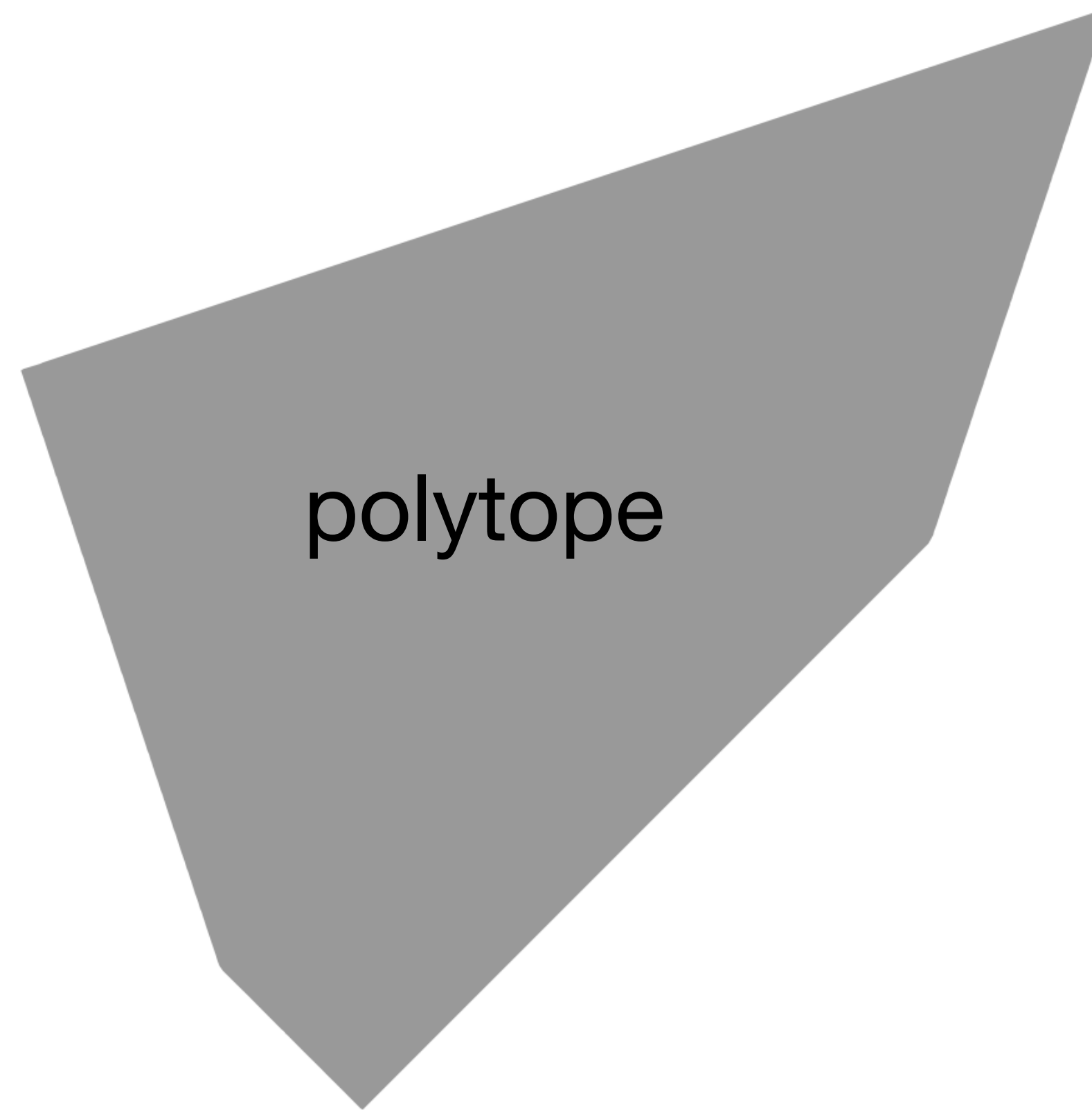


# **Linear Programming**

**A really very extremely big hammer**

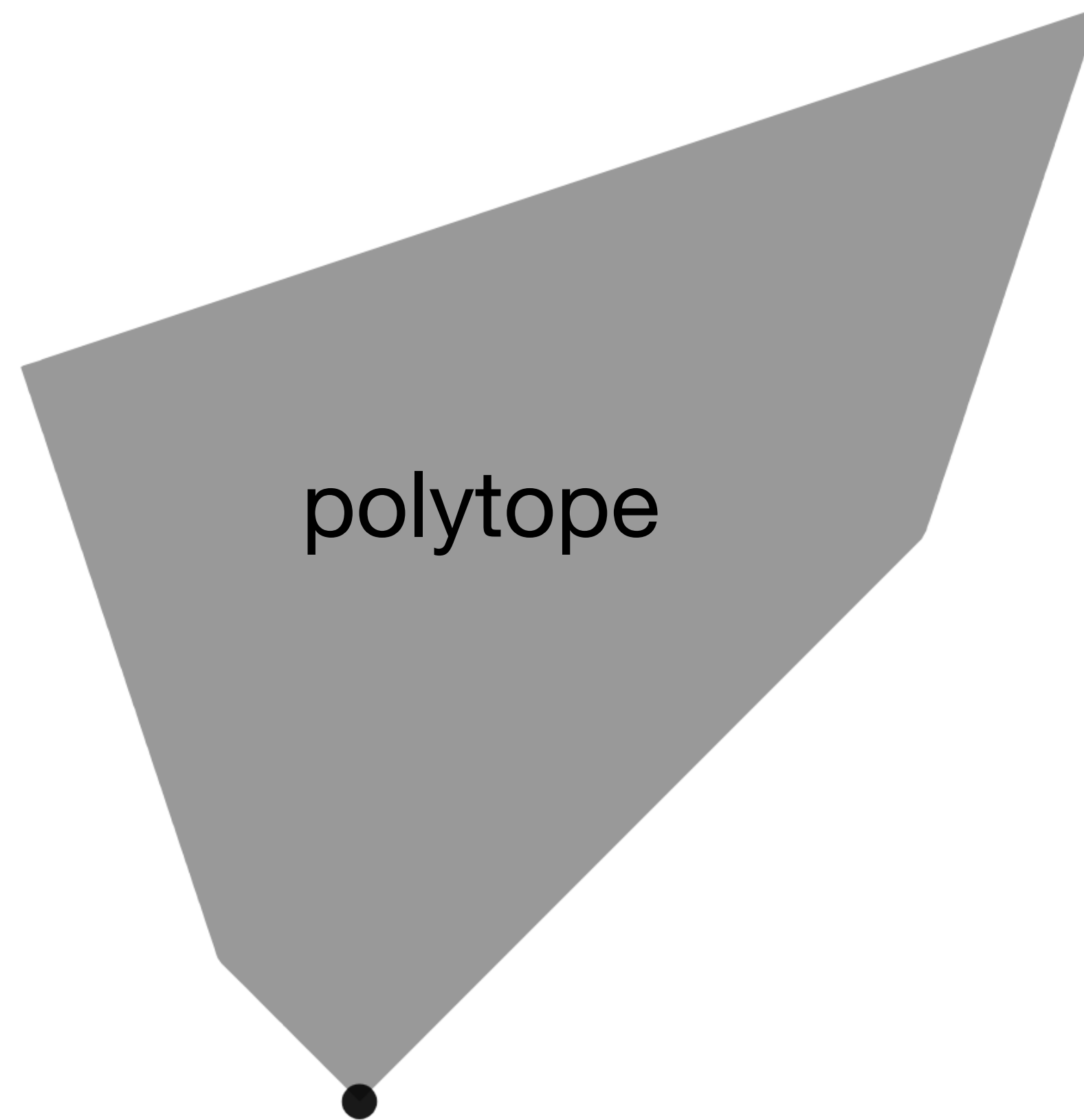
**Given:** a polytope

**Find:** the *lowest* point in the polytope



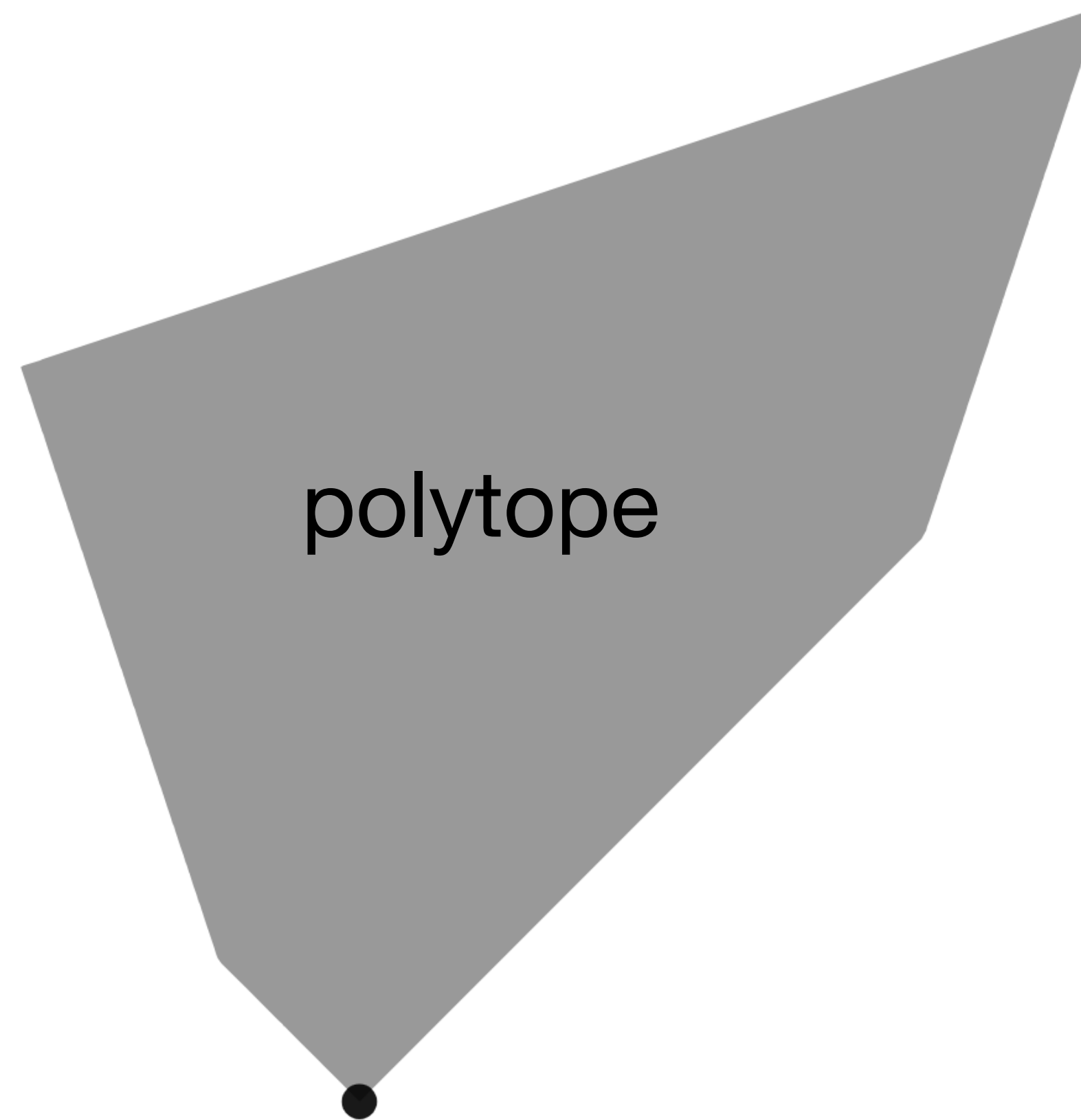
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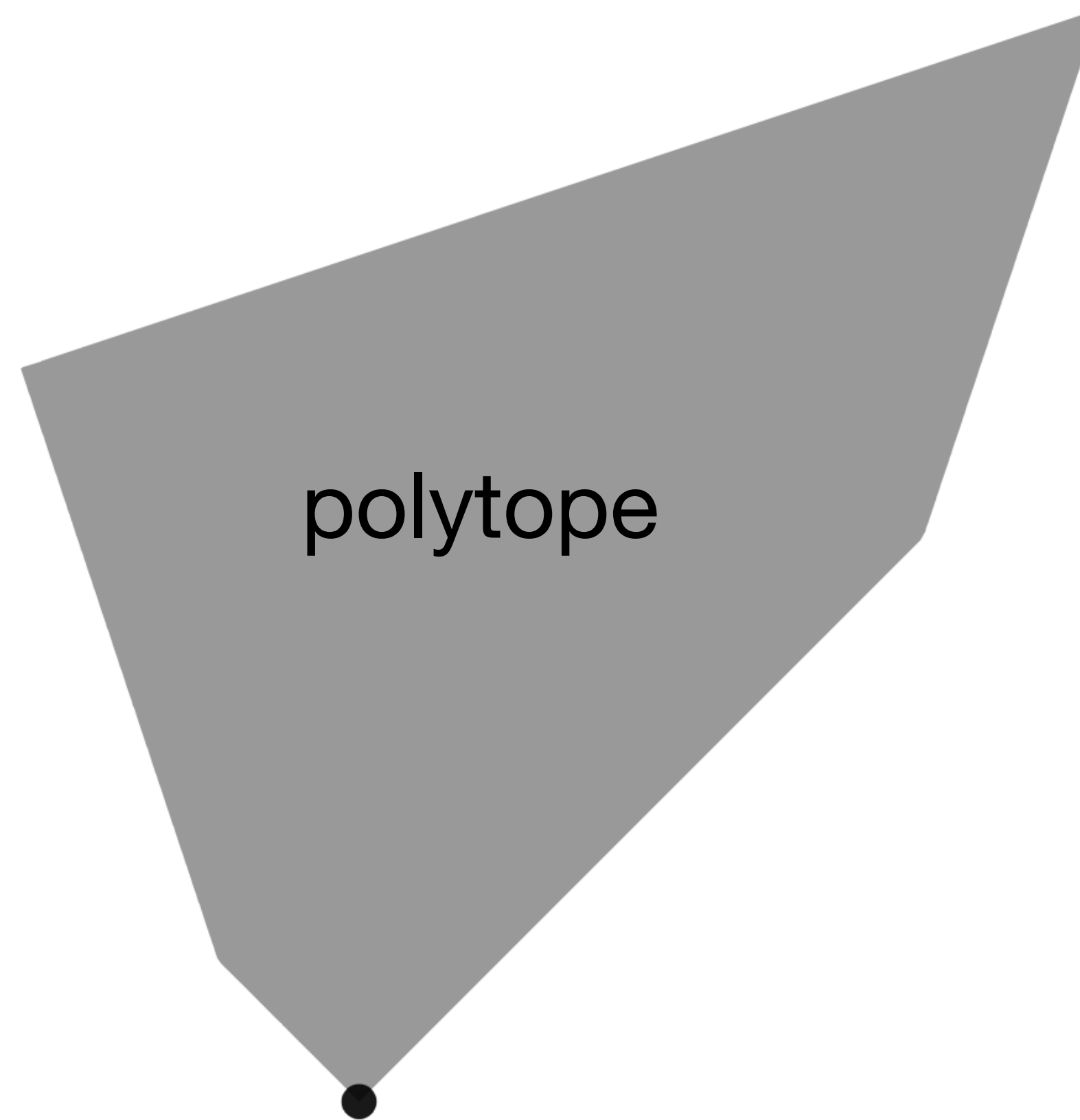
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**maximize**  $z_1 + 2z_3$   
subject to  
 $2z_1 - z_2 + 3z_3 \leq 1$   
 $-z_1 + z_2 - z_3 \leq 5$

**Given:** a polytope

**Find:** the *lowest* point in the polytope



**We have fast  
algorithms for this!**

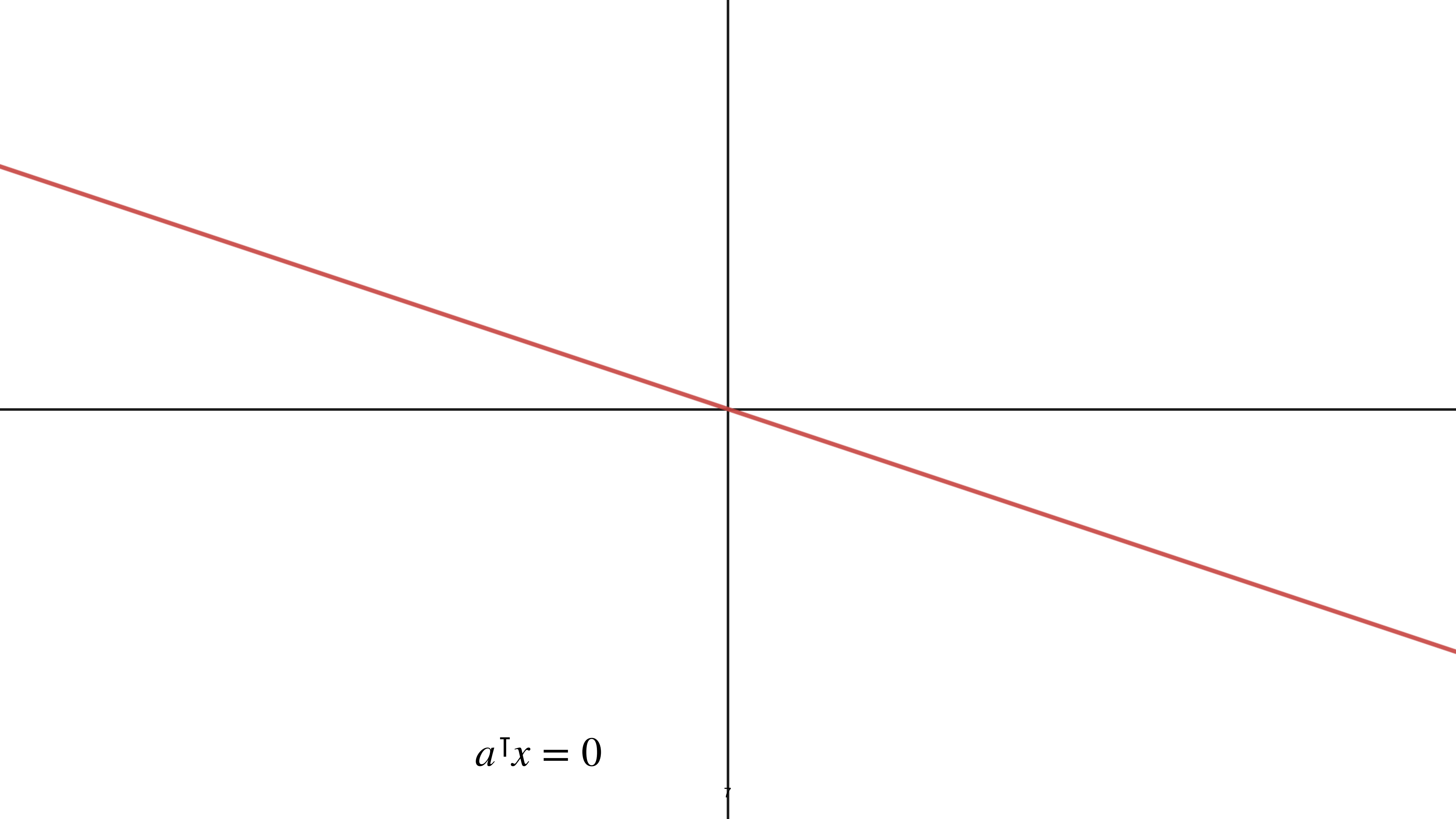
$$\begin{aligned} &\textbf{maximize} \quad z_1 + 2z_3 \\ &\text{subject to} \\ &2z_1 - z_2 + 3z_3 \leq 1 \\ &-z_1 + z_2 - z_3 \leq 5 \end{aligned}$$

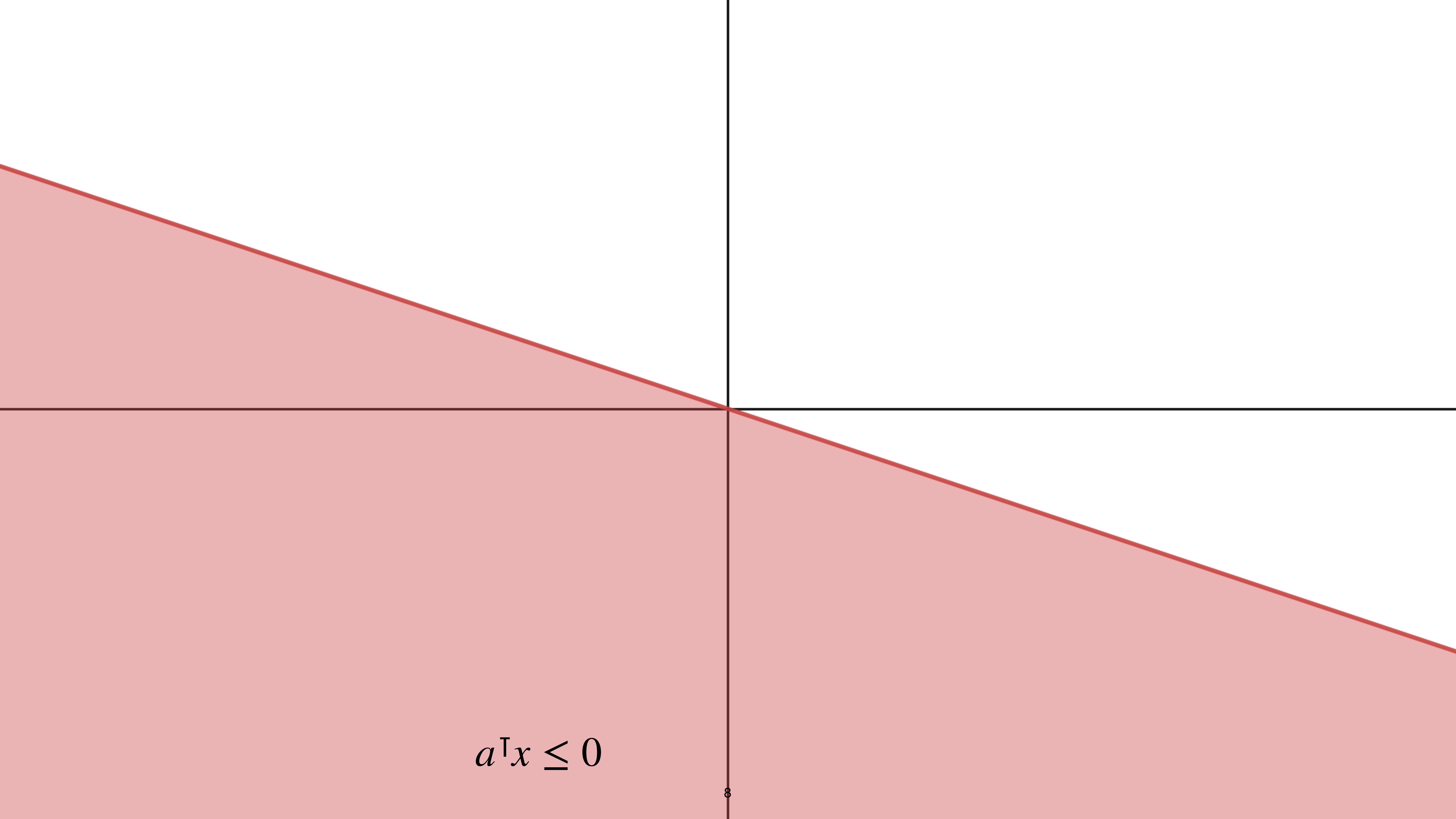
# Linear Algebra primer

$a, x \in \mathbb{R}^n$ , think of them as column vectors.

