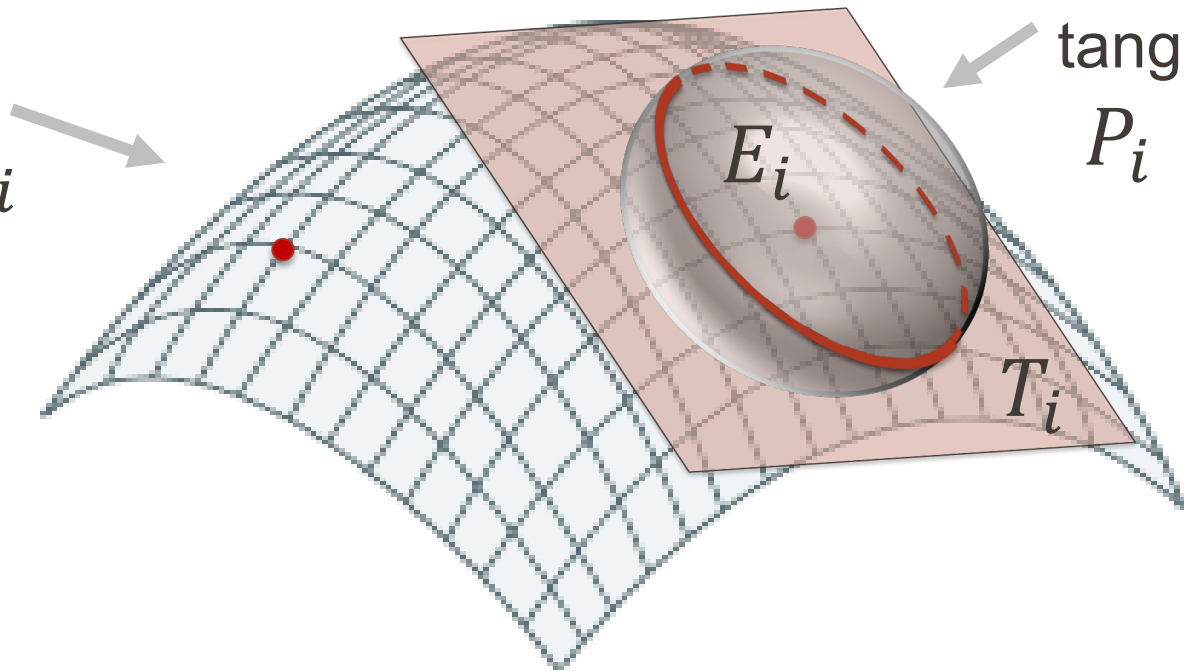


Approach

$$\mathcal{M}(A) \longrightarrow \overline{\mathcal{M}(A)} = \{P_1, \dots, P_K\}$$

point

$$P_i = p_i$$



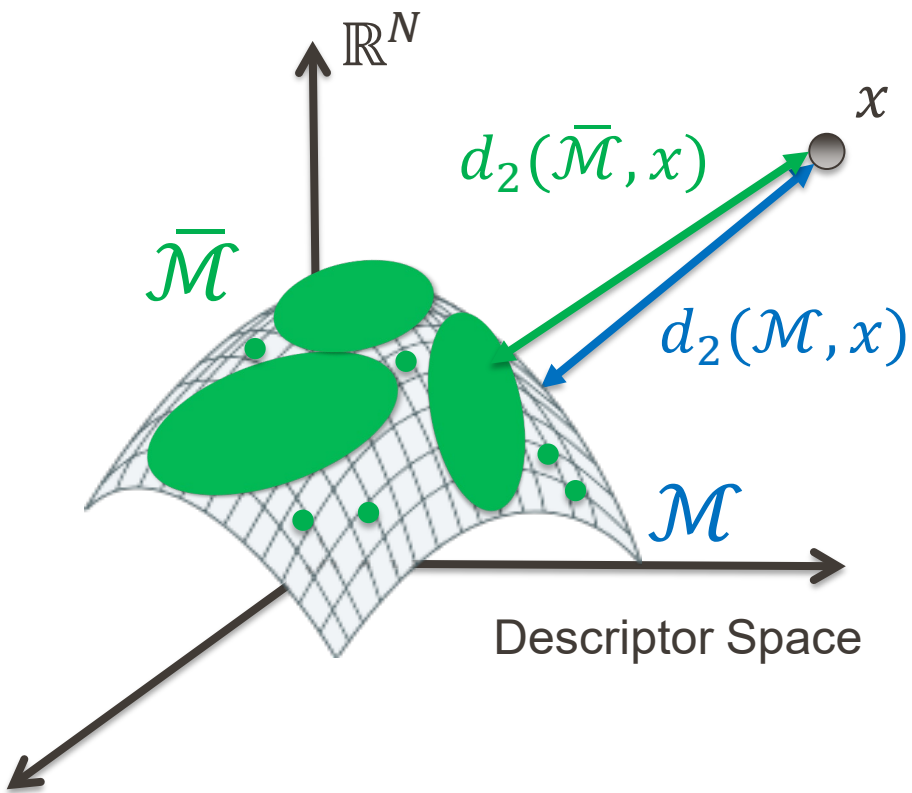
bounded
tangent space

$$P_i = T_i \cap E_i$$

Technical Contribution

Algorithm for efficiently representing parametric shapes with these primitives to allow accurate retrieval.

Accuracy Criteria



$$d_2(\bar{\mathcal{M}}, x) \approx d_2(\mathcal{M}, x)$$

$$|d_2(\bar{\mathcal{M}}, x) - d_2(\mathcal{M}, x)| \leq \delta$$

user specified

Coverage and Tightness

$$|d_2(\bar{\mathcal{M}}, x) - d_2(\mathcal{M}, x)| \leq \delta \quad \forall x \in \mathbb{R}^N$$