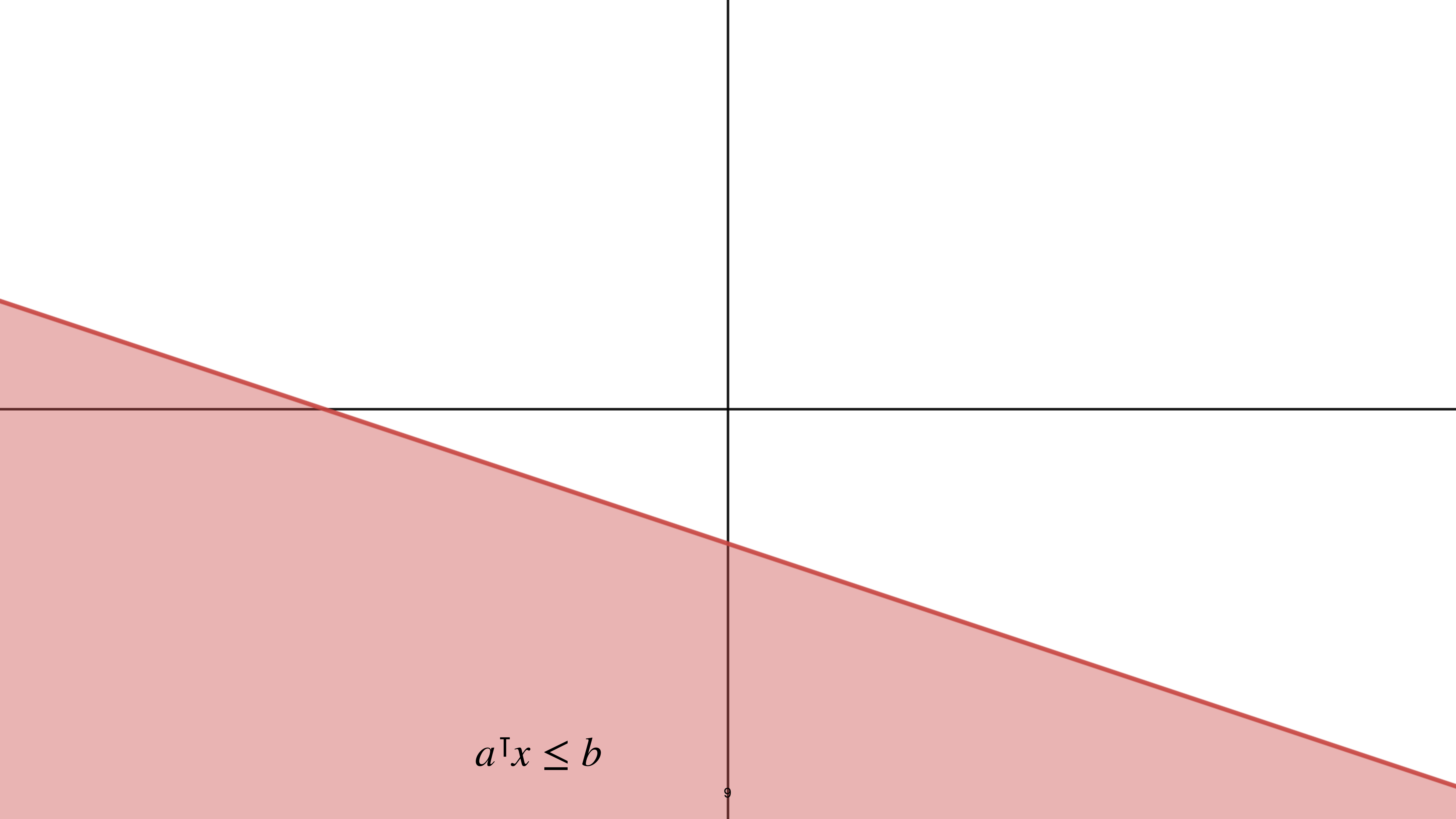
$$a^\top x = a_1 x_1 + \dots + a_n x_n$$

The set of  $x$  satisfying  $a^\top x = 0$  is a *hyperplane*.





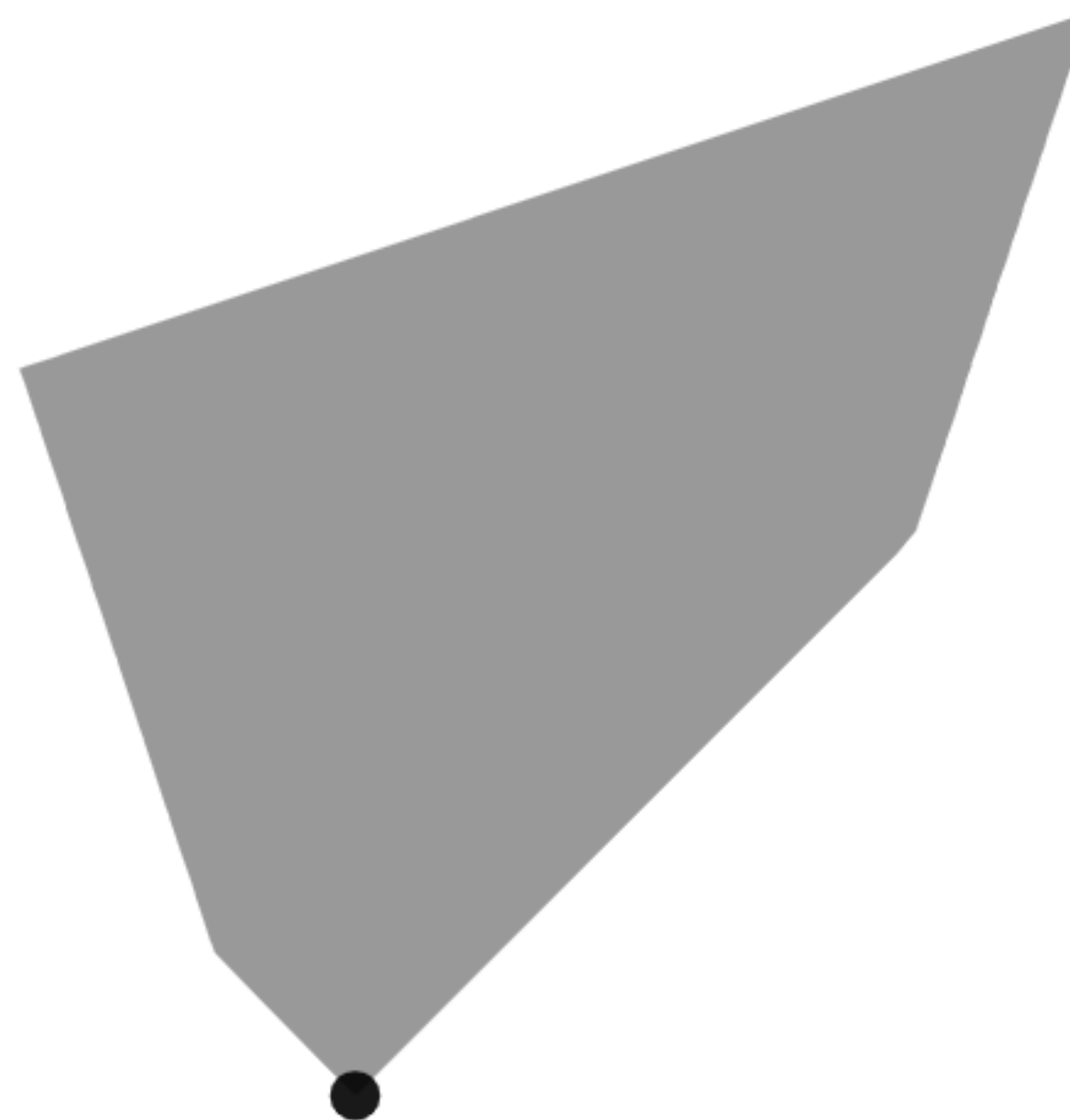




$$a^T x \leq b$$

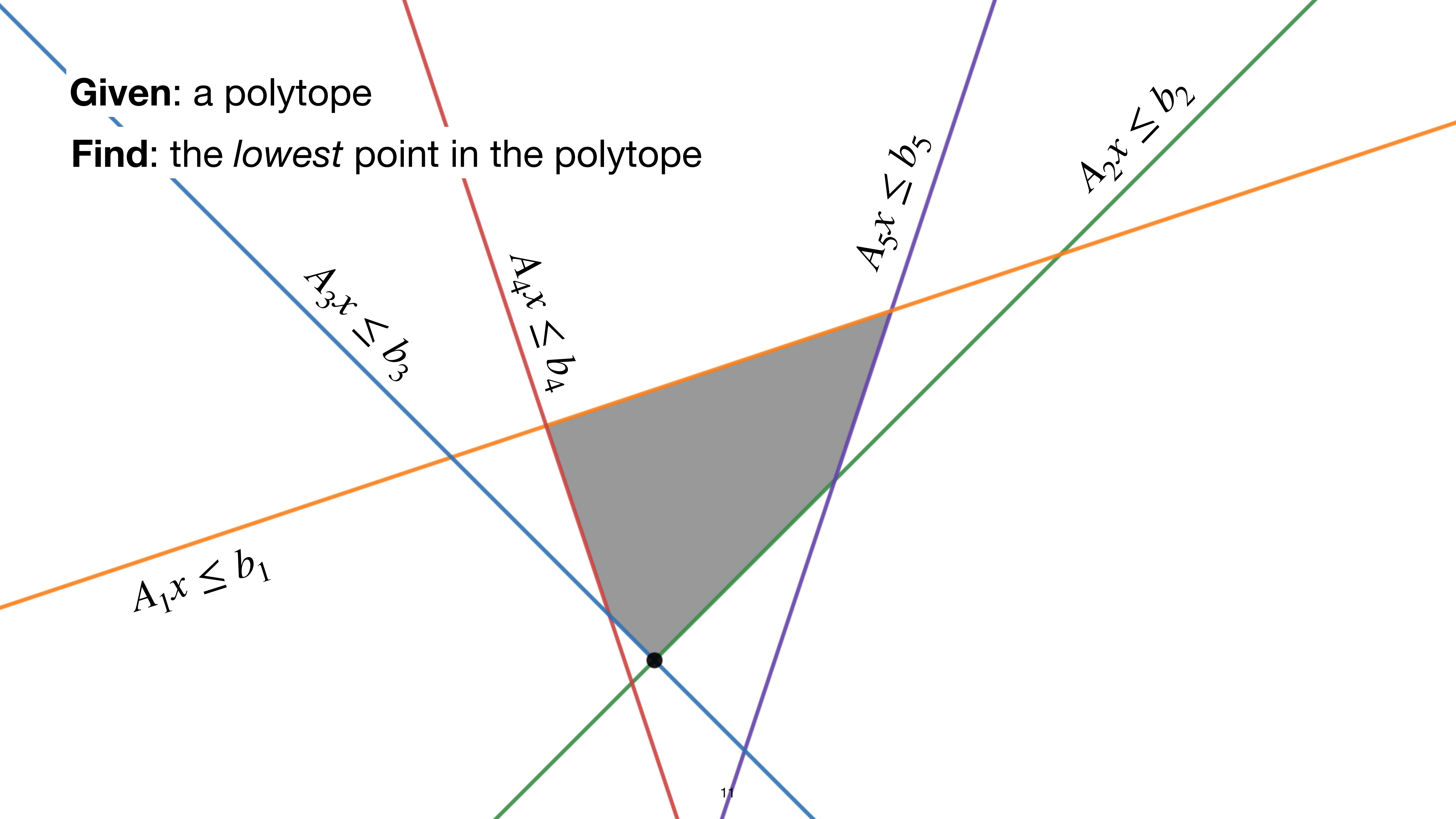
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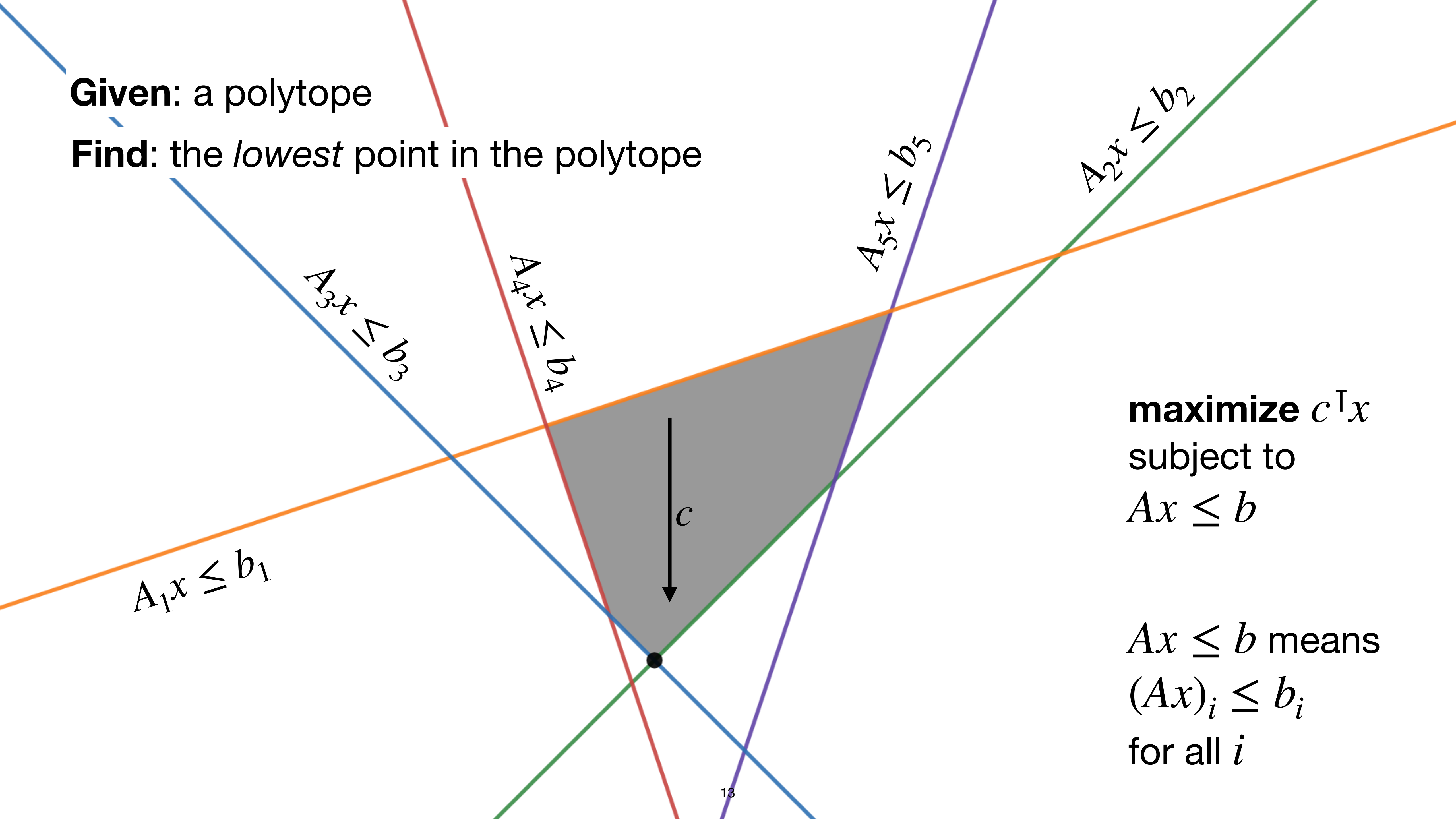
$$a^\top x = a_1 x_1 + \dots + a_n x_n$$

$$Ax = \begin{pmatrix} A_1 x \\ A_2 x \\ A_3 x \end{pmatrix}$$

$$A_m x$$

**Given:** a polytope

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# Standard form

**maximize**  $c^T x$

subject to

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$$x \geq 0$$

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$$\begin{aligned} &\textbf{maximize} \quad c^T x \\ &\text{subject to} \\ &Ax \leq b \\ &x \geq 0 \end{aligned}$$

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$$\begin{aligned} &\textbf{maximize} \quad (x_{1,a} - x_{1,b}) + 2(x_{3,a} - x_{3,b}) \\ &\text{subject to} \\ &2(x_{1,a} - x_{1,b}) - (x_{2,a} - x_{2,b}) + 3(x_{3,a} - x_{3,b}) \leq 1 \\ &-(x_{1,a} - x_{1,b}) + (x_{2,a} - x_{2,b}) - (x_{3,a} - x_{3,b}) \leq 5 \\ &x \geq 0 \end{aligned}$$



# Max Flow

**Given:** a flow network

**maximize** flow out of  $s$

subject to

Respecting capacities and  
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for all  $e$ ,

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$$\text{maximize } c^T x$$

subject to

$$Ax \leq b$$

$$x \geq 0$$

$$1. \quad c_e = \begin{cases} 1 & \text{if } e \text{ out of } s \\ 0 & \text{otherwise.} \end{cases}$$

$$\text{maximize } \sum_{e \text{ out of } s} x_e$$

subject to

for all  $e$ ,

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$$1. \quad c_e = \begin{cases} 1 & \text{if } e \text{ out of } s \\ 0 & \text{otherwise.} \end{cases}$$

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$$4. \quad \text{maximize } c^T x \equiv \text{minimize } (-c)^T x$$

# Shortest paths

**Given:** a directed graph

**Find:** shortest path from  $s$  to  $t$

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**Given:** a directed graph

**Find:** shortest path from  $s$  to  $t$

**Claim:** Length of the shortest path is solution to program.

$$\text{minimize } \sum_e x_e$$

subject to

for all  $e$ ,

$$x_e \geq 0,$$

flow out of  $s$  is 1

$$\sum_{e \text{ out of } s} x_e - \sum_{e \text{ in to } s} x_e = 1,$$

flow into  $t$  is 1

$$\sum_{e \text{ in to } t} x_e - \sum_{e \text{ out of } t} x_e = 1,$$

conservation of flow

for all  $v \neq s, t$ ,

$$\sum_{e \text{ out of } v} x_e = \sum_{e \text{ into } v} x_e$$

# Shortest paths

**Given:** a directed graph

**Find:** shortest path from  $s$  to  $t$

**Claim:** Length of the shortest path is solution to program.

**Proof sketch:** Optimal solution must be a combination of flows on shortest paths. Indeed, if there is a path using edges with  $x_e > 0$  that is not a shortest path, delete the flow on this path and reroute it on a shortest path to get a better solution.

$$\text{minimize } \sum_e x_e$$

subject to

for all  $e$ ,

$$x_e \geq 0,$$

$$\sum_{e \text{ out of } s} x_e - \sum_{e \text{ in to } s} x_e = 1,$$

$$\sum_{e \text{ in to } t} x_e - \sum_{e \text{ out of } t} x_e = 1,$$

for all  $v \neq s, t$ ,

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# Vertex Cover

**Given:** an undirected graph

**Find:** smallest set of vertices touching all edges

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**Find:** smallest set of vertices touching all edges

$$\text{minimize } \sum_v x_v$$

subject to

for all  $v$ ,

$$0 \leq x_v \leq 1,$$

for all  $e = \{u, v\}$

$$x_u + x_v \geq 1$$

# Vertex Cover

**Given:** an undirected graph

**Find:** smallest set of vertices touching all edges

**Want**

$$x_v = 0 \text{ or } x_v = 1$$

**minimize**  $\sum_v x_v$   
subject to

for all  $v$ ,

$$0 \leq x_v \leq 1,$$



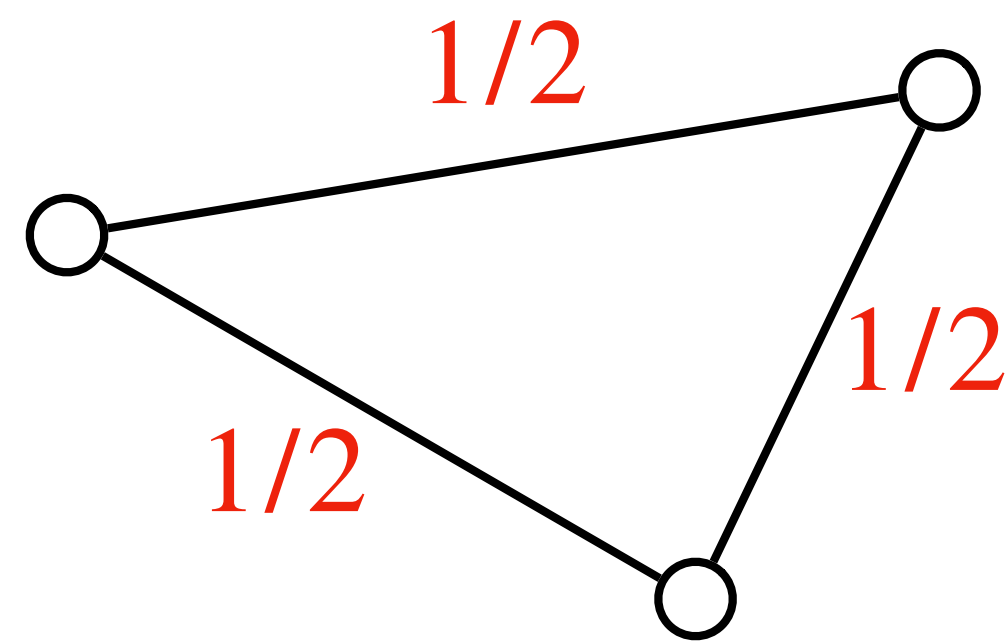
for all  $e = \{u, v\}$

$$x_u + x_v \geq 1$$

# Vertex Cover

**Given:** an undirected graph

**Find:** smallest set of vertices touching all edges



There is a solution of value  $3/2$ , even though smallest vertex cover has size 2.

**Want**

$$x_v = 0 \text{ or } x_v = 1$$

**minimize**  $\sum_v x_v$   
subject to

for all  $v$ ,

$$0 \leq x_v \leq 1,$$



for all  $e = \{u, v\}$

$$x_u + x_v \geq 1$$



# Duality

**maximize**  $x_1 + 2x_3$

subject to

$$2x_1 - x_2 + 3x_3 \leq 1$$

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**Claim:** Optimum  $\leq 6$

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**Claim:** Optimum  $\leq 6$

**Pf:**  $x_1 + 2x_3$

$$= (2x_1 - x_2 + 3x_3) + (-x_1 + x_2 - x_3)$$

$$\leq 6$$

# Duality

**maximize**  $x_1 + 2x_3$   
subject to

$a$   $2x_1 - x_2 + 3x_3 \leq 1$

$b$   $-x_1 + x_2 - x_3 \leq 5$

$x \geq 0$

**Claim:** Optimum  $\leq 6$

**Pf:**  $x_1 + 2x_3$   
 $= (2x_1 - x_2 + 3x_3) + (-x_1 + x_2 - x_3)$   
 $\leq 6$

**Claim:** For all non-negative  $a, b$ , if

$$2a - b \geq 1$$

$$-a + b \geq 0$$

$$3a - b \geq 2$$

then

$$\text{opt} \leq a + 5b$$

**Pf:**

$$\begin{aligned} x_1 + 2x_3 &\leq a(2x_1 - x_2 + 3x_3) + b(-x_1 + x_2 - x_3) \\ &\leq a + 5b. \end{aligned}$$

# Duality

$$\begin{array}{ll} & \textbf{maximize} \ x_1 + 2x_3 \\ & \text{subject to} \\ a \quad & 2x_1 - x_2 + 3x_3 \leq 1 \\ b \quad & -x_1 + x_2 - x_3 \leq 5 \\ & x \geq 0 \end{array}$$

primal

$$\begin{array}{ll} & \textbf{minimize} \ a + 5b \\ & \text{subject to} \\ & 2a - b \geq 1 \\ & -a + b \geq 0 \\ & 3a - b \geq 2 \\ & a, b \geq 0 \end{array}$$

dual

**Claim:** For all non-negative  $a, b$ , if

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**Pf:**

$$x_1 + 2x_3$$

$$\leq a(2x_1 - x_2 + 3x_3) + b(-x_1 + x_2 - x_3)$$

$$\leq a + 5b .$$

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$$\begin{array}{ll} & \text{maximize } x_1 + 2x_3 \\ & \text{subject to} \\ a & 2x_1 - x_2 + 3x_3 \leq 1 \\ b & -x_1 + x_2 - x_3 \leq 5 \\ & x \geq 0 \end{array}$$

primal

$$\begin{array}{ll} & \text{maximize } -a - 5b \\ & \text{subject to} \\ & -2a + b \leq -1 \\ & a - b \leq 0 \\ & -3a + b \leq -2 \\ & a, b \geq 0 \end{array}$$

dual

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$$2a - b \geq 1$$

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then

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**Pf:**

$$x_1 + 2x_3$$

$$\leq a(2x_1 - x_2 + 3x_3) + b(-x_1 + x_2 - x_3)$$

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# Duality

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What is dual of dual?

# Duality

$$\begin{array}{ll} & \textbf{maximize } x_1 + 2x_3 \\ & \text{subject to} \\ a & 2x_1 - x_2 + 3x_3 \leq 1 \\ b & -x_1 + x_2 - x_3 \leq 5 \\ & x \geq 0 \end{array} \quad \text{primal}$$

$$\begin{array}{ll} & \textbf{maximize } -a - 5b \\ & \text{subject to} \\ y_1 & -2a + b \leq -1 \\ y_2 & a - b \leq 0 \\ y_3 & -3a + b \leq -2 \\ & a, b \geq 0 \end{array} \quad \text{dual}$$

What is dual of dual?

$$\begin{array}{ll} & \textbf{minimize } -y_1 - 2y_3 \\ & \text{subject to} \\ & -2y_1 + y_2 - 3y_3 \geq -1 \\ & y_1 - y_2 + y_3 \geq -5 \\ & y \geq 0 \end{array}$$



# Duality

*a*      **maximize**  $x_1 + 2x_3$   
subject to  
*b*       $2x_1 - x_2 + 3x_3 \leq 1$       primal  
          $-x_1 + x_2 - x_3 \leq 5$   
          $x \geq 0$

*y*<sub>1</sub>      **maximize**  $-a - 5b$   
subject to  
*y*<sub>2</sub>       $-2a + b \leq -1$       dual  
*y*<sub>3</sub>       $a - b \leq 0$   
          $-3a + b \leq -2$   
          $a, b \geq 0$

**What is dual of dual?**

**minimize**  $-y_1 - 2y_3$   
subject to  
 $-2y_1 + y_2 - 3y_3 \geq -1$   
 $y_1 - y_2 + y_3 \geq -5$   
 $y \geq 0$

**equivalent to**

**maximize**  $y_1 + 2y_3$   
subject to  
 $2y_1 - y_2 + 3y_3 \leq 1$   
 $-y_1 + y_2 - y_3 \leq 5$   
 $y \geq 0$

# Duality

primal

$$\begin{aligned} &\textbf{maximize} \quad c^\top x \\ &\text{subject to} \\ &Ax \leq b \\ &x \geq 0 \end{aligned}$$

dual

$$\begin{aligned} &\textbf{minimize} \quad b^\top y \\ &\text{subject to} \\ &A^\top y \geq c \\ &y \geq 0 \end{aligned}$$

$\equiv$

dual

$$\begin{aligned} &\textbf{maximize} \quad (-b)^\top y \\ &\text{subject to} \\ &(-A)^\top y \leq -c \\ &y \geq 0 \end{aligned}$$

# Duality

primal

$$\begin{aligned} &\textbf{maximize} \quad c^\top x \\ &\text{subject to} \\ &Ax \leq b \\ &x \geq 0 \end{aligned}$$

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dual

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**Thm:** The dual of the dual is the primal.

# Duality

primal

$$\begin{aligned} &\textbf{maximize } c^T x \\ &\text{subject to} \\ &Ax \leq b \\ &x \geq 0 \end{aligned}$$

dual

$$\begin{aligned} &\textbf{minimize } b^T y \\ &\text{subject to} \\ &A^T y \geq c \\ &y \geq 0 \end{aligned}$$

$\equiv$

dual

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dual of dual

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# Duality

primal

$$\begin{aligned} &\textbf{maximize } c^T x \\ &\text{subject to} \\ &Ax \leq b \\ &x \geq 0 \end{aligned}$$

dual

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$\equiv$

dual

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dual of dual

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# Duality

primal

**maximize**  $c^T x$

subject to

$$Ax \leq b$$

$$x \geq 0$$

dual

**minimize**  $b^T y$

subject to

$$A^T y = c$$

$$y \geq 0$$

**Thm:** The dual of the dual is the primal.

**Thm: (Weak Duality)** Every solution to primal is at most every solution to dual.

# Duality

primal

**maximize**  $c^T x$

subject to

$$Ax \leq b$$

$$x \geq 0$$

dual

**minimize**  $b^T y$

subject to

$$A^T y = c$$

$$y \geq 0$$

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**Thm: (Weak Duality)** Every solution to primal is at most every solution to dual.

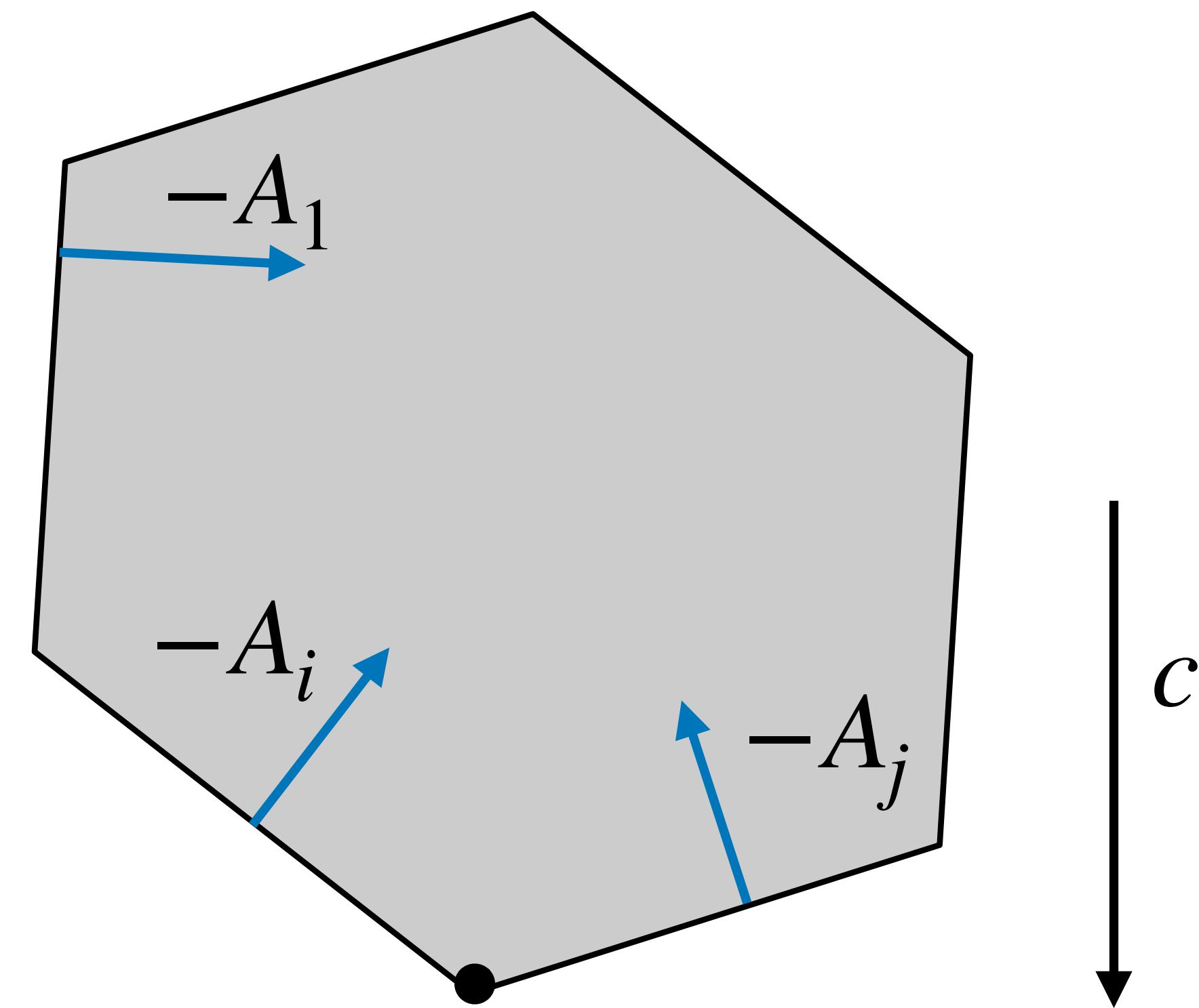
**Thm: (Strong Duality)** If primal has solution of finite value, then value is equal to optimal solution of dual.

# Duality

primal	dual
<b>maximize</b> $c^T x$	<b>minimize</b> $b^T y$
subject to	subject to
$Ax \leq b$	$A^T y \leq c$
$x \geq 0$	$y \geq 0$

**Thm: (Strong Duality)** If primal has solution of finite value, then value is equal to optimal solution of dual.

**Fact:** A vertex is point for which  $n$  of the inequalities become tight.



**By physics:**

There must be  $y_i, y_j \geq 0$

$$y_i A_i + y_j A_j = c.$$

If  $\hat{A}x = \hat{b}$  correspond to sides touching  $x$ ,  
 $A^T y = \hat{A}^T \hat{y} = c.$

Then

$$b^T y_{48} = \hat{b}^T \hat{y} = (\hat{A}x)^T y = x^T \hat{A}^T \hat{y} = x^T c = c^T x$$



# Duality of Max flow

$$\text{maximize } \sum_{e \text{ out of } s} x_e$$

subject to

for all  $e$ ,

$$0 \leq x_e \leq c(e)$$

for all intermediate  $v$ ,

$$\sum_{e \text{ out of } v} x_e = \sum_{e \text{ into } v} x_e$$

$$\text{minimize } c^T a$$

subject to

for all  $e = (s, v)$ ,

$$a_e + b_v \geq 1$$

for all  $e = (u, t)$ ,

$$a_e - b_u \geq 0$$

for all other  $e = (u, v)$ ,

$$a_e - b_u + b_v \geq 0$$

for all  $e$

$$a_e \geq 0$$

# Duality of Max flow

$$\text{maximize } \sum_{e \text{ out of } s} x_e$$

subject to

$$\text{for all } e, \\ 0 \leq x_e \leq c(e)$$

for all intermediate  $v$ ,

$$\sum_{e \text{ out of } v} x_e = \sum_{e \text{ into } v} x_e$$

$$\text{minimize } c^T a$$

subject to

$$\text{for all } e = (s, v),$$

$$a_e + b_v \geq 1$$

$$\text{for all } e = (u, t),$$

$$a_e - b_u \geq 0$$

$$\text{for all other } e = (u, v),$$

$$a_e - b_u + b_v \geq 0$$

for all  $e$

$$a_e \geq 0$$

$$\text{minimize } c^T a$$

subject to

$$b_s = 1, b_t = 0$$

$$\text{for all } e = (u, v),$$

$$a_e \geq b_u - b_v$$

for all  $e$

$$a_e \geq 0$$

$\equiv$

**minimize**  $c^\top a$

subject to

for all  $e = (s, v)$ ,

$$a_e + b_v \leq 1$$

for all  $e = (u, t)$ ,

$$a_e - b_u \leq 0$$

for all other  $e = (u, v)$ ,

$$a_e - b_u + b_v \leq 0$$

for all  $e$

$$a_e \geq 0$$

$\equiv$

**minimize**  $c^\top a$

subject to

$$b_s = 1, b_t = 0$$

for all  $e = (u, v)$ ,

$$a_e \geq b_u - b_v$$

for all  $e$

$$a_e \geq 0$$

$\equiv$

**minimize**  $c^\top a$

subject to

$$b_s = 1, b_t = 0$$

for all  $e = (u, v)$ ,

$$a_e = \max\{0, b_u - b_v\}$$

**minimize**  $c^T a$

subject to

$$b_s = 1, b_t = 0$$

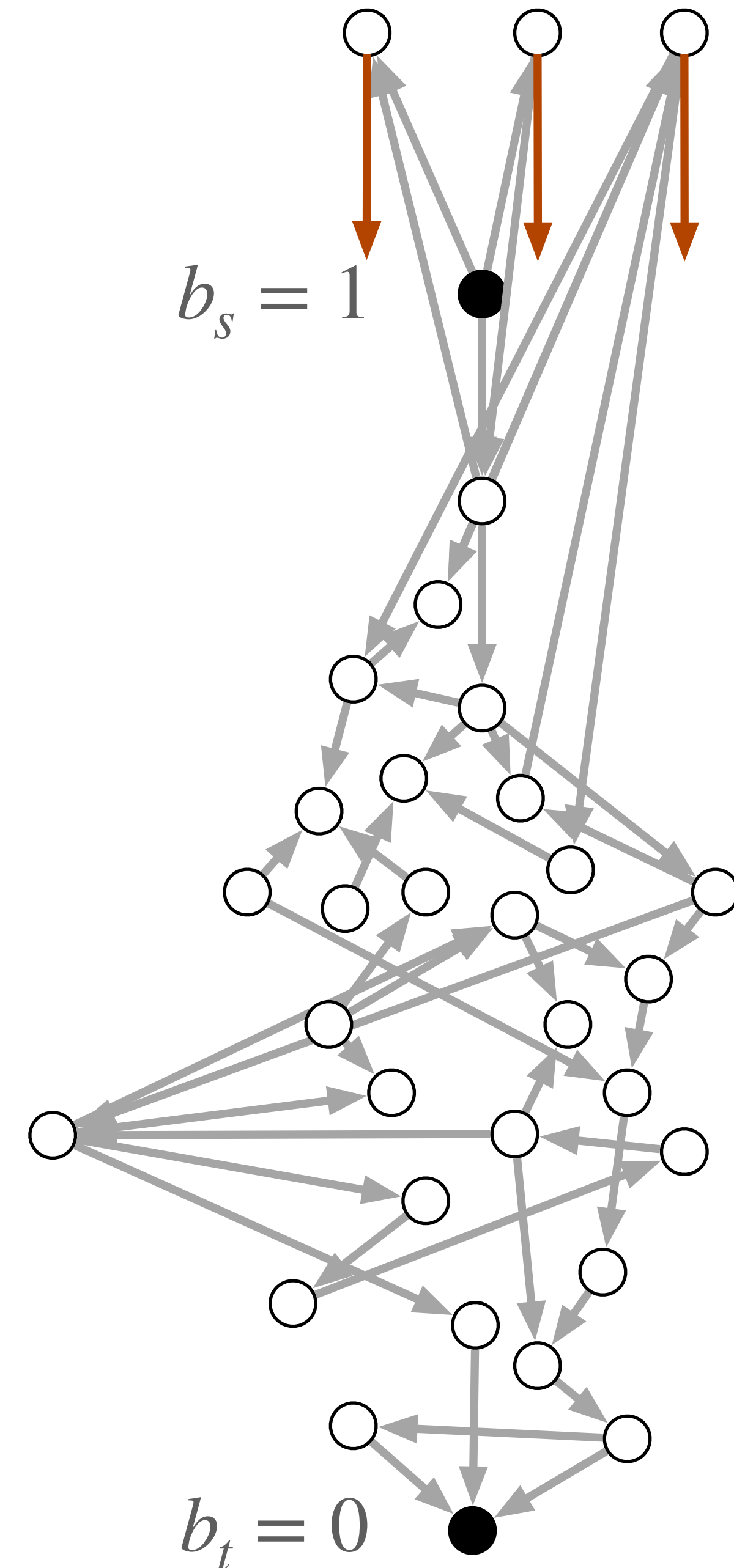
$$0 \leq b_u \leq 1$$

for all  $e = (u, v)$ ,

$$a_e = \max\{0, b_u - b_v\}$$

**Claim:** Opt is achieved with  
 $1 \geq b_u \geq 0$ .

Pf: Take any solution and  
move the extreme values  
up/down. The solution only  
improves.