Coverage Property

$$d_2(\bar{\mathcal{M}}, y) \leq \delta \quad \forall y \in \mathcal{M}$$

Tightness Property

$$d_2(\mathcal{M}, y) \leq \delta \quad \forall y \in \bar{\mathcal{M}}$$

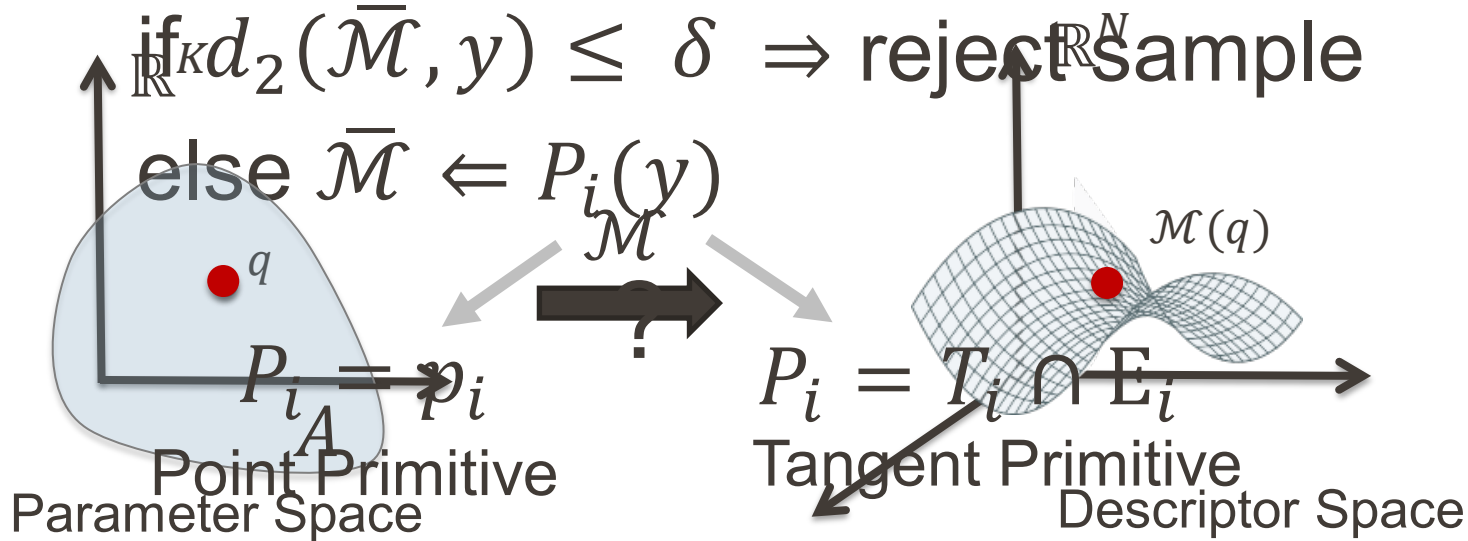
Algorithm

Initialize $\bar{\mathcal{M}} = \emptyset$

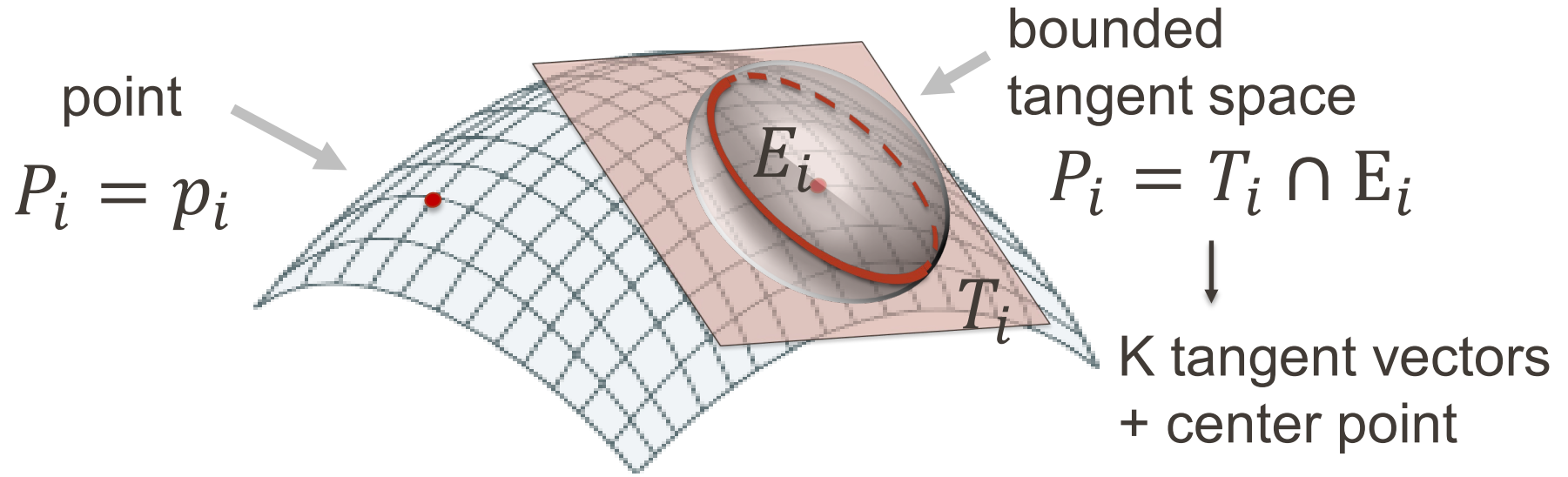
Sample $y \in \mathcal{M}$

if $kd_2(\bar{\mathcal{M}}, y) \leq \delta \Rightarrow$ reject sample

else $\bar{\mathcal{M}} \leftarrow P_i(y)$