**minimize**  $c^\top a$

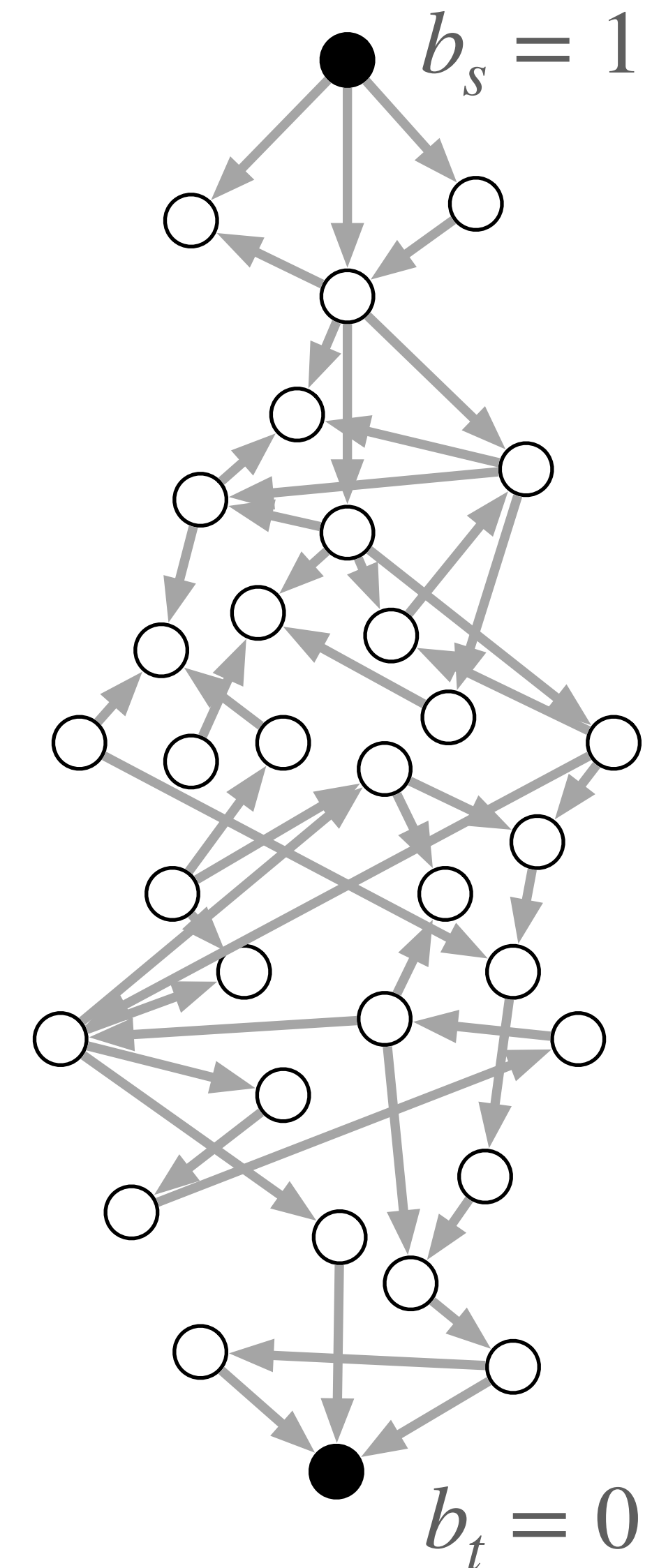
subject to

$$b_s = 1, b_t = 0$$

$$0 \leq b_u \leq 1$$

for all  $e = (u, v)$ ,

$$a_e = \max\{0, b_u - b_v\}$$



**minimize**  $c^\top a$

subject to

$$b_s = 1, b_t = 0$$

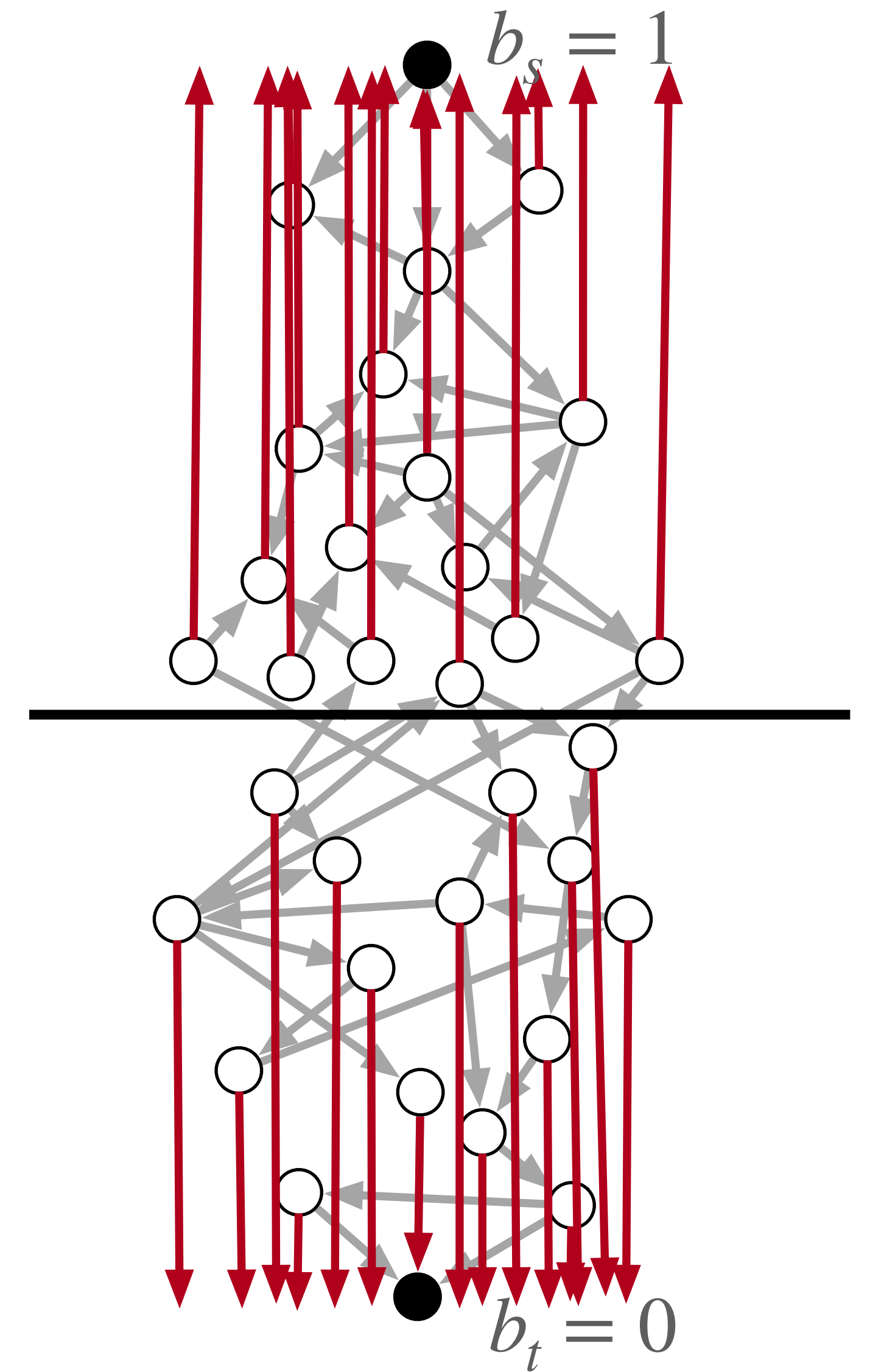
$$0 \leq b_u \leq 1$$

for all  $e = (u, v)$ ,

$$a_e = \max\{0, b_u - b_v\}$$

**Claim:** Opt is achieved with  
 $b_u = 0/1$ .

Pf: Pick  $0 \leq t \leq 1$   
uniformly at random. If  
 $b_u \geq t$ , set  $b_u = 1$ ,  
otherwise set it to 0. The  
expected value of resulting  
solution is the same as  
original!



**minimize**  $c^\top a$

subject to

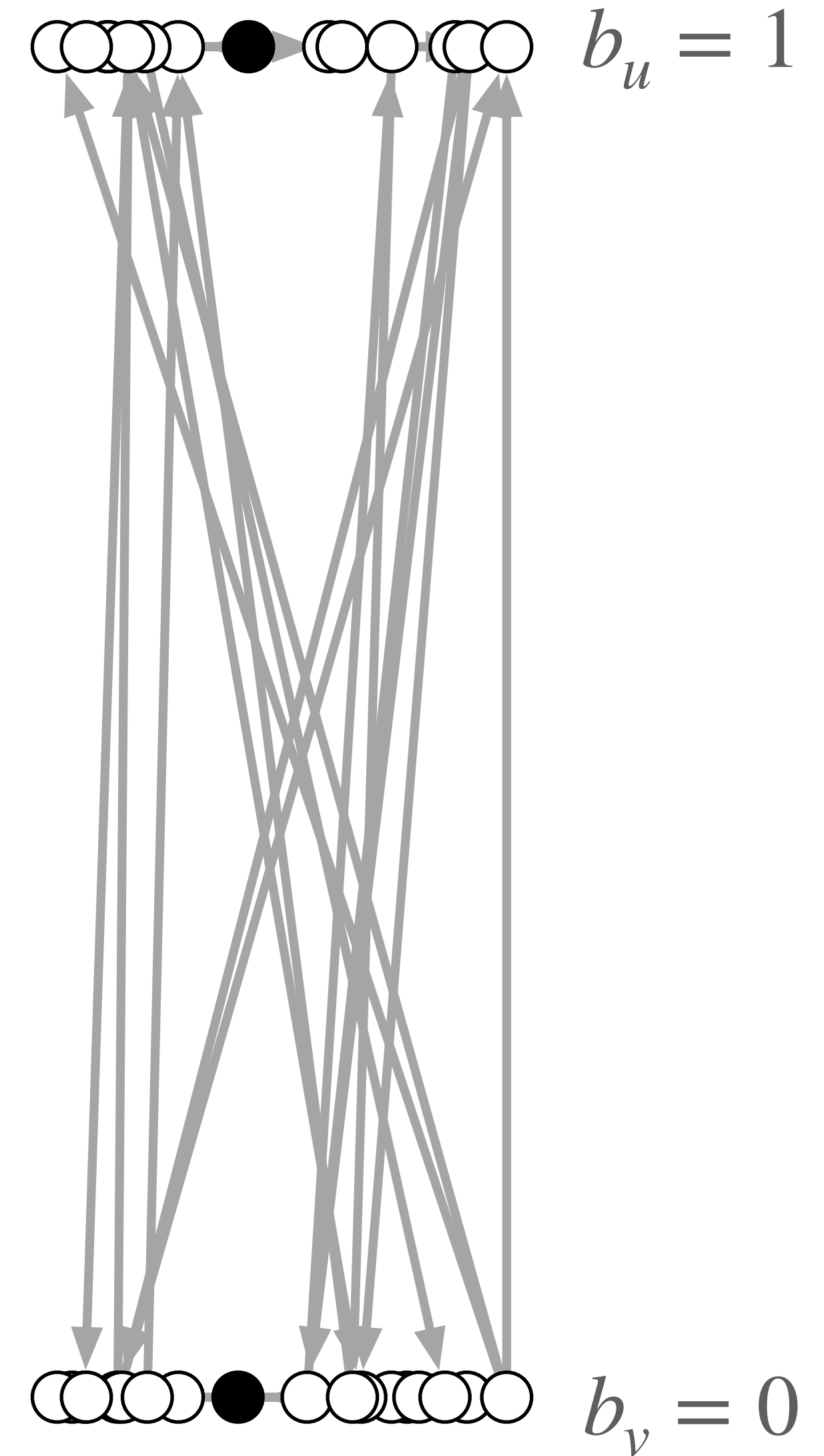
$$b_s = 1, b_t = 0$$

$$b_u \in \{0, 1\}$$

for all  $e = (u, v)$ ,

$$a_e = \max\{0, b_u - b_v\}$$

Min-Cut!



# Duality of Shortest Path

$$\text{minimize } \sum_e x_e$$

subject to

for all  $e$ ,

$$x_e \geq 0,$$

$$\sum_{e \text{ out of } s} x_e - \sum_{e \text{ in to } s} x_e = 1,$$

$$\sum_{e \text{ out of } t} x_e - \sum_{e \text{ in to } t} x_e = -1,$$

for all  $v \neq s, t$ ,

$$\sum_{e \text{ out of } v} x_e - \sum_{e \text{ into } v} x_e = 0$$



# Duality of Shortest Path

$$\text{minimize } \sum_e x_e$$

subject to

for all  $e$ ,

$$x_e \geq 0,$$

$$\sum_{e \text{ out of } s} x_e - \sum_{e \text{ in to } s} x_e = 1,$$

$$\sum_{e \text{ out of } t} x_e - \sum_{e \text{ in to } t} x_e = -1,$$

for all  $v \neq s, t$ ,

$$\sum_{e \text{ out of } v} x_e - \sum_{e \text{ into } v} x_e = 0$$

dual

$$\text{maximize } a_s - a_t$$

subject to

for all edges  $e = (u, v)$ ,

$$a_u - a_v \leq 1$$

# Duality of Shortest Path

$$\text{minimize } \sum_e x_e$$

subject to

for all  $e$ ,

$$x_e \geq 0,$$

$$\sum_{e \text{ out of } s} x_e - \sum_{e \text{ in to } s} x_e = 1,$$

$$\sum_{e \text{ out of } t} x_e - \sum_{e \text{ in to } t} x_e = -1,$$

for all  $v \neq s, t$ ,

$$\sum_{e \text{ out of } v} x_e - \sum_{e \text{ into } v} x_e = 0$$

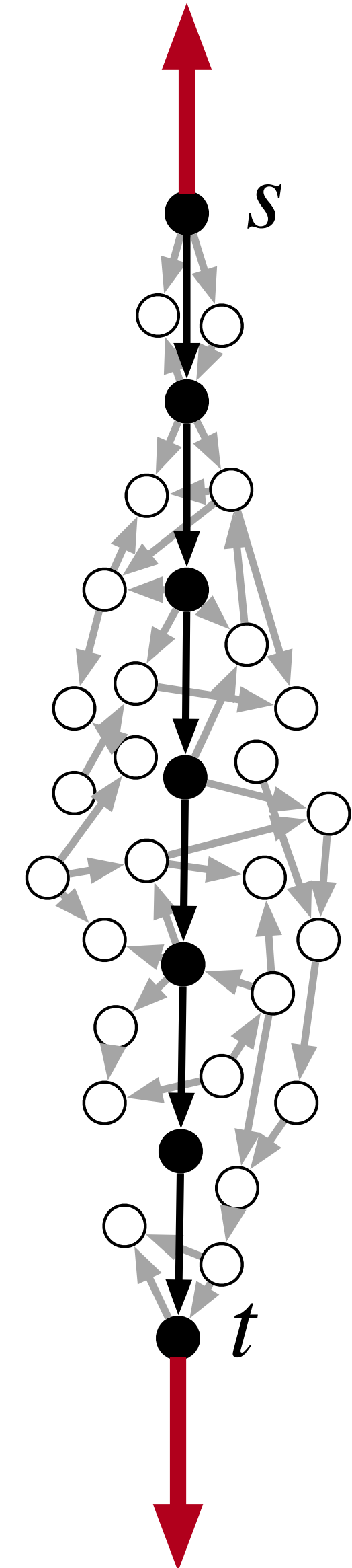
dual

$$\text{maximize } a_s - a_t$$

subject to

for all edges  $e = (u, v)$ ,

$$a_u - a_v \leq 1$$



# Duality and zero-sum games

## Two player zero-sum game:

an  $m \times n$  matrix  $G$

$G_{i,j}$ : payoff to row player, assuming row player uses strategy  $i$ , and column player uses strategy  $j$ .

–  $G_{i,j}$ : payoff to column player.

Example: Chess

$i$ : specifies how white would move in every possible board configuration.

$j$ : specifies how black would move.

$$G_{i,j} = \begin{cases} 1 & \text{if white wins} \\ -1 & \text{if black wins} \\ 0 & \text{stalemate} \end{cases}$$

## Randomized strategy:

probability distribution on row strategies

A column vector  $x$  with

$$x_i \geq 0, \sum_i x_i = 1$$

probability distribution on column strategies

$$y_j \geq 0, \sum_j y_j = 1$$

expected payoff to row player

$$x^T G y$$

# Who decides on their strategy first?

**If row player commits to  $x$**

Row player will get payoff

$$\min_y x^\top G y = \min_j (x^\top G)_j$$

So, if row player has to play first:

$$\max_x \min_y x^\top G y$$

**If column player commits to  $y$**

Row player will get payoff

$$\max_x x^\top G y = \max_i (G y)_i$$

So, if column player has to play first

$$\min_y \max_x x^\top G y$$

**Randomized strategy:**

probability distribution on row strategies

A column vector  $x$  with

$$x_i \geq 0, \sum_i x_i = 1$$

probability distribution on column strategies

$$y_j \geq 0, \sum_j y_j = 1$$

expected payoff to row player

$$x^\top G y$$

# von-Neumann's min-max Theorem

**If row player commits to  $x$**

Row player will get payoff

$$\min_y x^\top G y = \min_j (x^\top G)_j$$

So, if row player has to play first:

$$\max_x \min_y x^\top G y$$

**If column player commits to  $y$**

Row player will get payoff

$$\max_x x^\top G y = \max_i (G y)_i$$

So, if column player has to play first

$$\min_y \max_x x^\top G y$$

Doesn't matter who plays first:

**Thm:**

$$\max_x \min_y x^\top G y = \min_y \max_x x^\top G y.$$

# Using strong duality

$$\text{Thm: } \max_x \min_y x^\top G y = \min_y \max_x x^\top G y.$$

$$\max_x \min_j (x^\top G)_j = \min_y \max_i (Gy)_i$$

primal

**maximize**  $z$   
subject to

$$x_1 + \dots + x_m = 1$$

for all  $j$ ,

$$z \leq (x^\top G)_j$$

$$x \geq 0$$

dual

**minimize**  $w$   
subject to

coefficient of  $z$  must be 1

$$y_1 + \dots + y_m = 1$$

for all  $i$ ,

coefficient of  $x_i$  must be  $\geq 0$

$$w \geq (Gy)_i$$

$$y \geq 0$$

# Algorithms for Linear programs

## **Simplex Algorithm**

Simple

Often fast in practice

Not polynomial time (on pathological counterexamples)

## **Ellipsoid Algorithm**

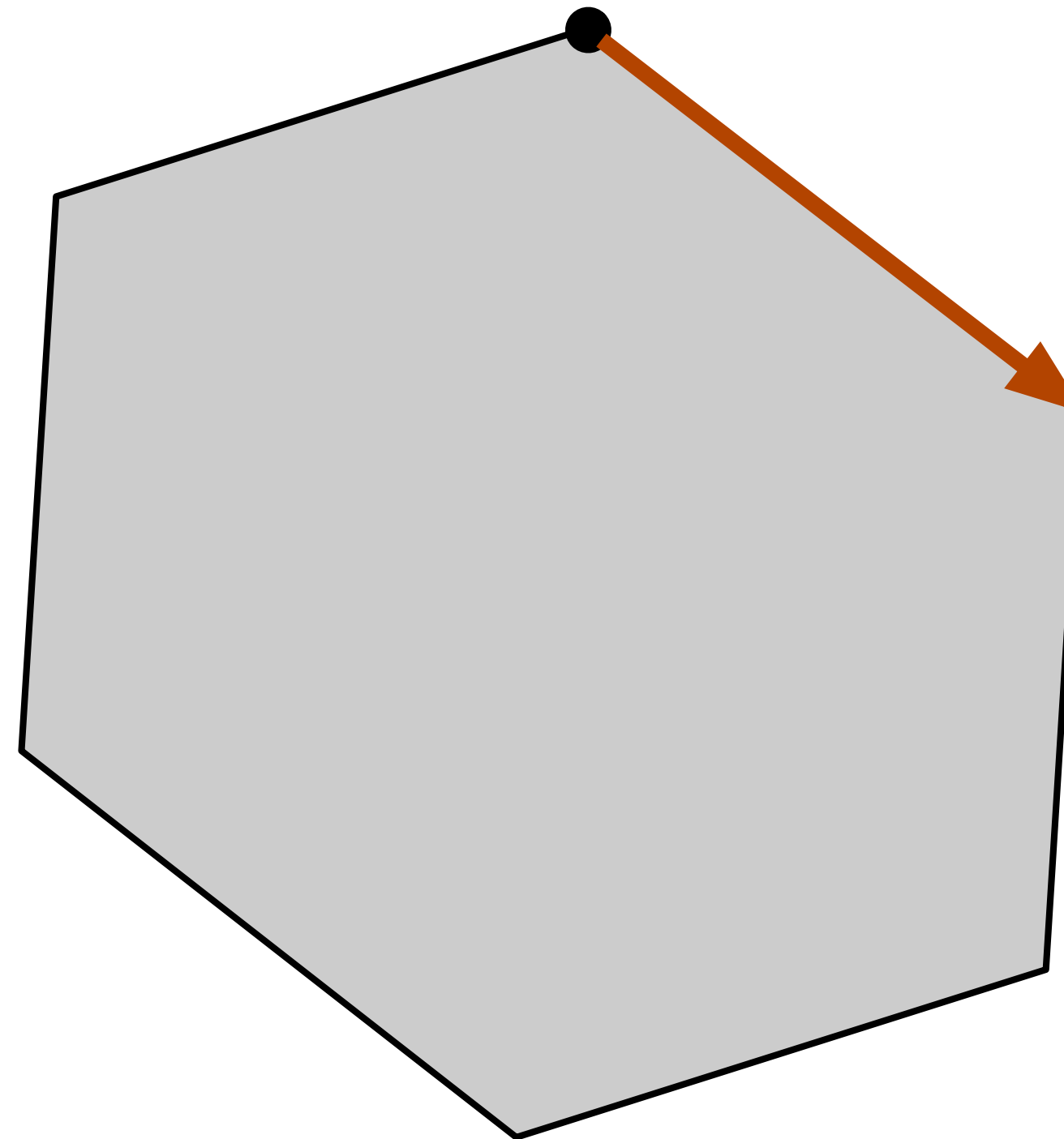
More complicated

Polynomial time, but not always fast

# Simplex

Start with a vertex  
In each step,  
move to a lower vertex

Problem: Number of vertices  
on this path can be  
exponential!





# Simplex: how to find initial vertex?

**maximize**  $c^T x$   
subject to  
 $Ax \leq b$   
 $x \geq 0$



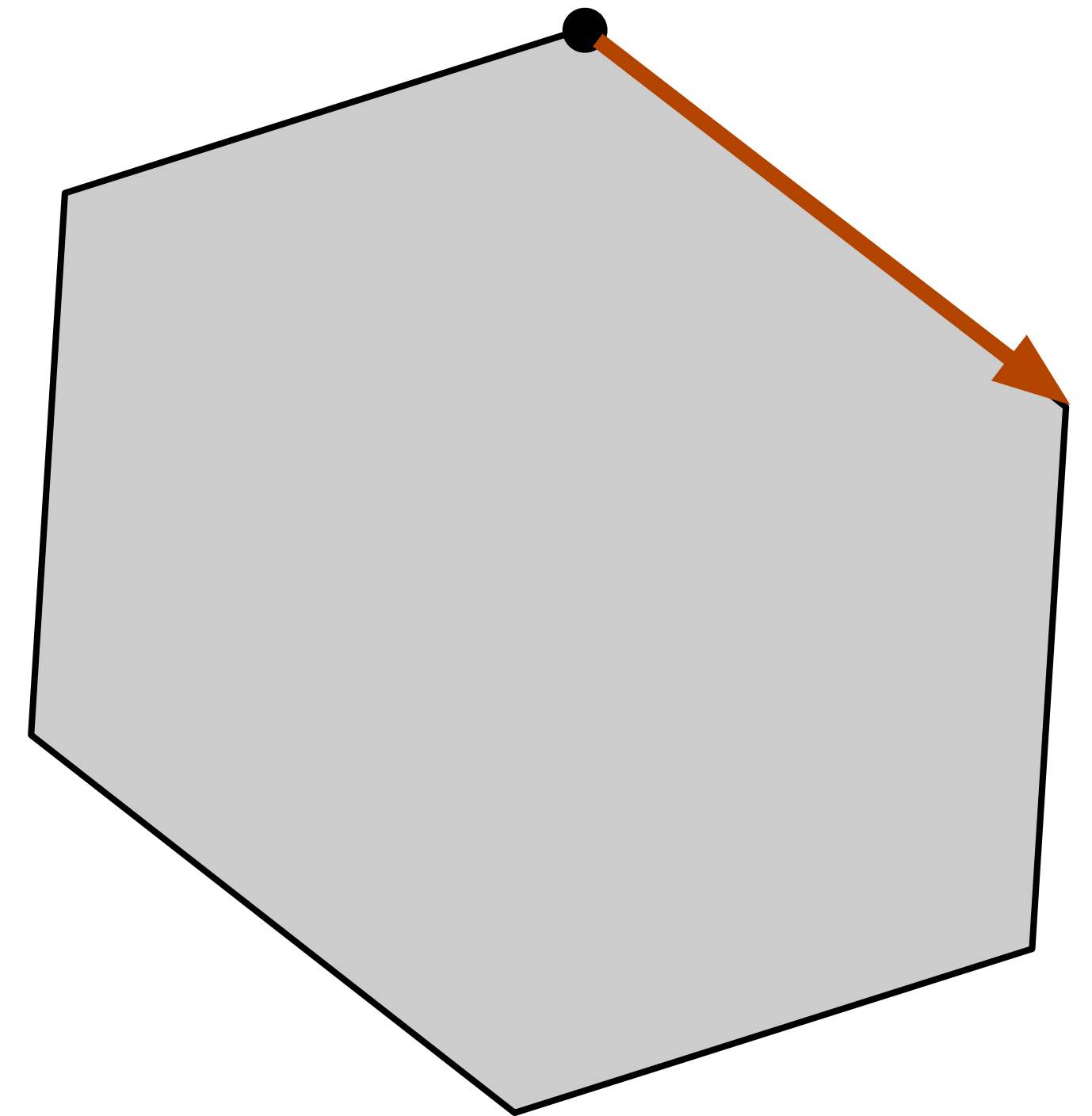
**minimize**  $z_1 + z_2 + \dots$   
subject to  
 $Ax \leq b + z$   
 $x, z \geq 0$

For this program,  $z_i = \max\{0, -b_i\}$ ,  $x = 0$  is a vertex. Run simplex to find a solution with  $z = 0$ . The  $x$  value of solution will be a vertex of original program!

# Simplex: how to go to better vertex?

**maximize**  $c^T x$   
subject to  
 $Ax \leq b$   
 $x \geq 0$

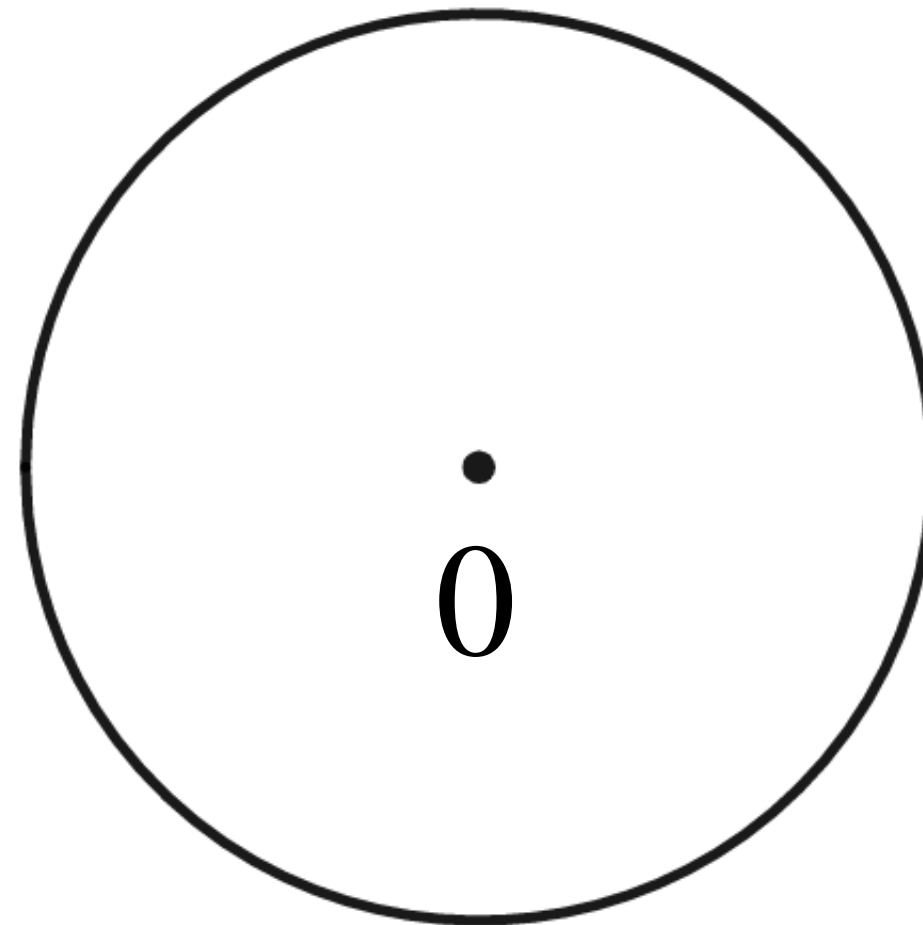
1. There must be  $\hat{A}x = \hat{b}$ .
2. Find  $y$  satisfying  $n - 1$  of the equations,  $c^T y > 0$ .
3. Change  $x = x + \epsilon y$ , until some new equation becomes tight.