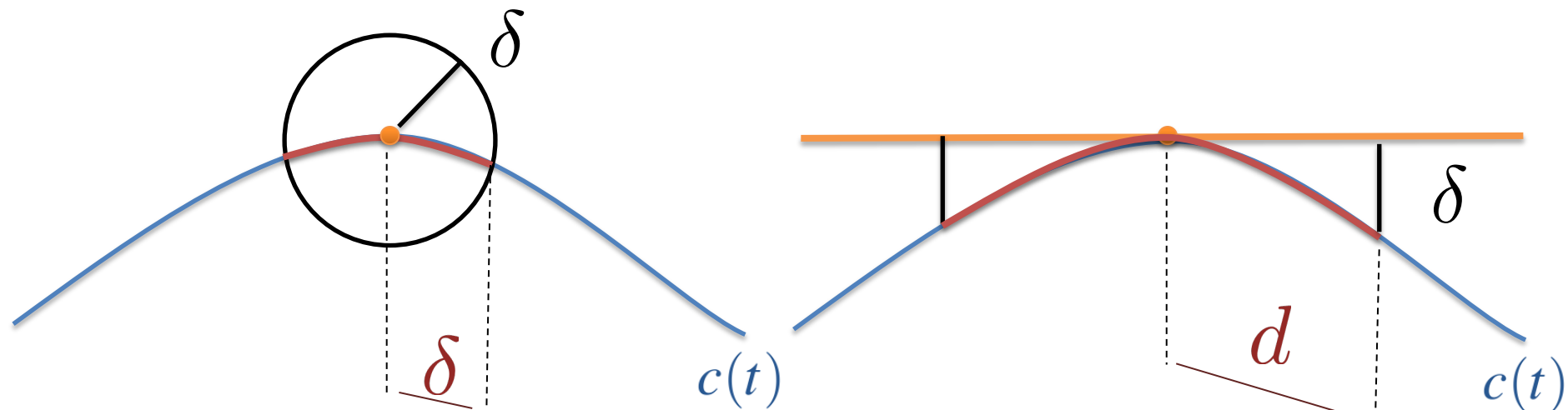
Choosing Between Primitives



cost of tangent = $(K + 1)$ cost of point

coverage of tangent $>$ $(K + 1)$ coverage of points

Coverage of Points and Tangents



$$\frac{d}{\delta} = \sqrt{\frac{2}{\delta \kappa}}$$

curvature

Criteria for Primitive Selection

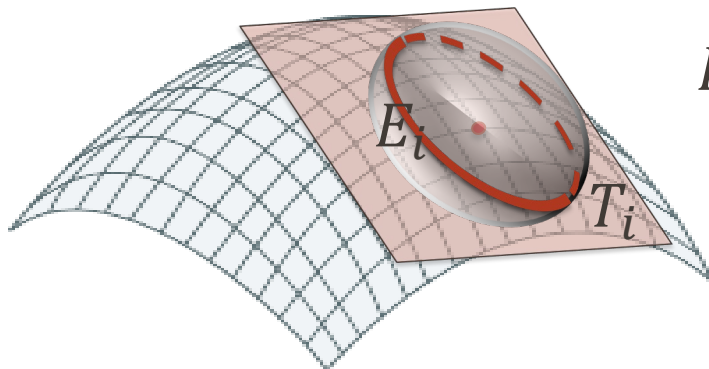
One-Dimensional Case

Use tangents if: $\kappa \leq \frac{2}{\delta(K+1)^2}$

Multi-Dimensional Case

Use tangents if: $\kappa^{max} \leq \frac{2}{\delta(K+1)^{\frac{2}{K}}}$

Bounding Tangent Primitives

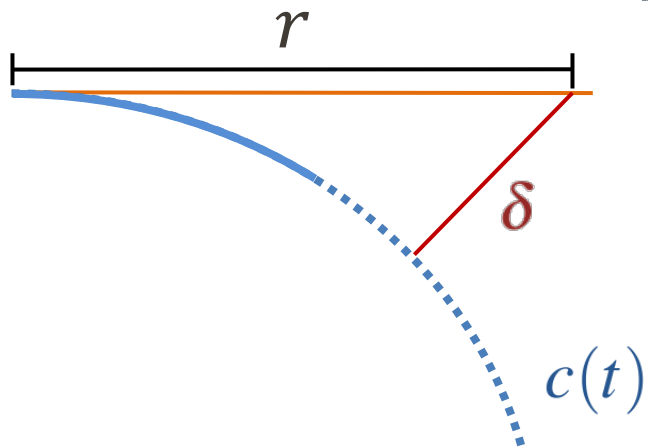


$$P_i = T_i \cap E_i$$

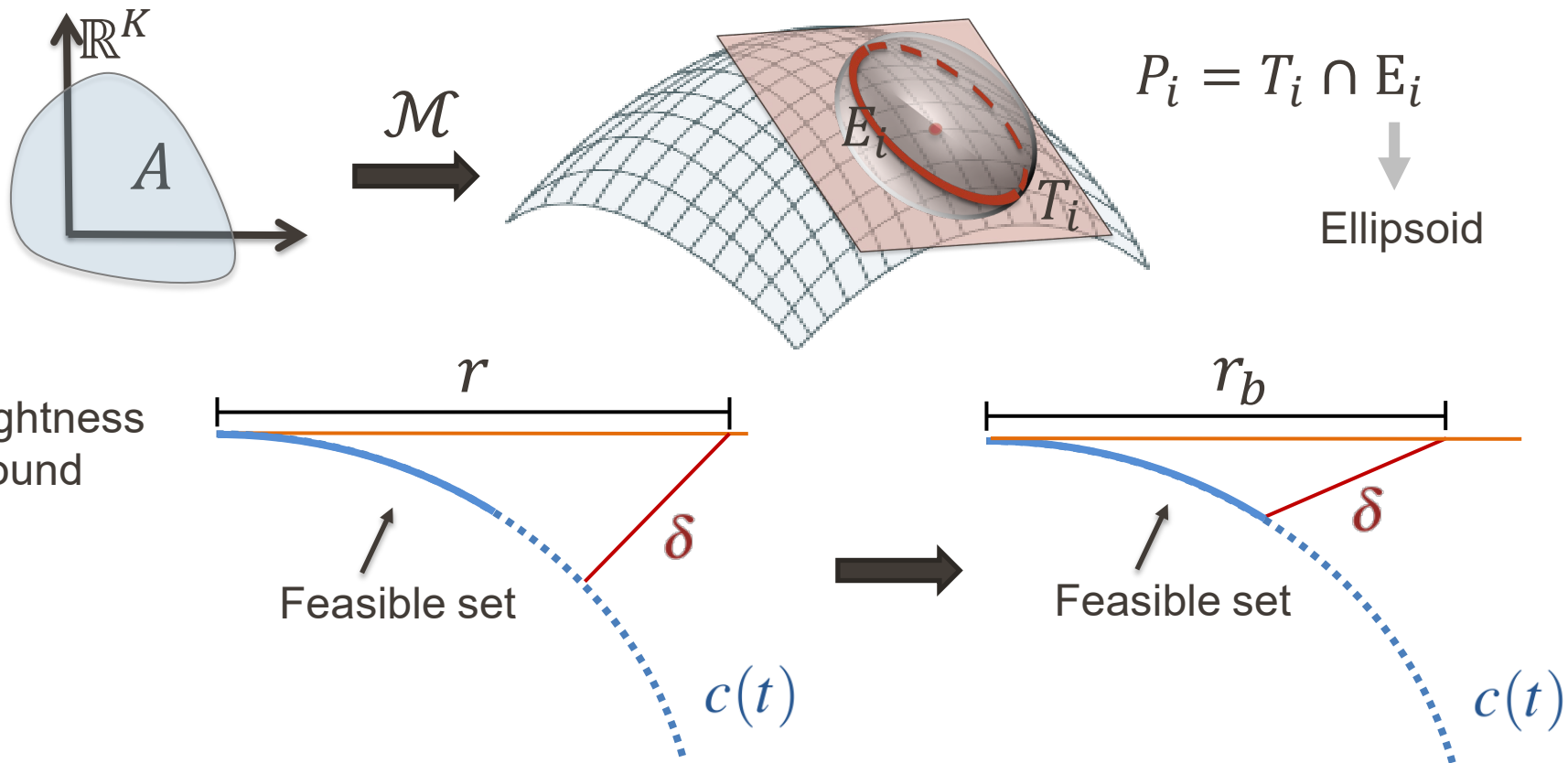


Hyperphere of
radius r

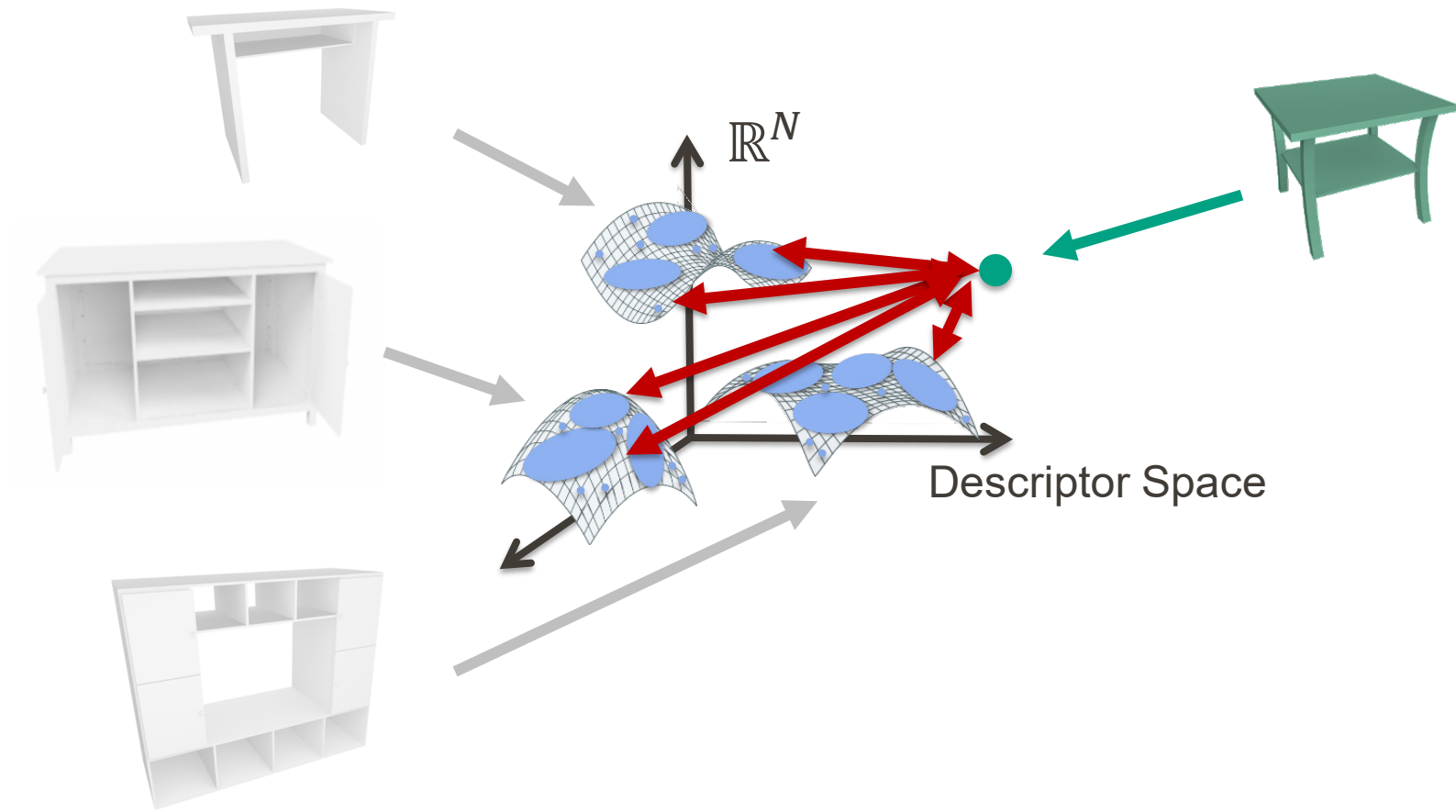
Tightness
Bound



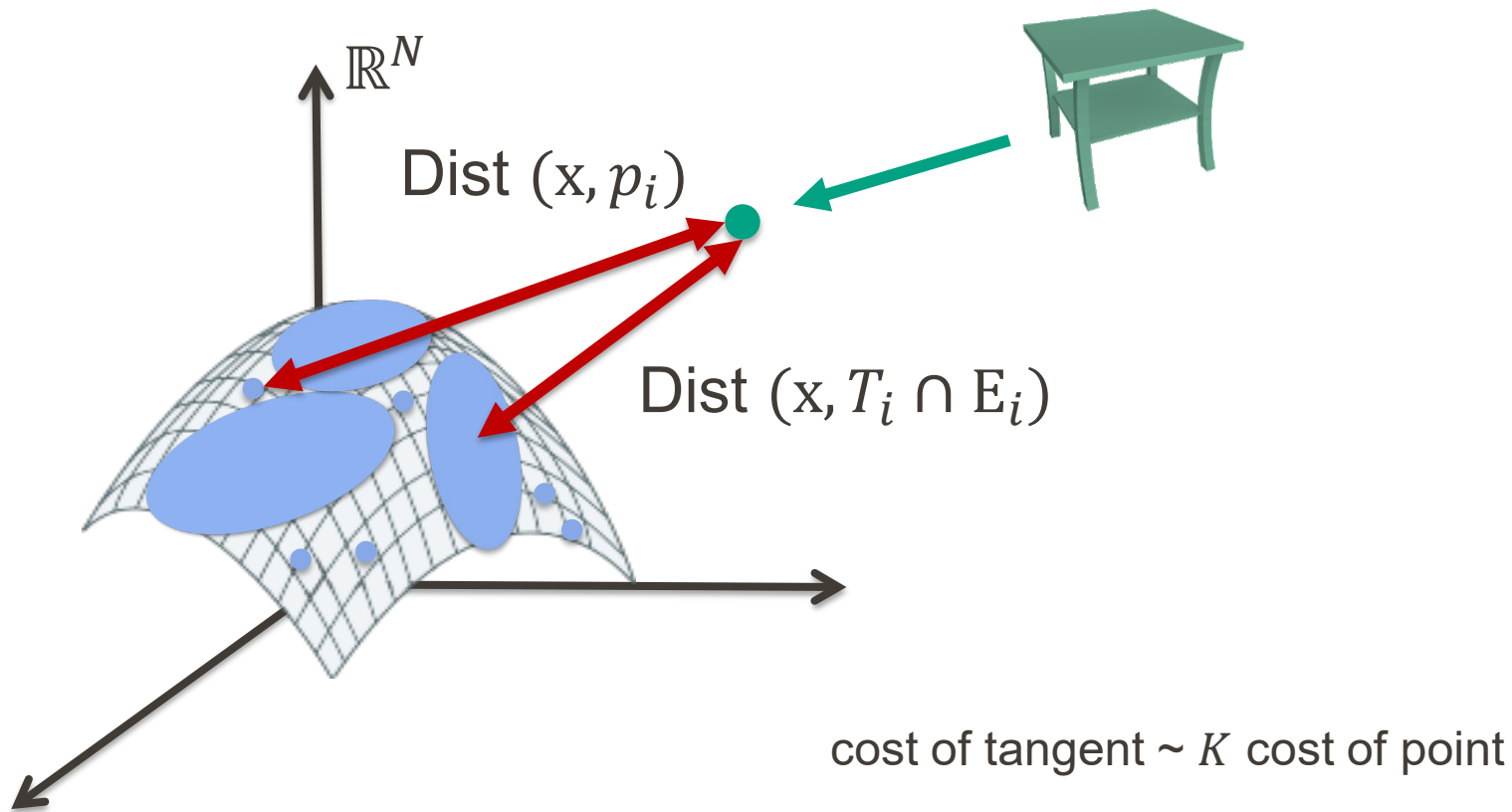
Handling the Feasible set A



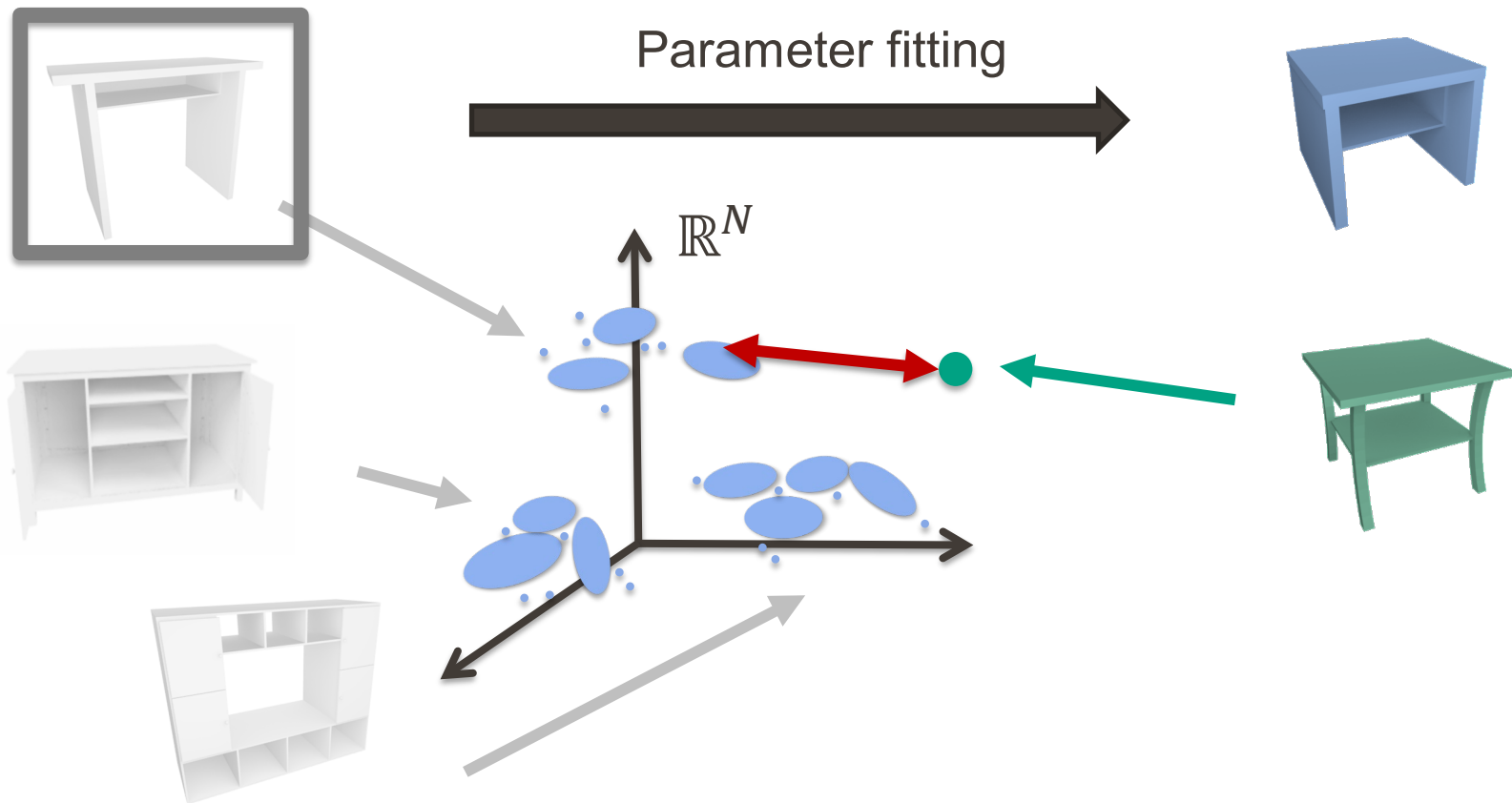
Our Approach: Retrieval



Retrieving the Parametric Shape

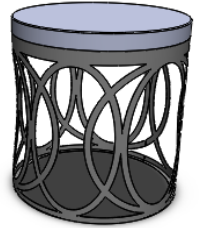