# Ellipsoid method

*Ellipsoid*: a squished ball

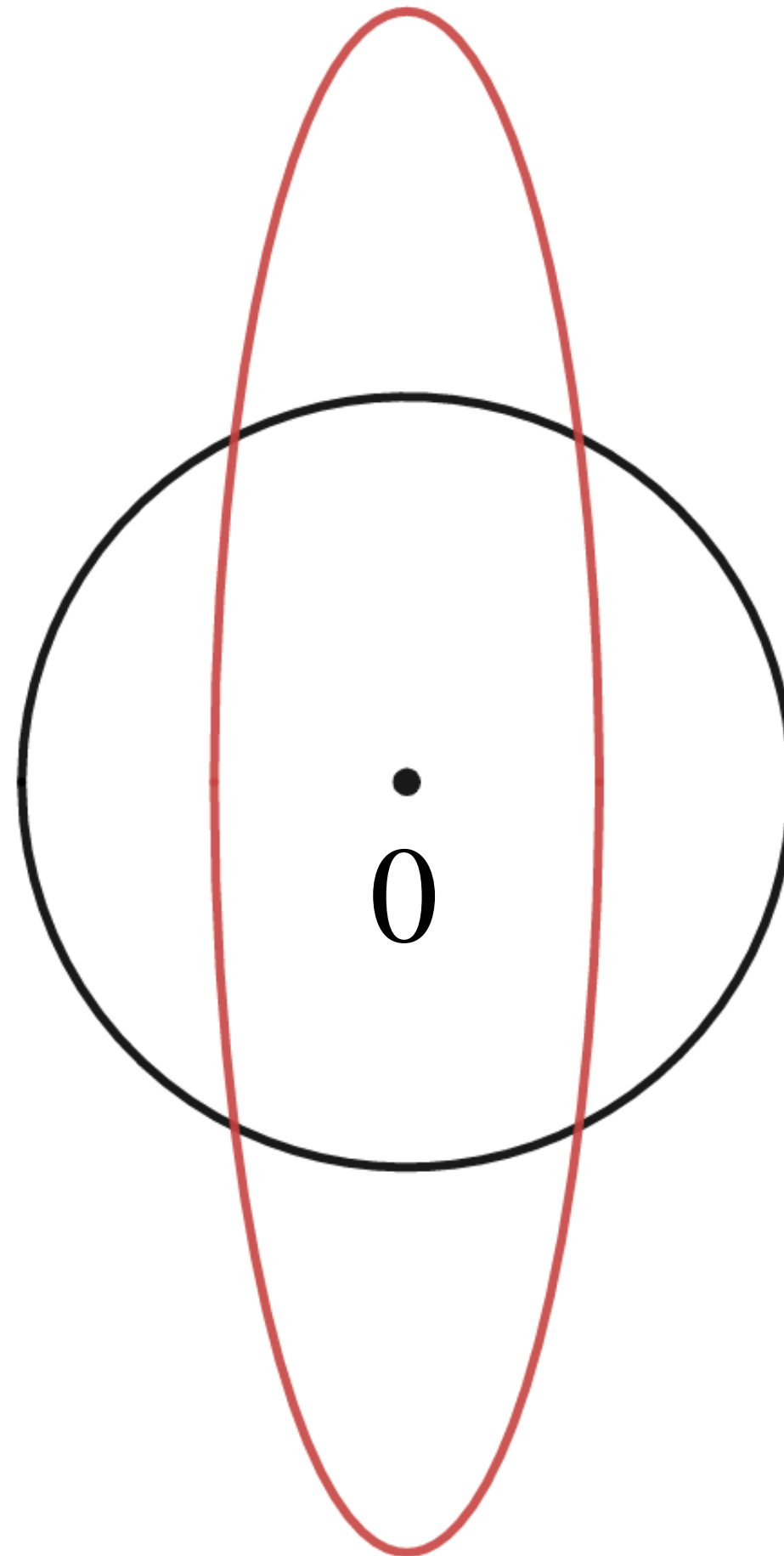
$$x^2 + y^2 \leq 1$$



# Ellipsoid method

*Ellipsoid*: a squished ball

$$x^2 + y^2 \leq 1$$

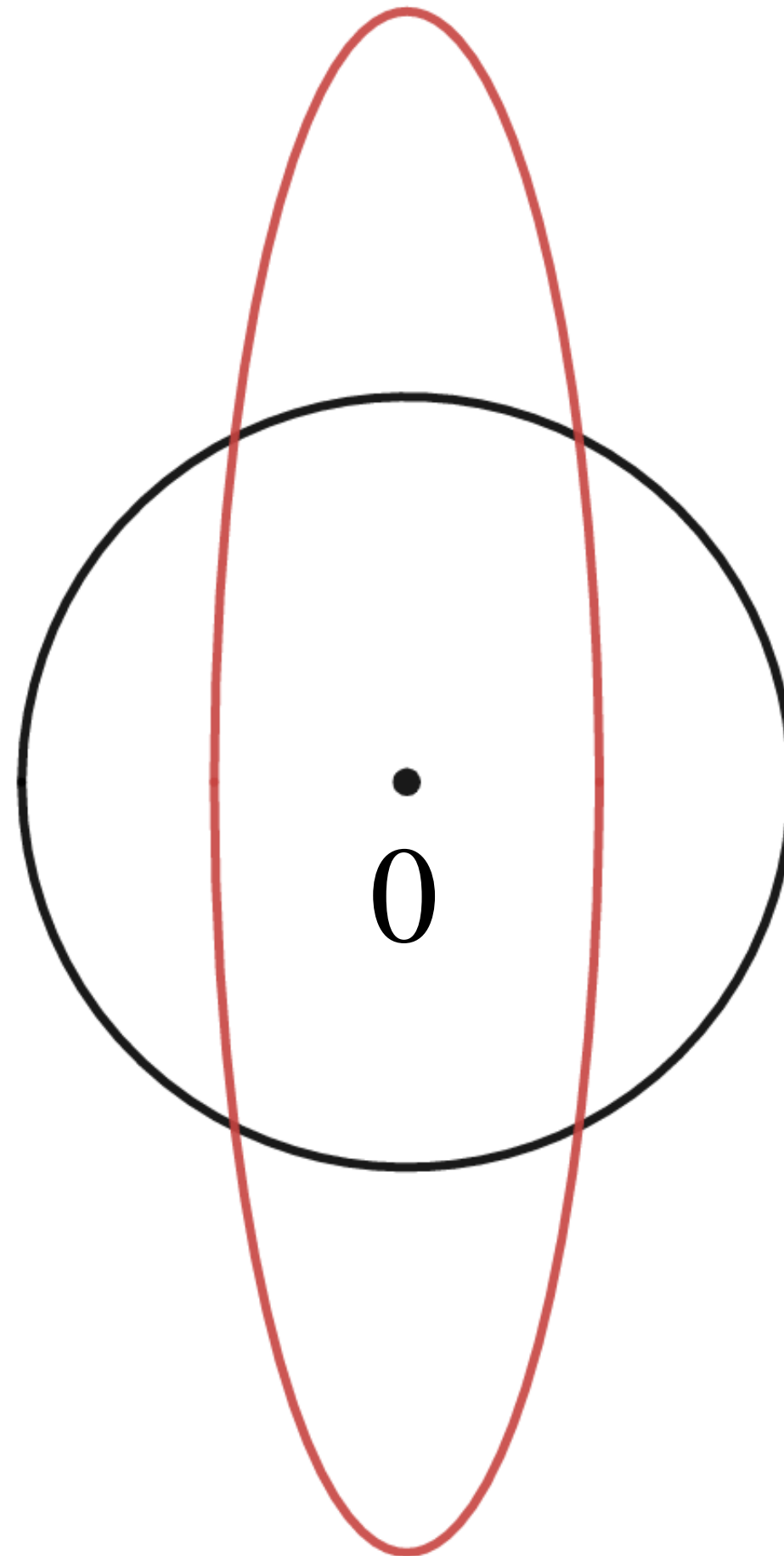


$$(2x)^2 + (y/2)^2 \leq 1$$

# Ellipsoid method

*Ellipsoid*: a squished ball

$$x^2 + y^2 \leq 1$$

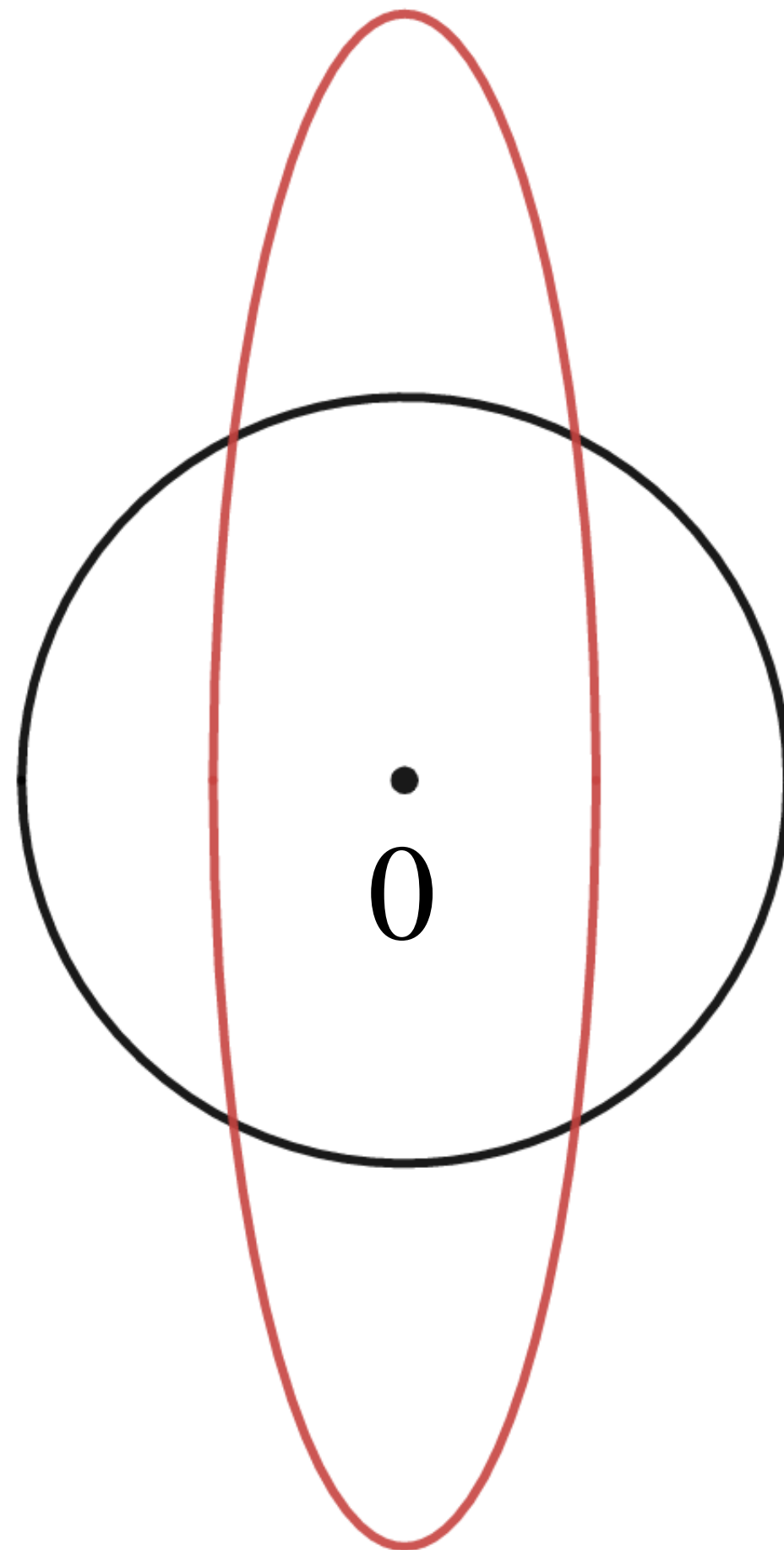


$$(2x)^2 + (y/2)^2 \leq 1$$

# Ellipsoid method

*Ellipsoid*: a squished ball

$$x^2 + y^2 \leq 1$$



$$(2x)^2 + (y/2)^2 \leq 1$$

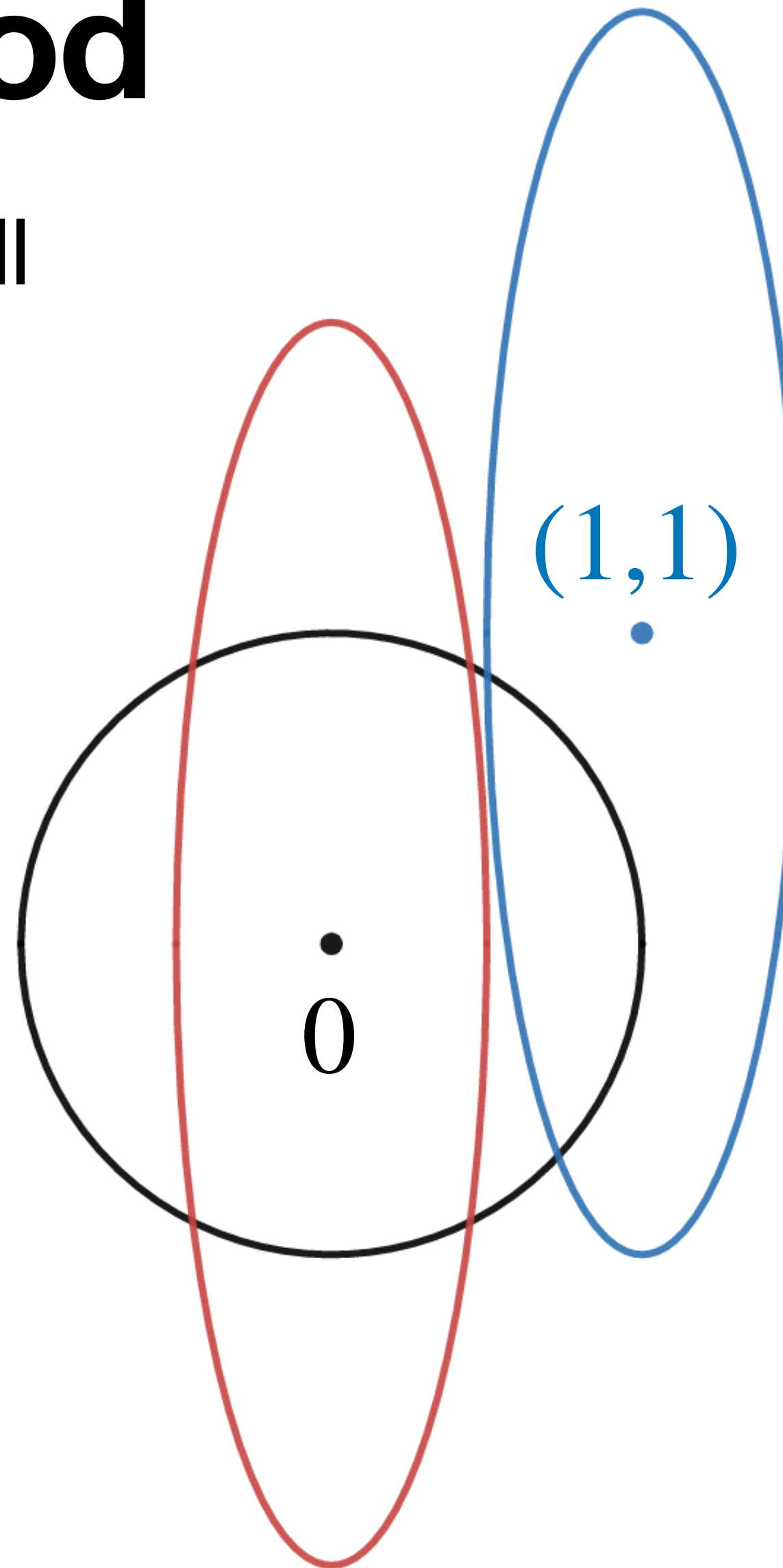
Ratio of area of ellipsoid to sphere:

$$\frac{1}{2} \cdot \frac{2}{1} = 1$$

# Ellipsoid method

*Ellipsoid*: a squished ball

$$x^2 + y^2 \leq 1$$



(1,1)

$$(2(x-1))^2 + ((y-1)/2)^2 \leq 1$$

Ratio of area of ellipsoid to sphere:

$$\frac{1}{2} \cdot \frac{2}{1} = 1$$

$$(2x)^2 + (y/2)^2 \leq 1$$

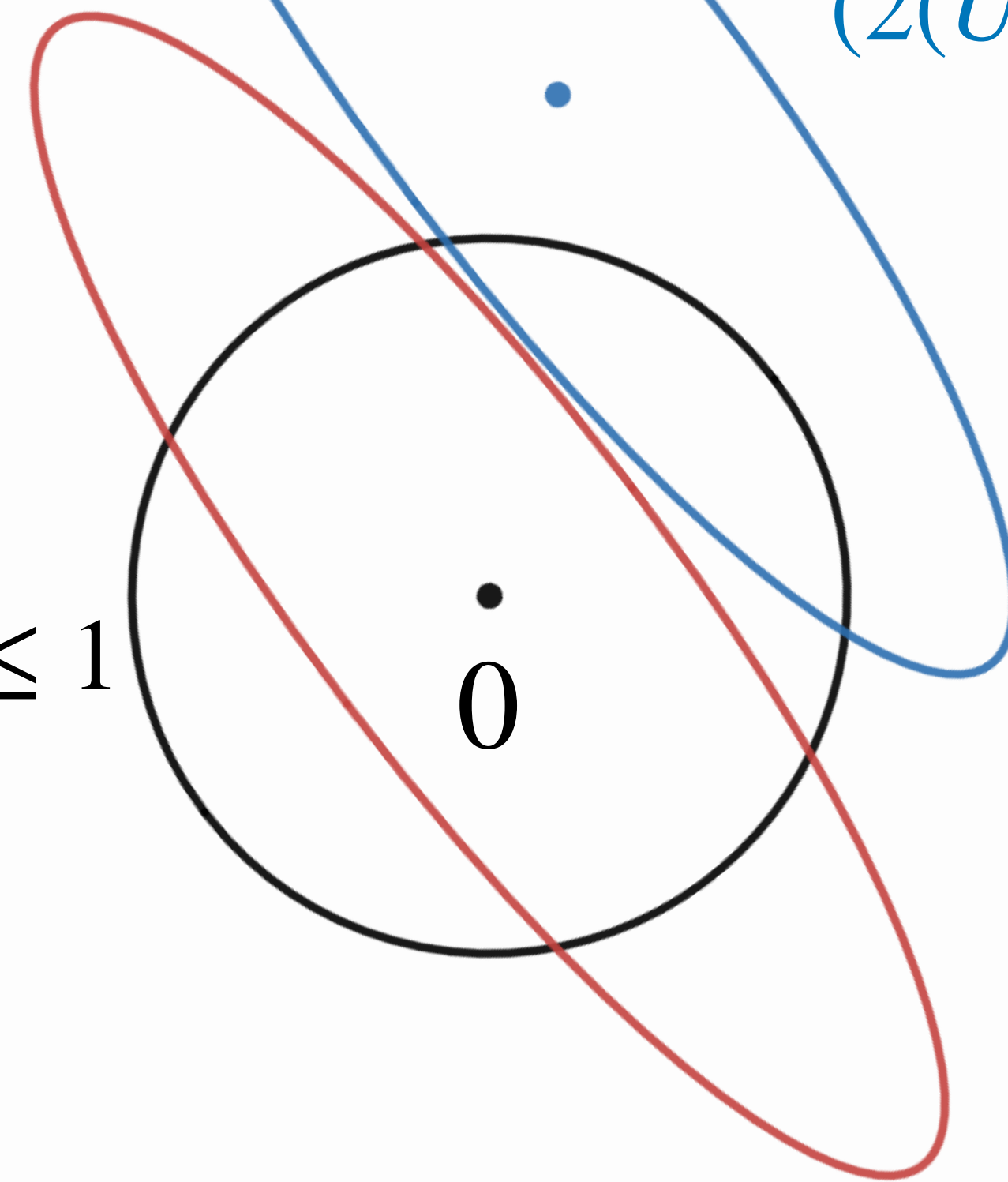
# Ellipsoid method

*Ellipsoid*: a squished ball

Let  $U^{-1}$  be the linear transformation corresponding to a rotation.

$$(2(U_1(x, y) - 1))^2 + ((U_2(x, y) - 1)/2)^2 \leq 1$$

$$(U_1(x, y))^2 + (U_2(x, y))^2 \leq 1$$



Ratio of area of ellipsoid to sphere:

$$\frac{1}{2} \cdot \frac{2}{1} = 1$$

$$(2U_1(x, y))^2 + (U_2(x, y)/2)^2 \leq 1$$



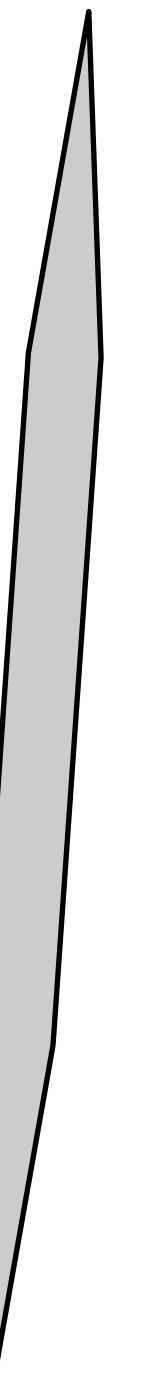
# The desired solution is bounded

**Fact:** If the solution is finite, then its magnitude is at most  $2^{O(\text{poly}(\text{input length}))}$ .

**Pf:** If finite, the solution occurs at a vertex. Since every vertex satisfies  $Bx = d$ , for some  $B, d$ , we have  $x = B^{-1}d$ , and the size of coefficients of  $B^{-1}$  are polynomially related to the size of coefficients of  $A$ .

**Fact:** If there is finite solution, then volume of feasible region (i.e. polytope) is at least  $2^{-O(\text{poly}(\text{input length}))}$ .

**Pf sketch:** The smallest angle that can be generated is  $2^{-O(\text{poly}(\text{input length}))}$ .



# Ellipsoid method

**maximize**  $c^T x$   
subject to  
 $Ax \leq b$   
 $x \geq 0$



**Is there**  $x$   
with  
 $c^T x \geq d$   
 $Ax \leq b$   
 $x \geq 0$

**Claim:** If we can find  $x$  inside polytope in poly time, we can use binary search to find the best value of  $d$  in poly time!

**Fact:** If the solution is finite, then its magnitude is at most  $2^{O(\text{poly}(\text{input length}))}$ .

**Fact:** If there is finite solution, then volume of feasible region (i.e. polytope) is at least  $2^{-O(\text{poly}(\text{input length}))}$ .

**Consequence:** We know  $-T \leq c^T x \leq T$ , where  $T \leq 2^{O(\text{poly}(\text{input length}))}$ .

# Using binary search

$$y = T$$

---



$$y = -T$$

---

# Check polytope is non-empty

$$y = T$$

---



$$y = -T$$

---

# Add new constraint

$$y = T$$

$$y \leq 0$$

$$y = -T$$



# Find point

$$y = T$$

$$y \leq 0$$

$$y = -T$$



# Add new constraint

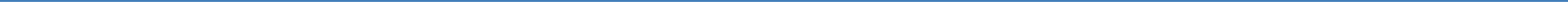
$$y \leq 0$$

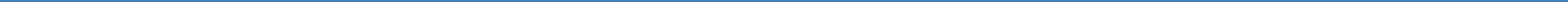
$$y \leq -T/2$$

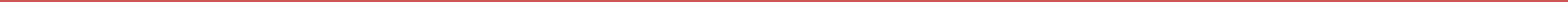
$$y = -T$$



Find point: polytope is empty!

$$y \leq 0$$


$$y \leq -T/2$$


$$y = -T$$




# Add new constraint

$$y \leq 0$$

$$y \leq -T/4$$

$$y \leq -T/2$$



# Add new constraint

$$y \leq 0$$

$$y \leq -T/4$$

$$y \leq -T/2$$



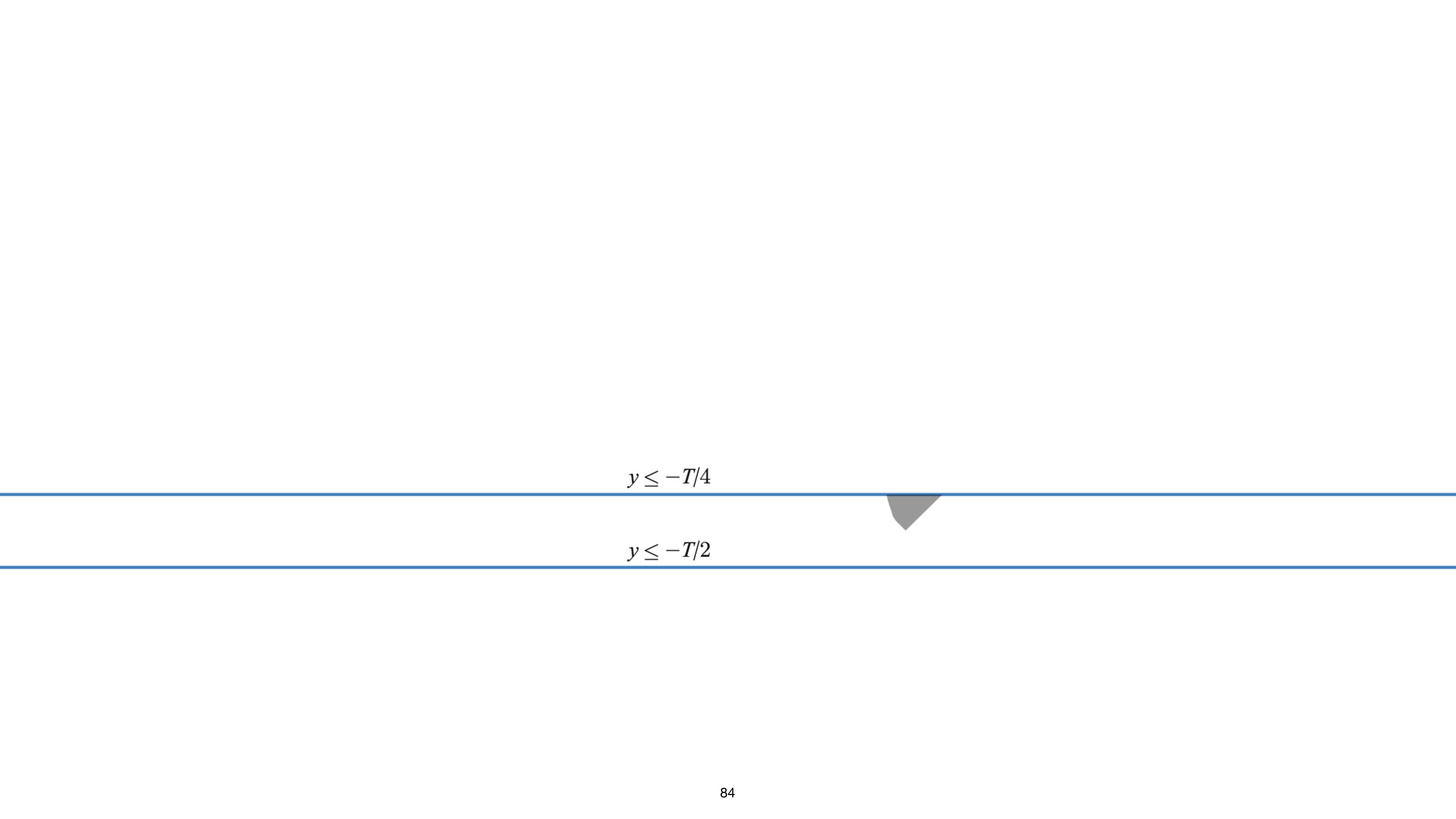
# Find point

$$y \leq 0$$

$$y \leq -T/4$$

$$y \leq -T/2$$





The diagram consists of two horizontal blue lines. Between these lines, on the right side, is a gray triangle pointing downwards. The top line is labeled with the equation  $y \leq -T/4$  and the bottom line is labeled with the equation  $y \leq -T/2$ .

$$y \leq -T/4$$

$$y \leq -T/2$$

# Add new constraint

$$y \leq -T/4$$

$$y \leq -3T/8$$

$$y \leq -T/2$$



Find point: polytope is empty!