Parameter Fitting



Evaluations

Experiments: Data



Number of parameters: 2-9

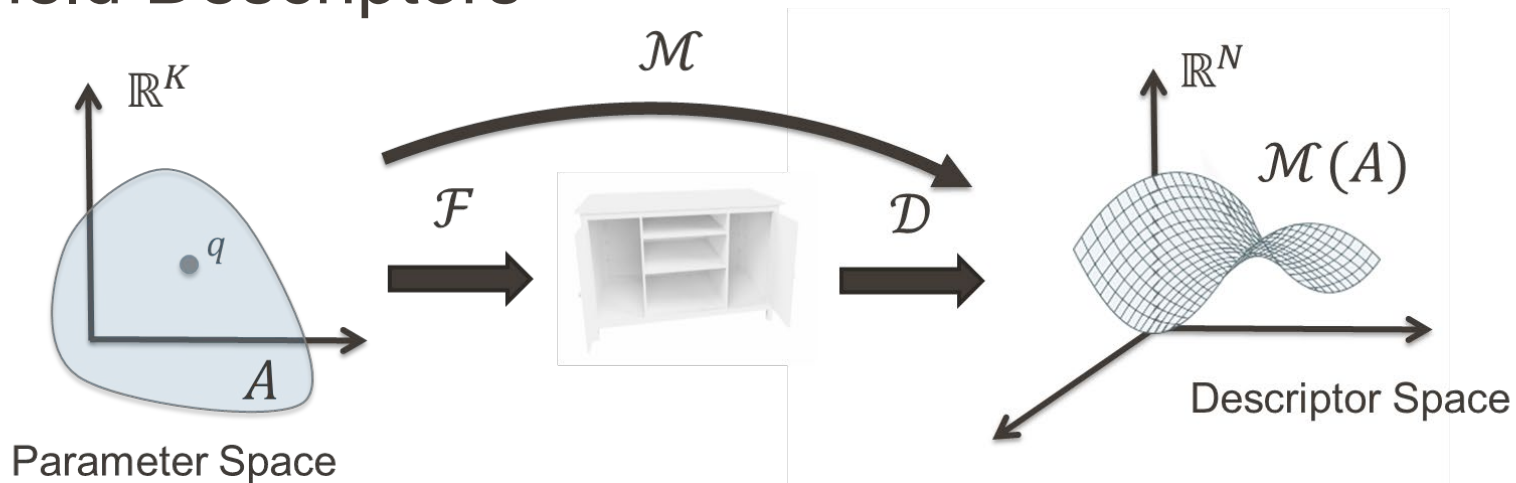
Category	Number of Models
lamps	17
boats	11
chairs	15
planes	9
carts	10
tables	15

Experiments: Descriptors

D2 Shape Distribution

VOXEL Shape Histogram

Light Field Descriptors

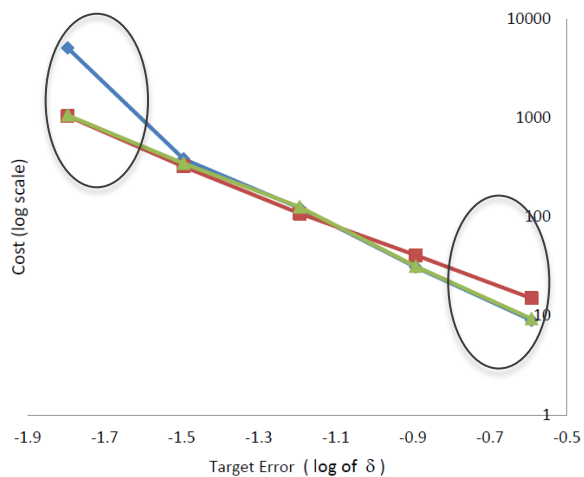


Manifold Representation: Efficiency

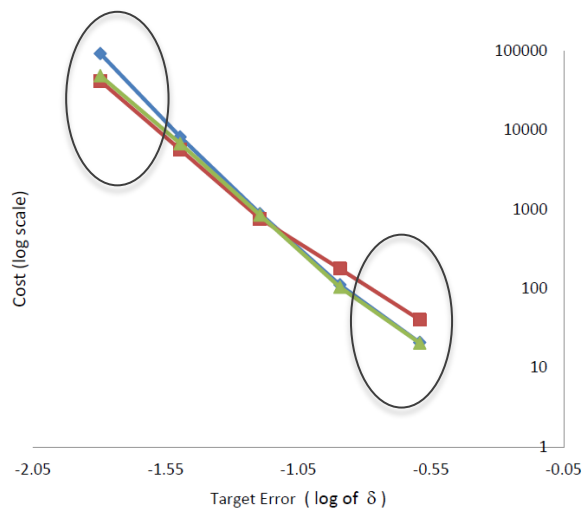
◆ Points

▲ Hybrid
(our method)

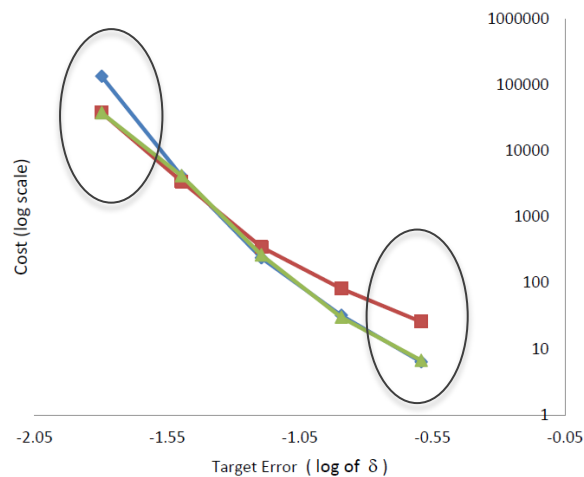
■ Tangents



$K = 3$



$K = 5$



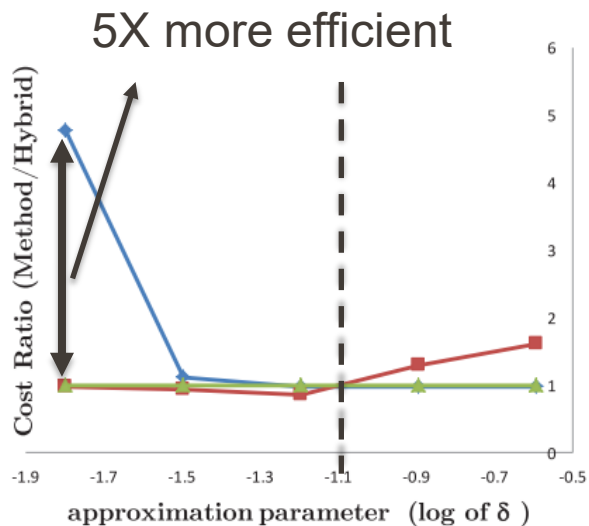
$K = 7$

Manifold Representation: Efficiency

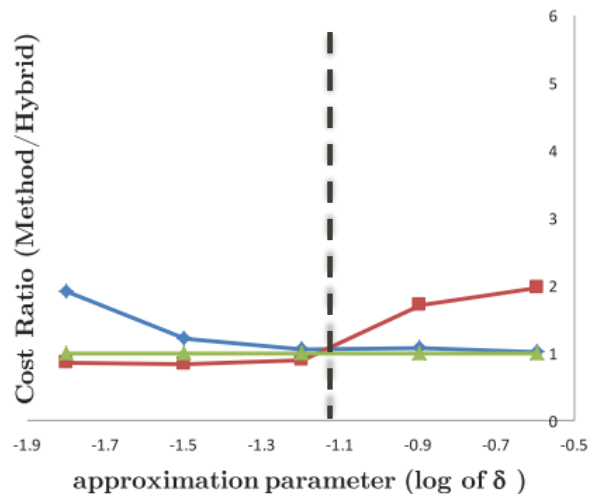
◆ Points

▲ Hybrid

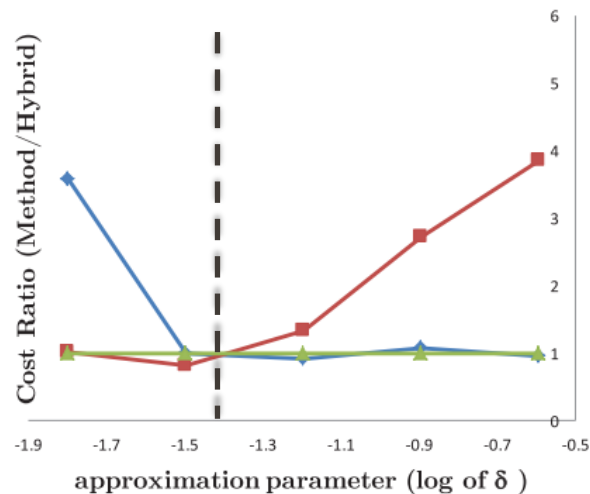
■ Tangents



$K = 3$

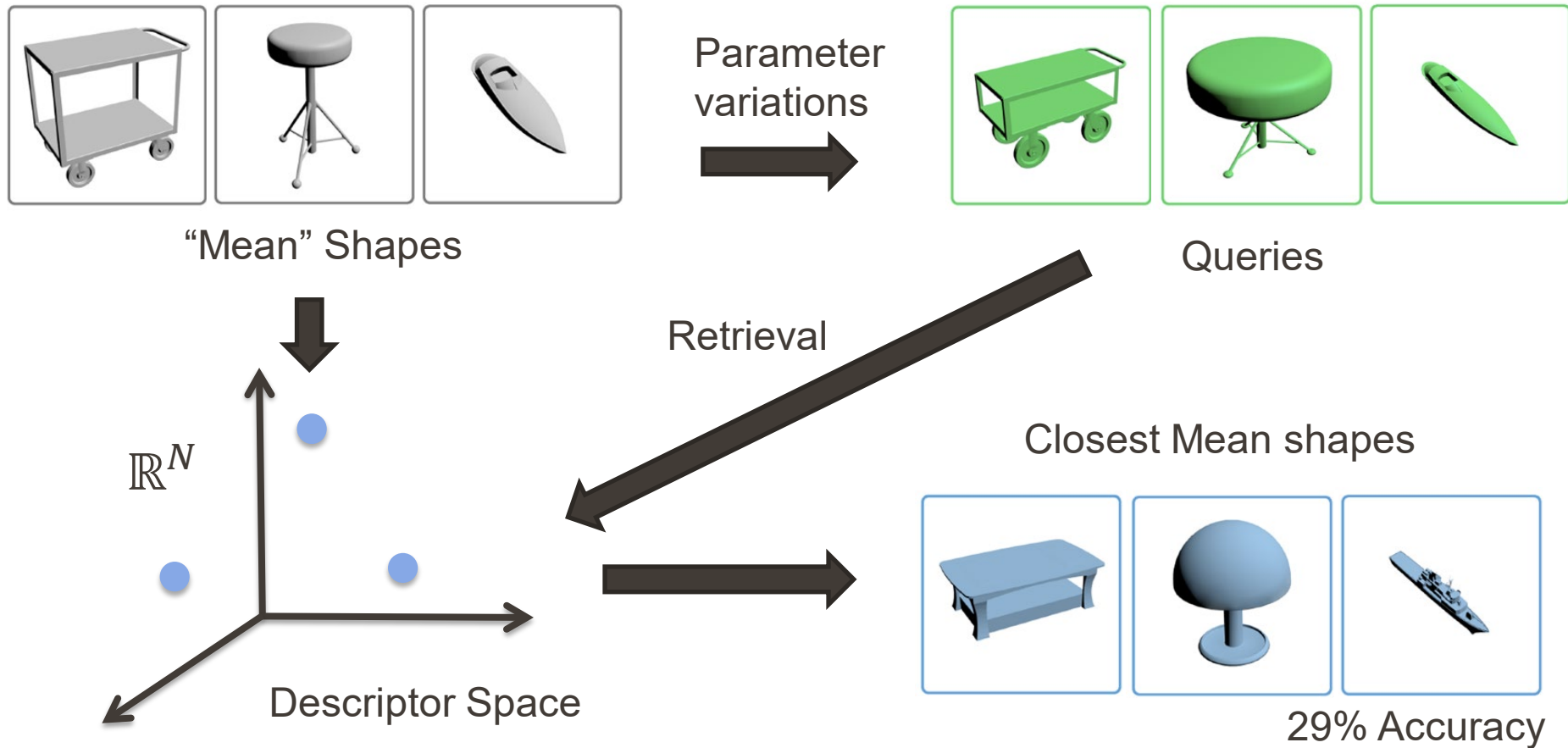


$K = 5$



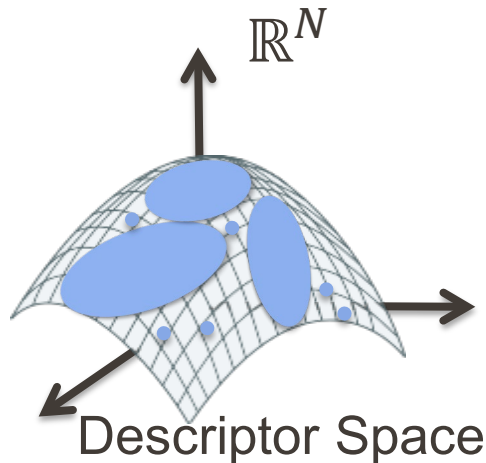
$K = 7$

Querying Parametric Variations

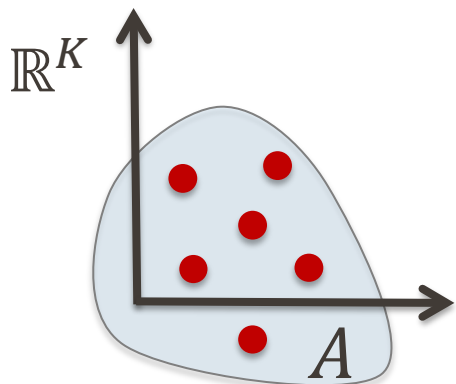


Querying Parametric Variations

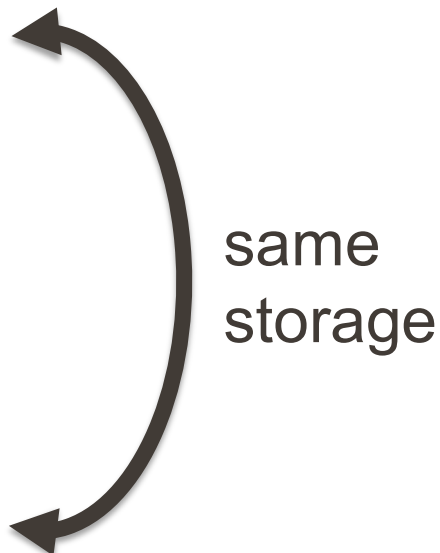
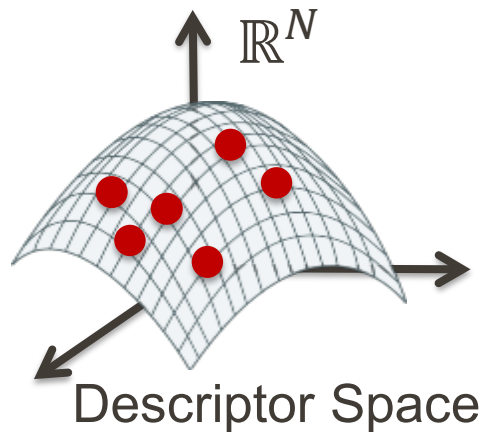
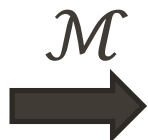
Our Method