$$y \leq -T/4$$

$$y \leq -3T/8$$

$$y \leq -T/2$$

$$y \leq -T/4$$

$$y \leq -3T/8$$



# Find point

$$y \leq -T/4$$

$$y \leq -3T/8$$

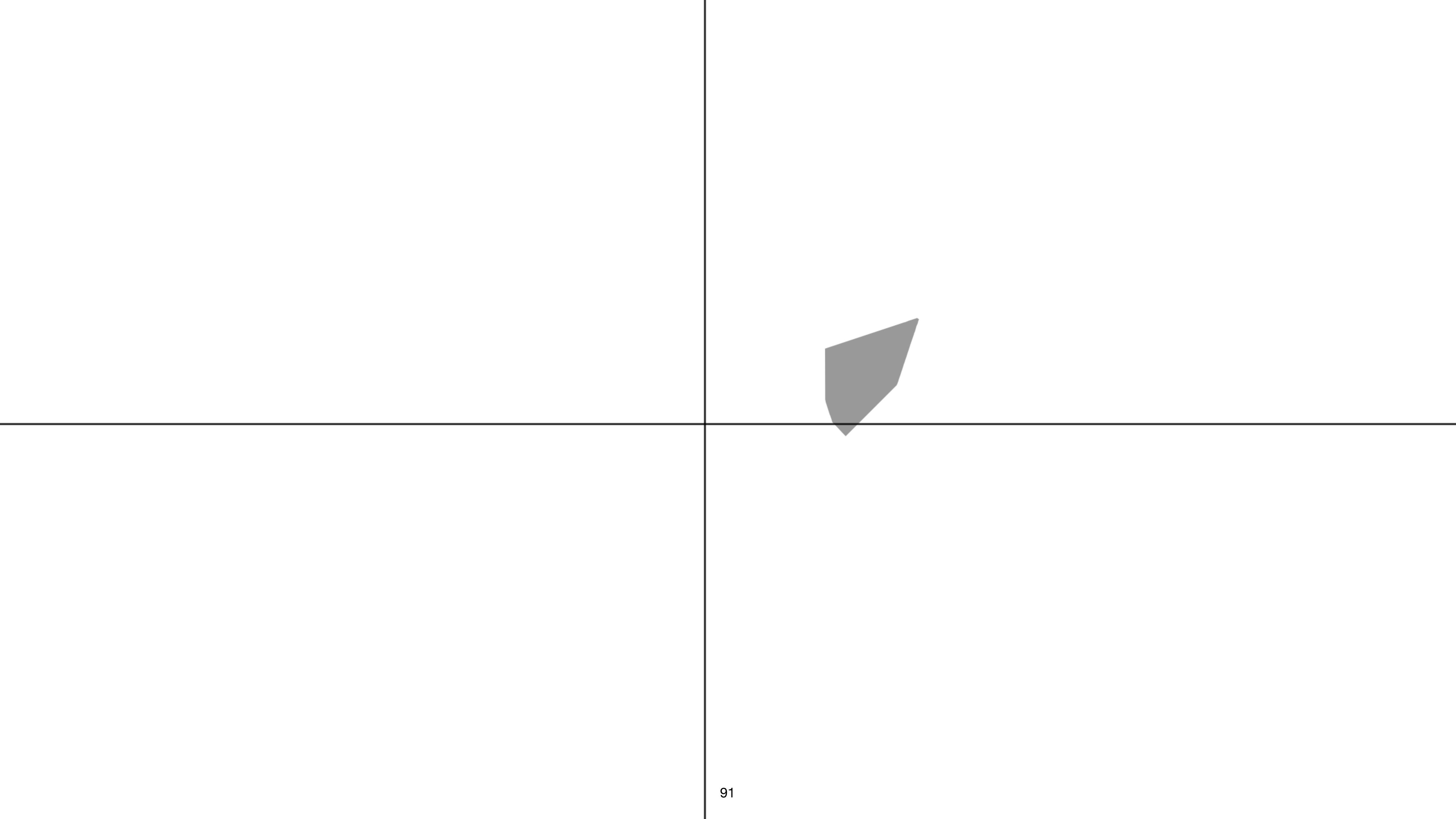




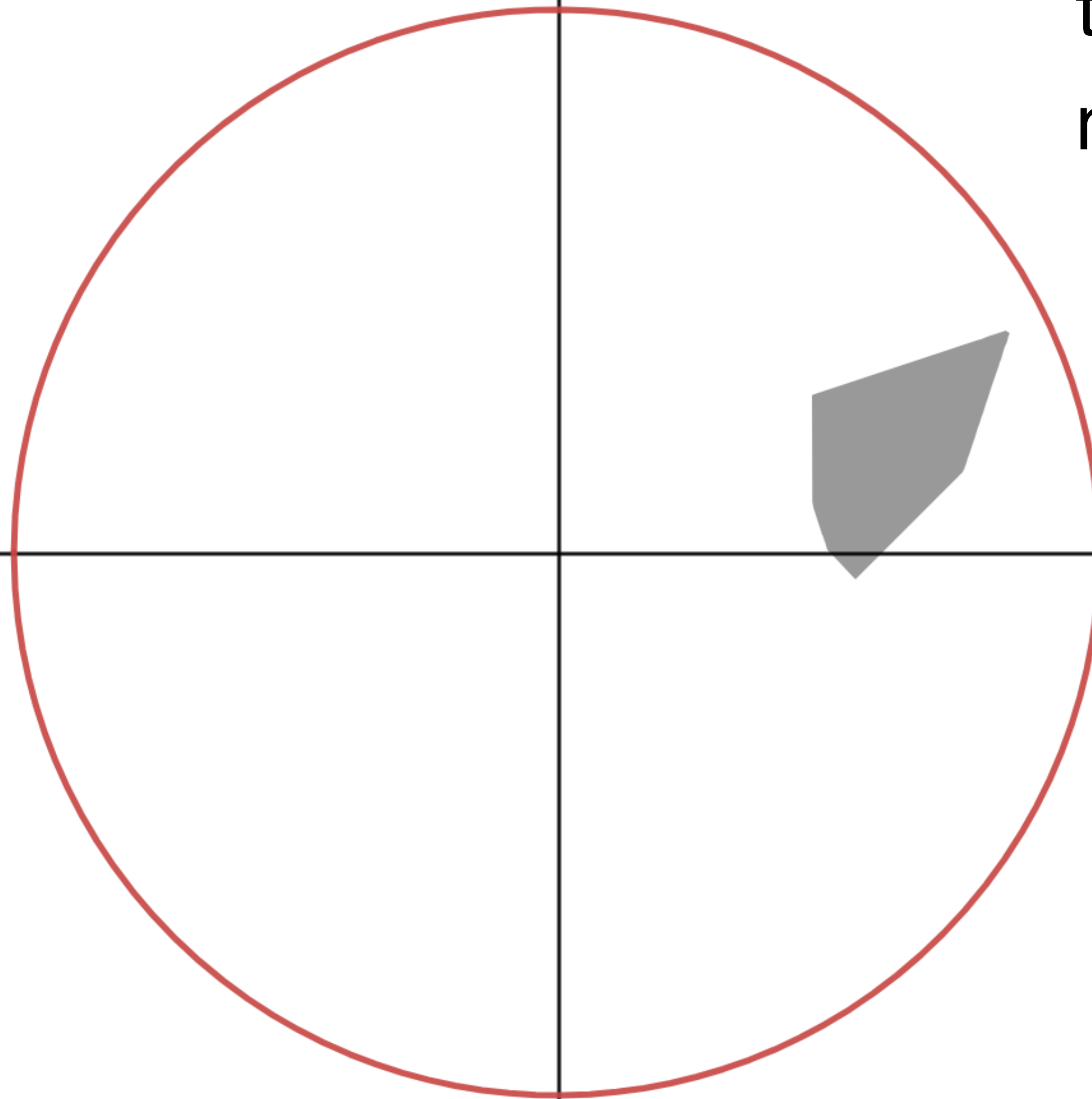
***Conclusion:*** It is enough to give an algorithm to find a point in a polytope.

# Ellipsoid algorithm for finding points in polytopes

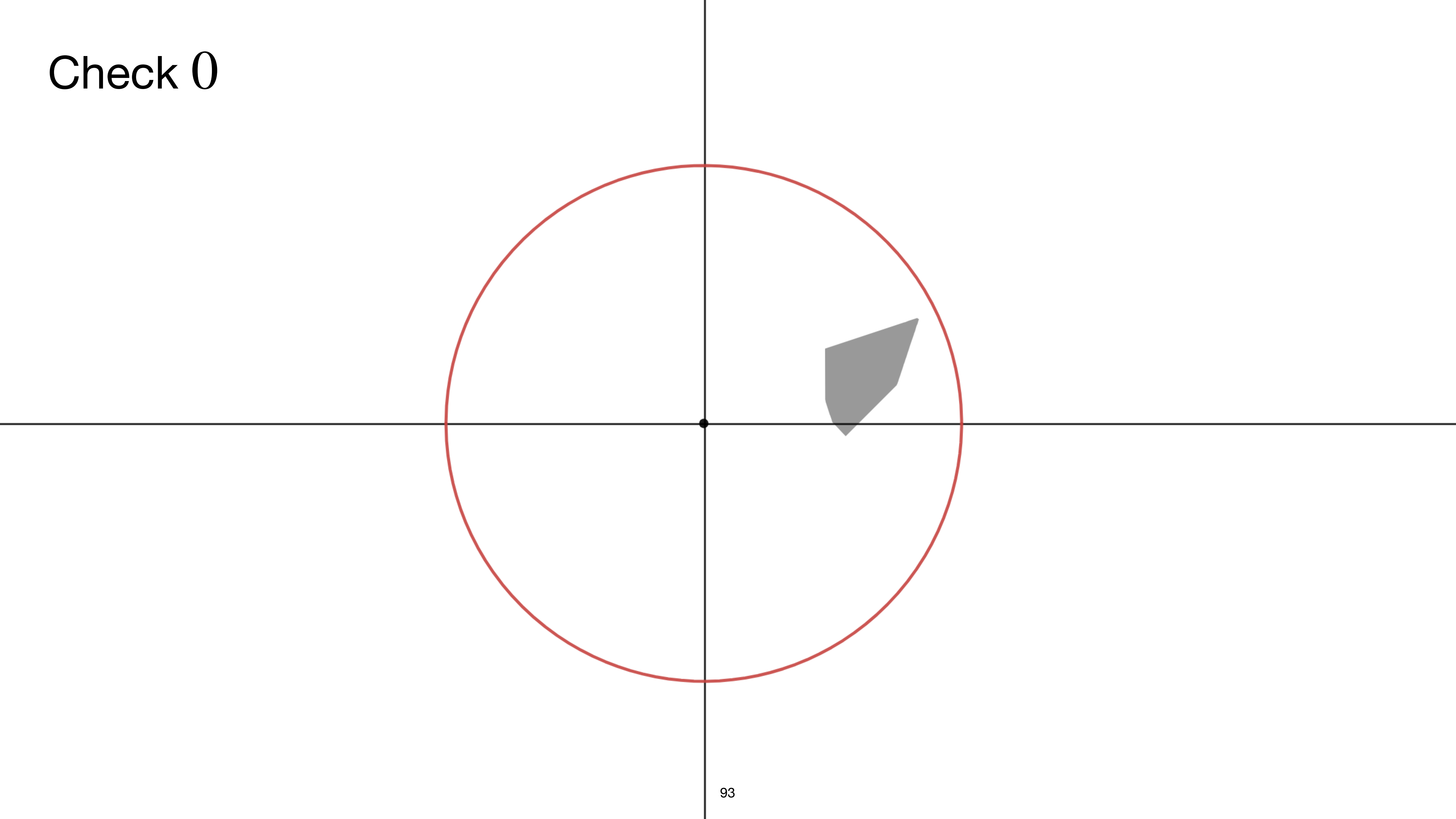
**Idea:** Iteratively find ellipsoids where the density of the polytope is larger and larger, until a point is found



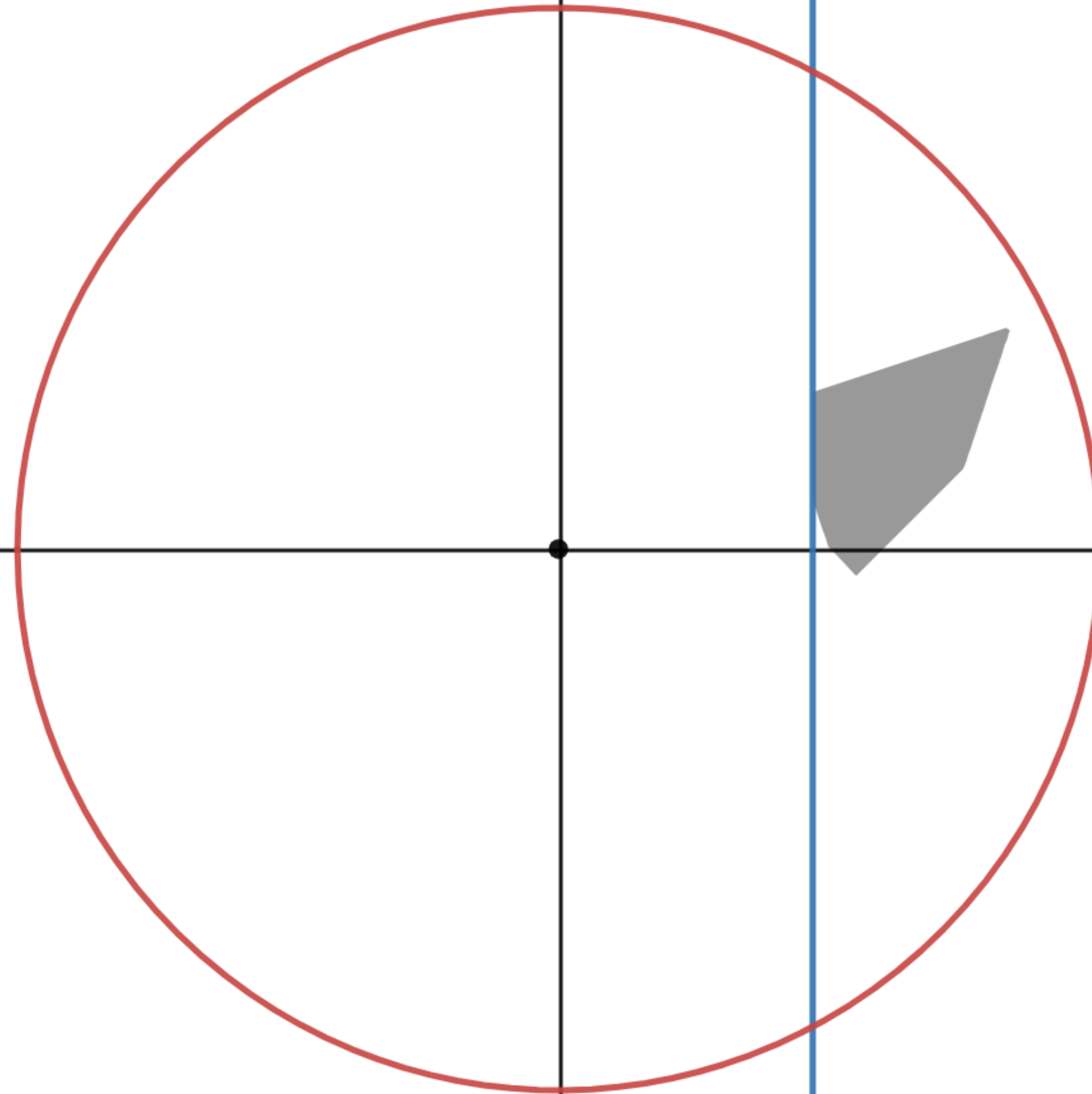
**Fact:** If the solution is finite,  
then its magnitude is at  
most  $2^{O(\text{poly}(\text{input length}))}$ .