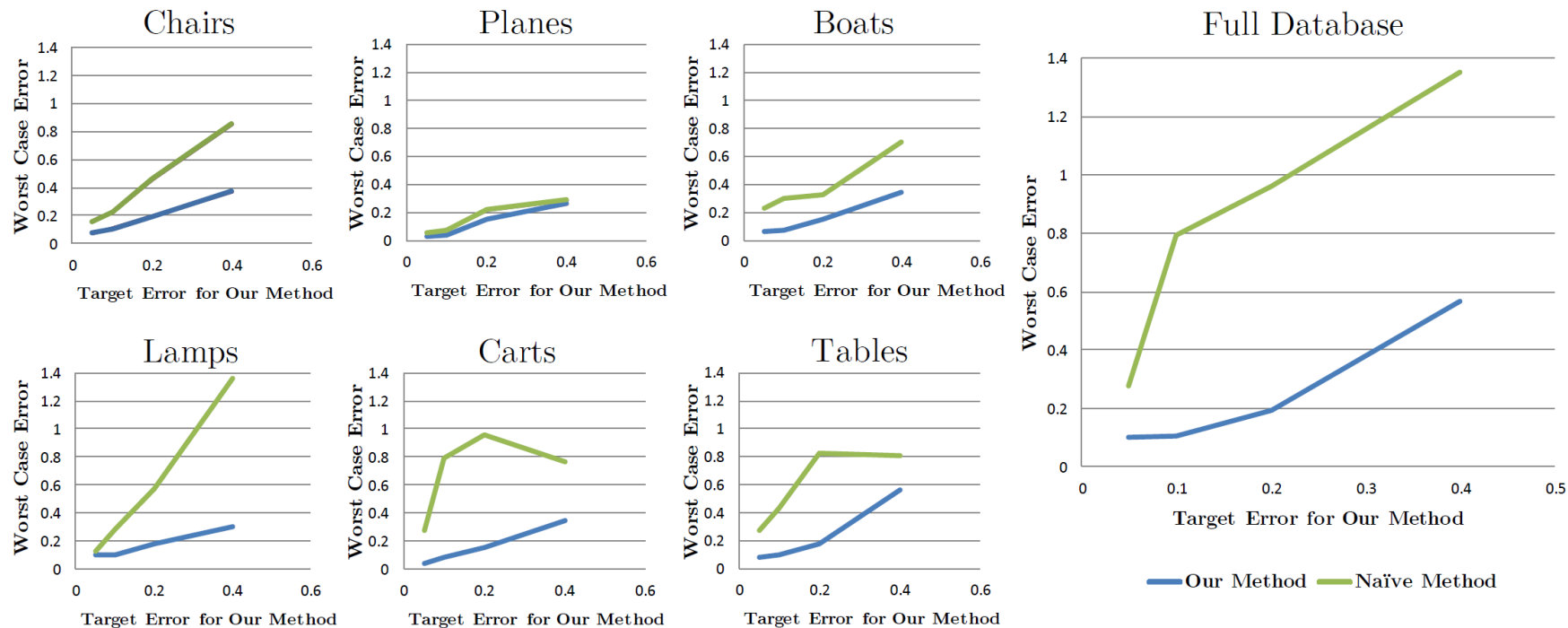
Naïve Approach



Parameter Space



Comparison with Naïve Method

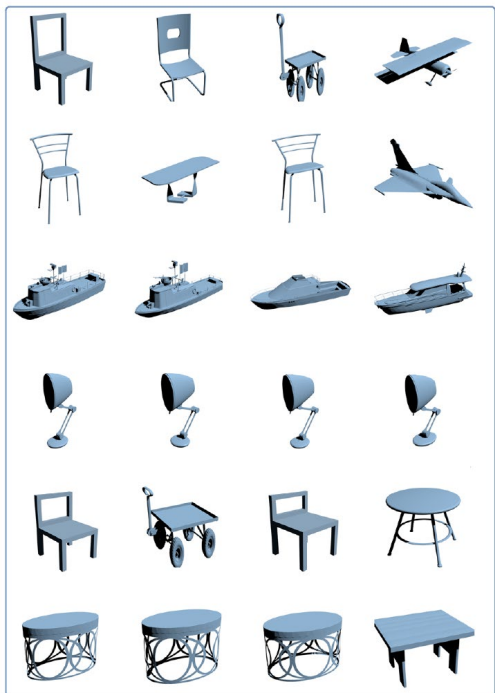


Querying Shapes from Online Repositories

Query

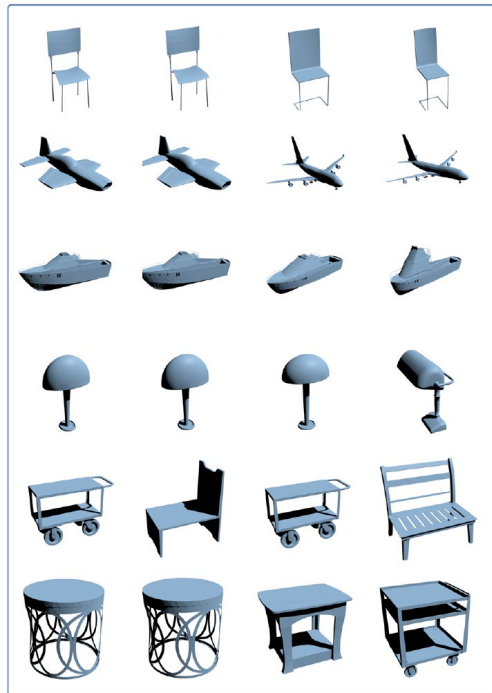


D2 Descriptor



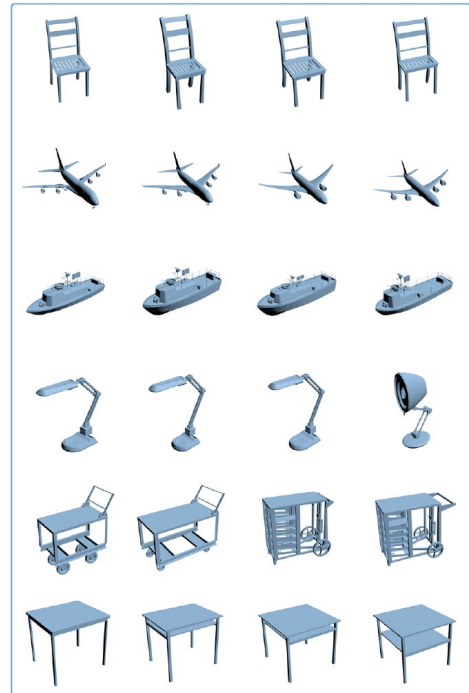
0.05 0.1 0.2 0.4

Voxel Descriptor



0.075 0.1 0.2 0.4

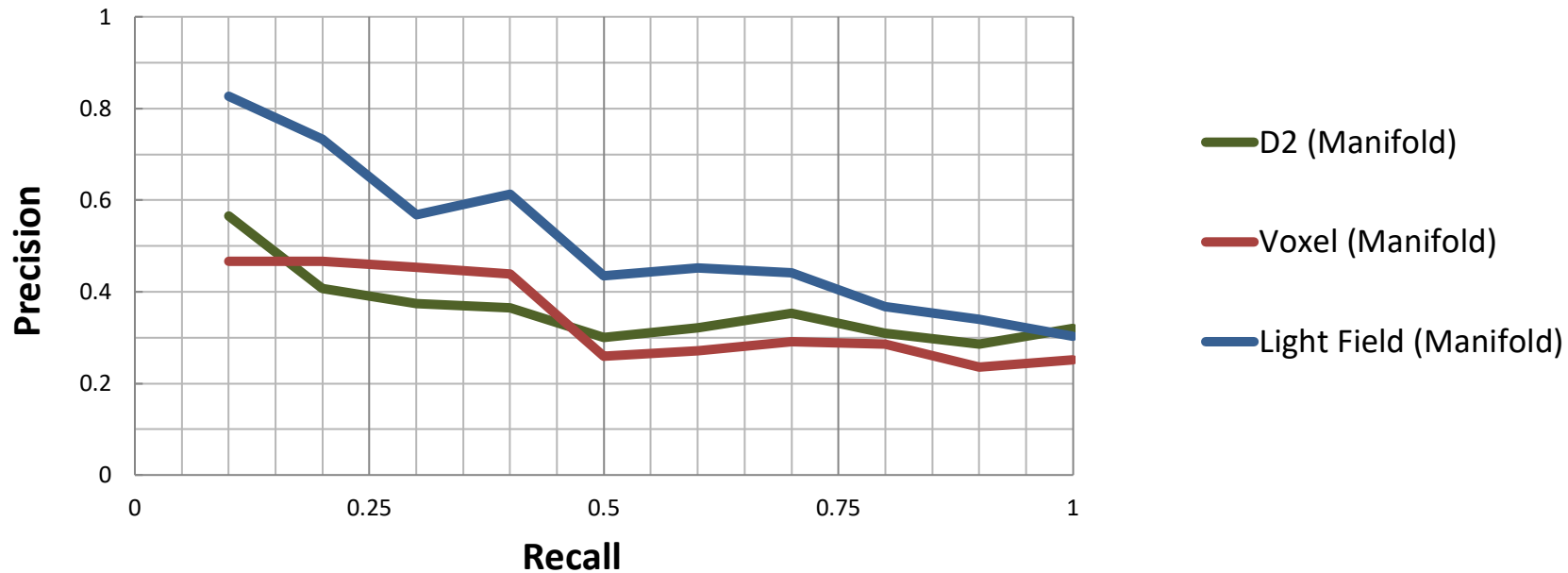
Light Field Descriptor



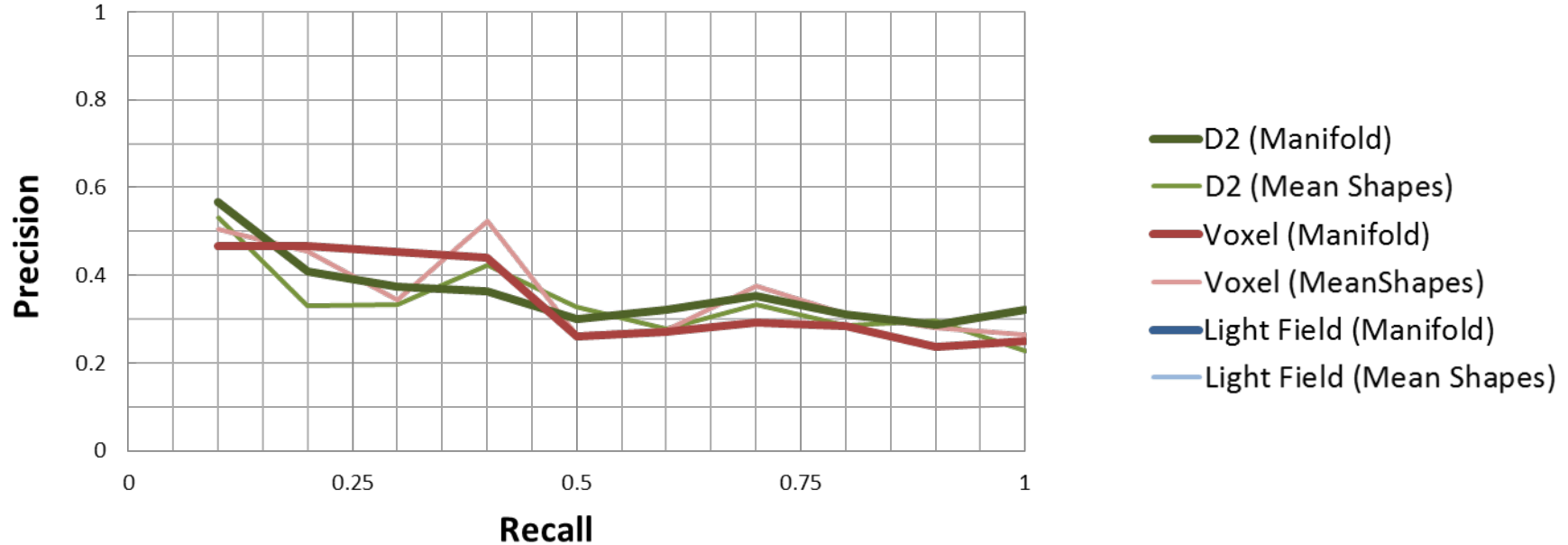
0.6 0.8 1.0 2.0

Error(δ)

Classification



Classification

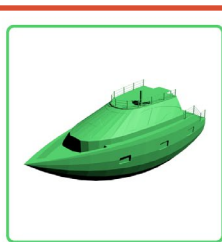
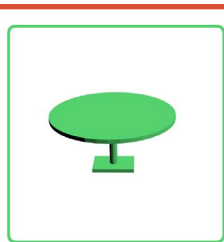


High Quality Descriptors \Rightarrow improves precision/recall

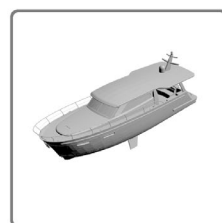
Low Quality Descriptors \Rightarrow additional complexity cannot be captured (noise)

Beyond Classification

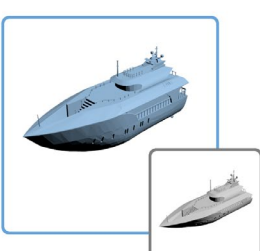
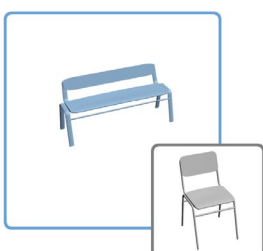
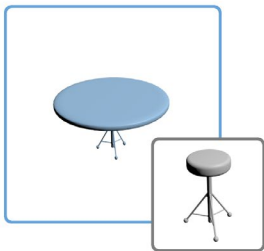
Query



Closest mean shape



Closest parametric Shape(our Method)



Limitation and Future work

- Scalability (number of parameters)

Limitation and Future work

- Scalability (number of parameters)
- Supporting Discrete Variations

Limitation and Future work

- Scalability (number of parameters)
- Supporting Discrete Variations
- Retrieval Methods

Conclusion

First approach for efficient retrieval on a collection of parametric shapes

Acknowledgements

Charles K. Smart

NSF CCF-1138967

Baker Logan

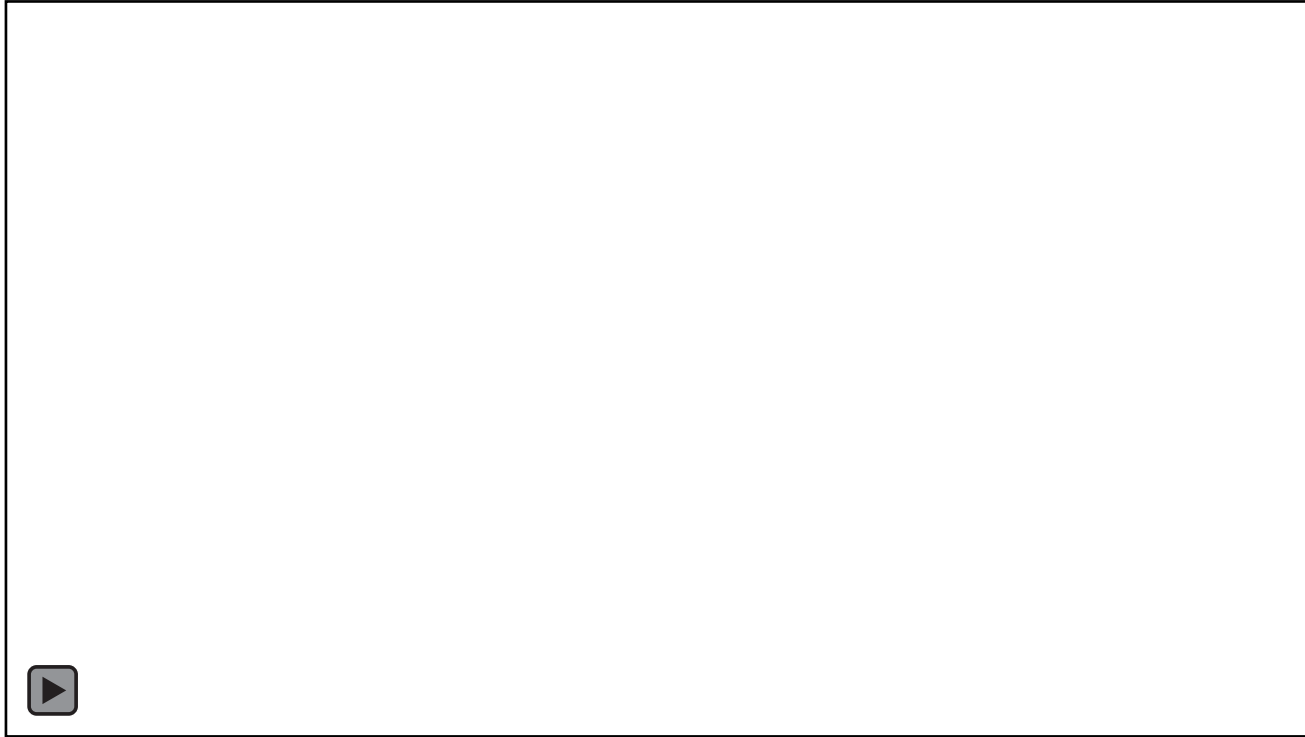
ISF grant 324/11

Marie P. E. Moudio

Jacob Haip

Megan C. Chao

Thank you!



Data available at :
<http://people.csail.mit.edu/aschulz/paramShapeRetrieval>