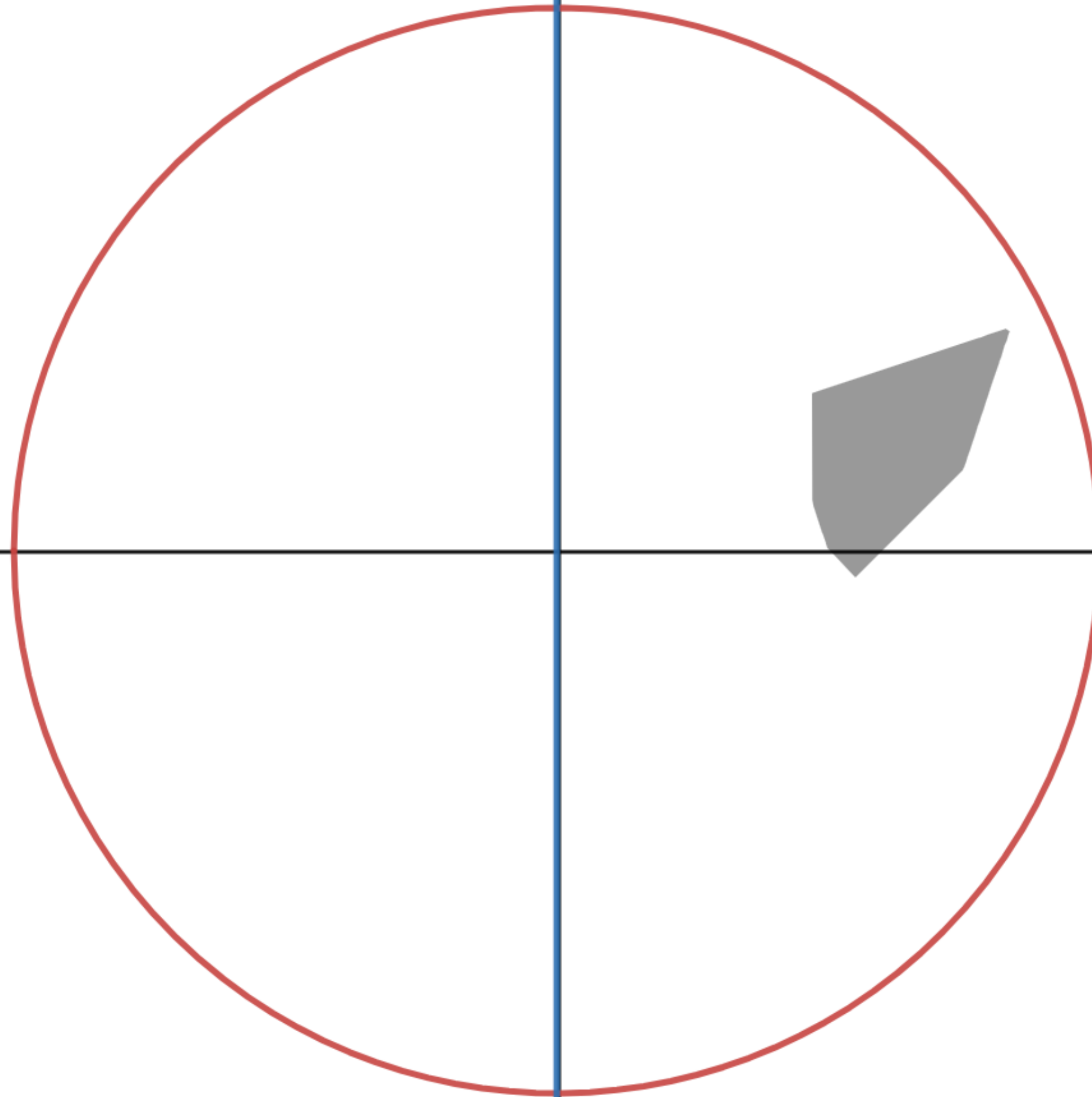
Check 0



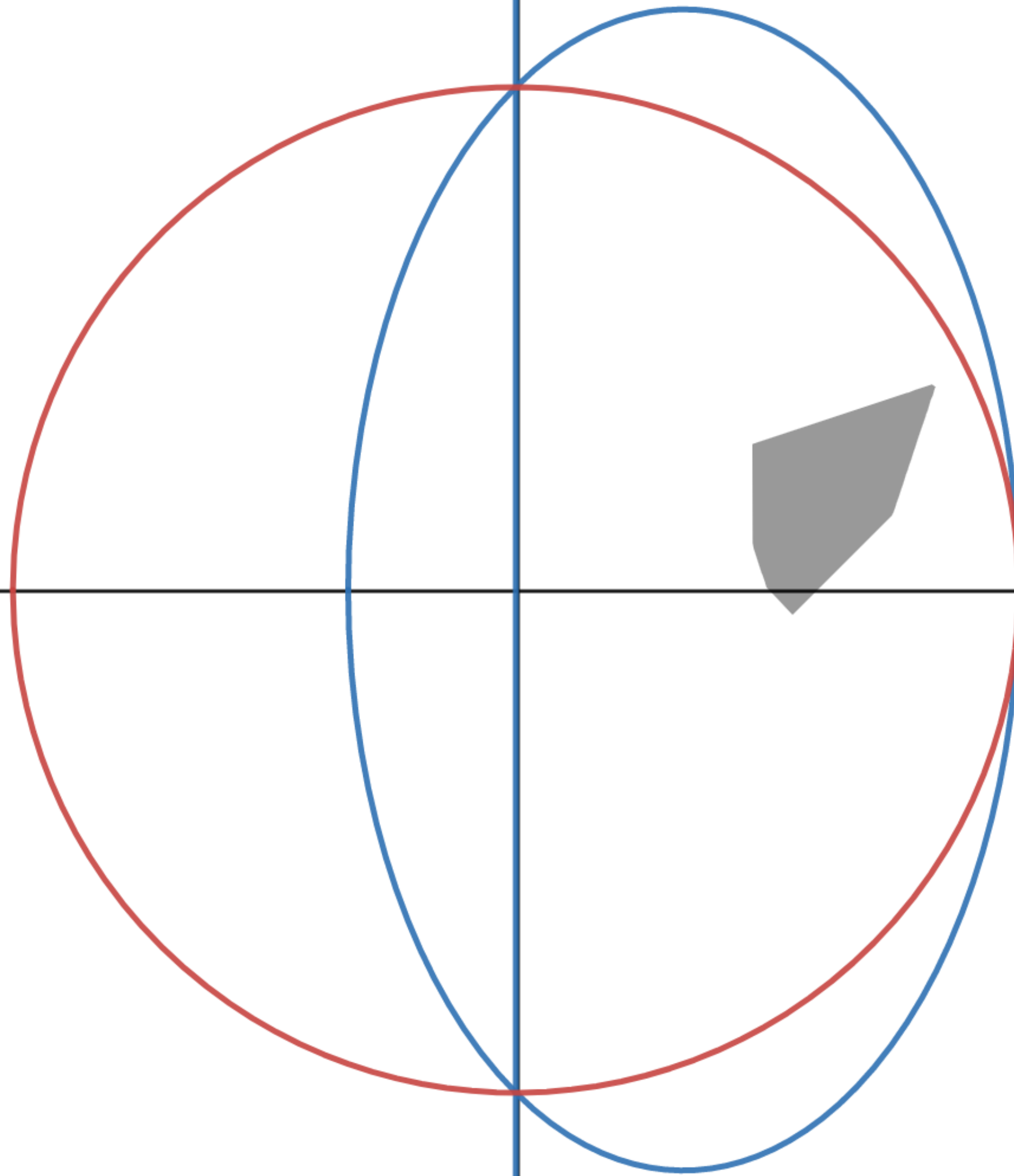
Find violated inequality



Shift inequality to origin

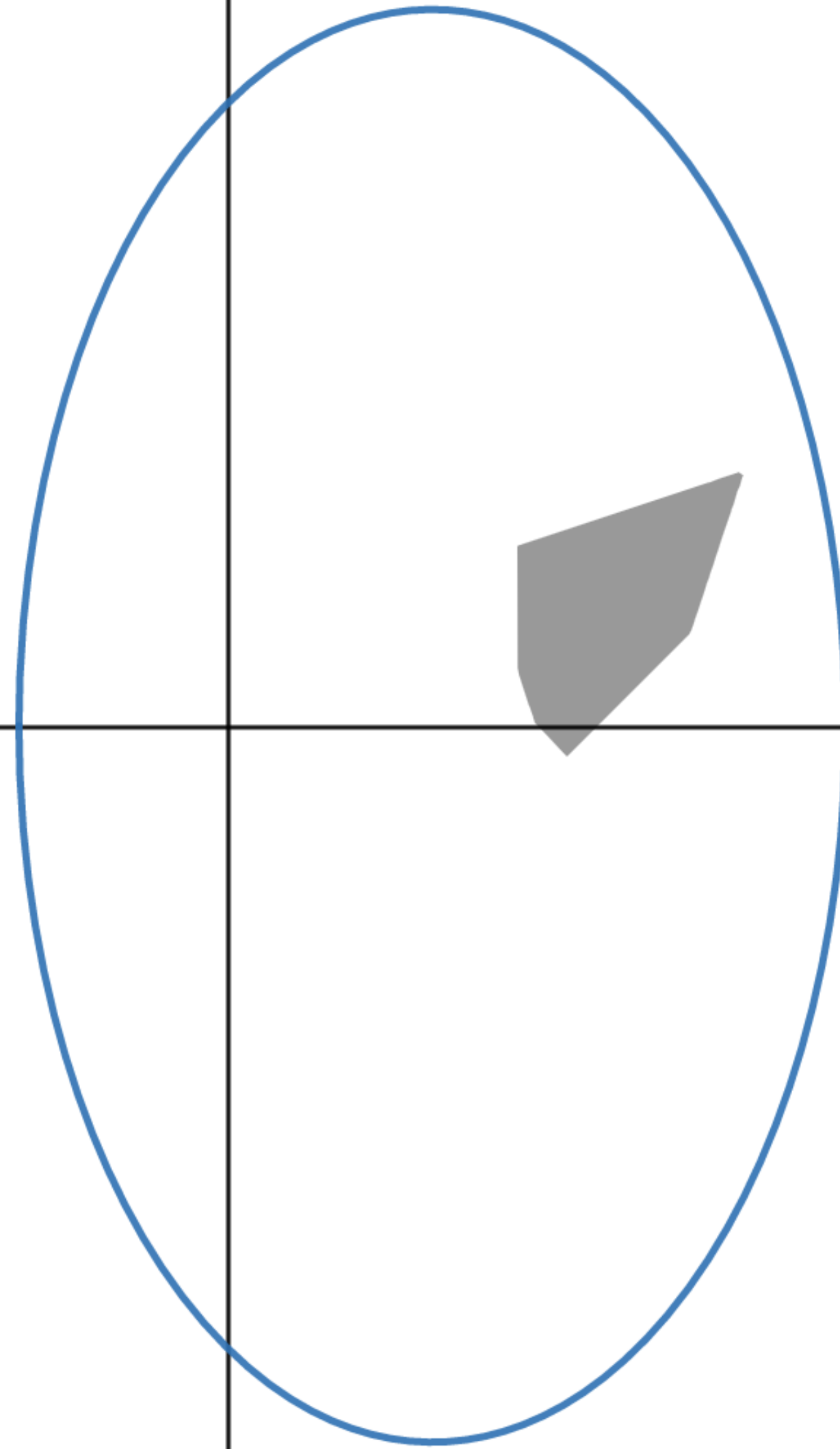


Find ellipsoid containing  
half-sphere

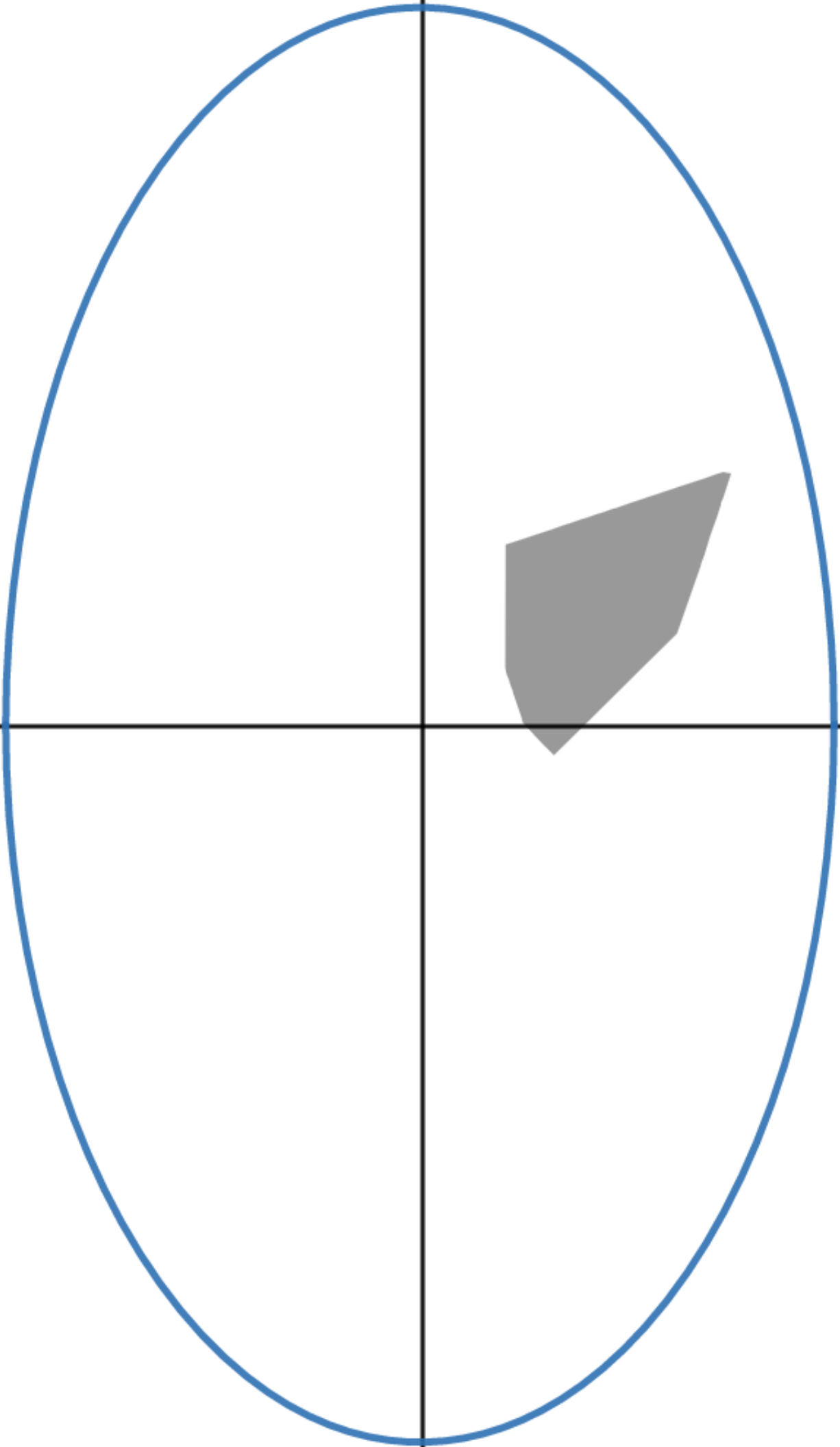




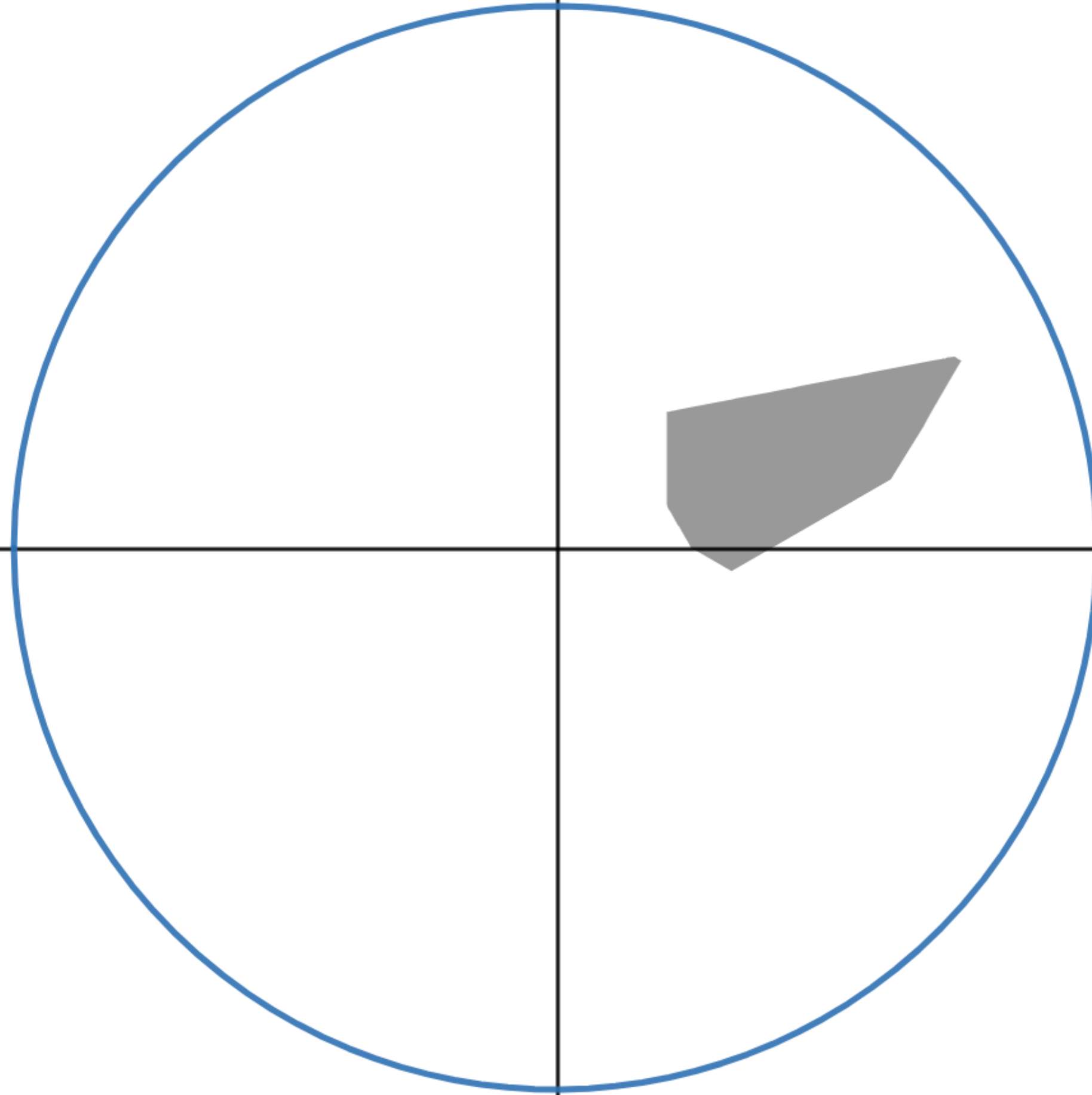
Find ellipsoid containing  
half-sphere



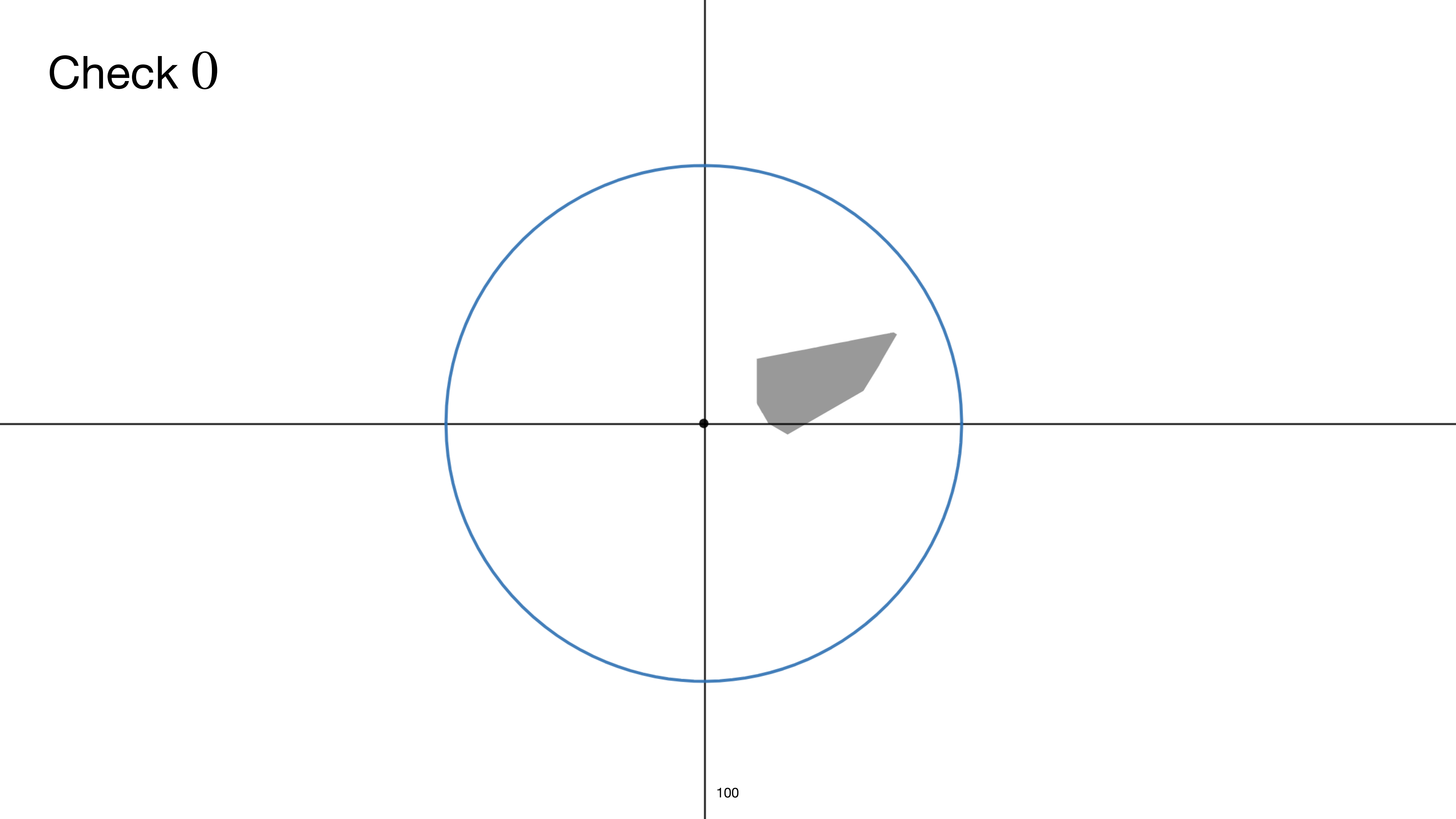
Shift to center



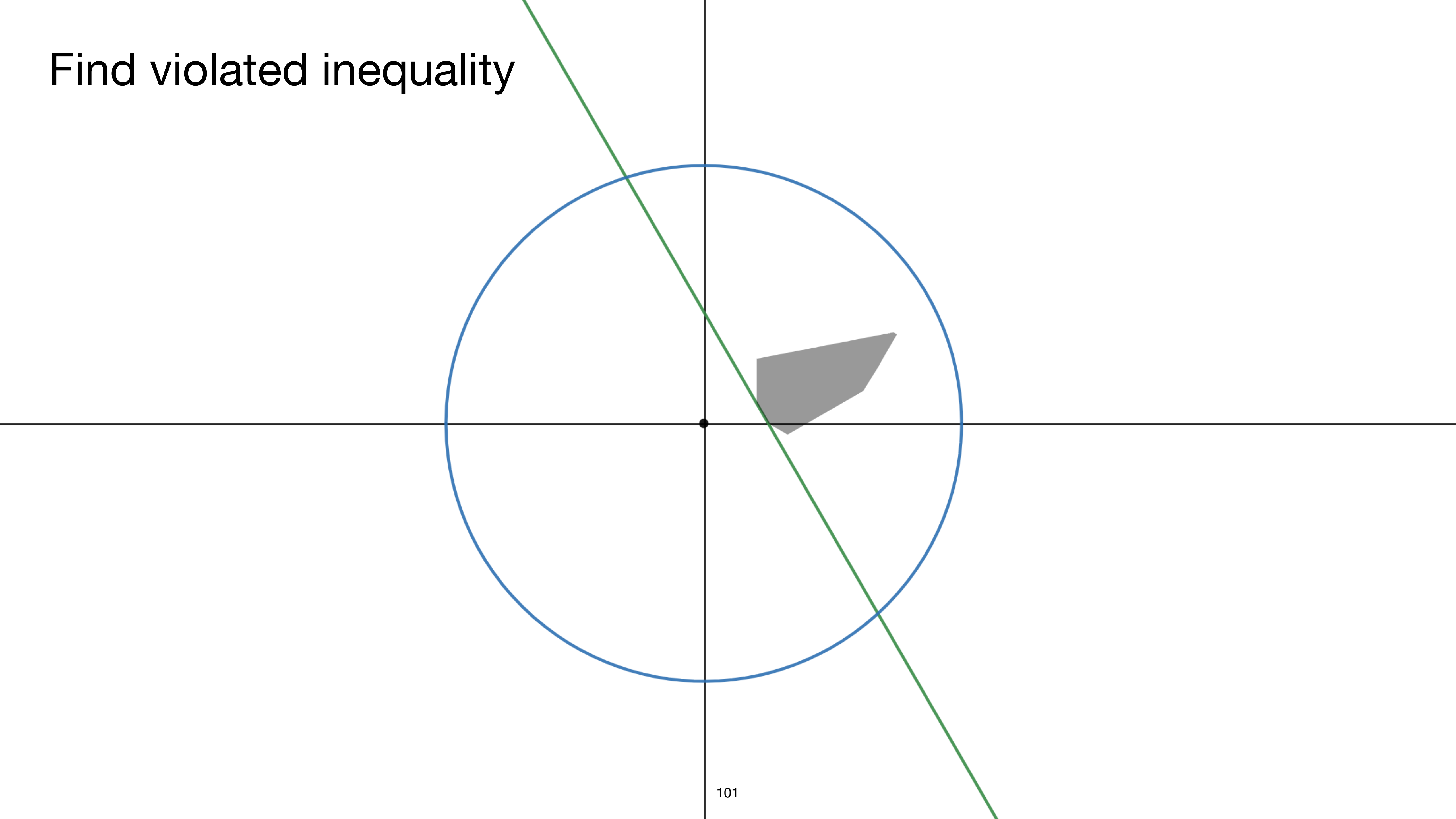
Stretch to get sphere



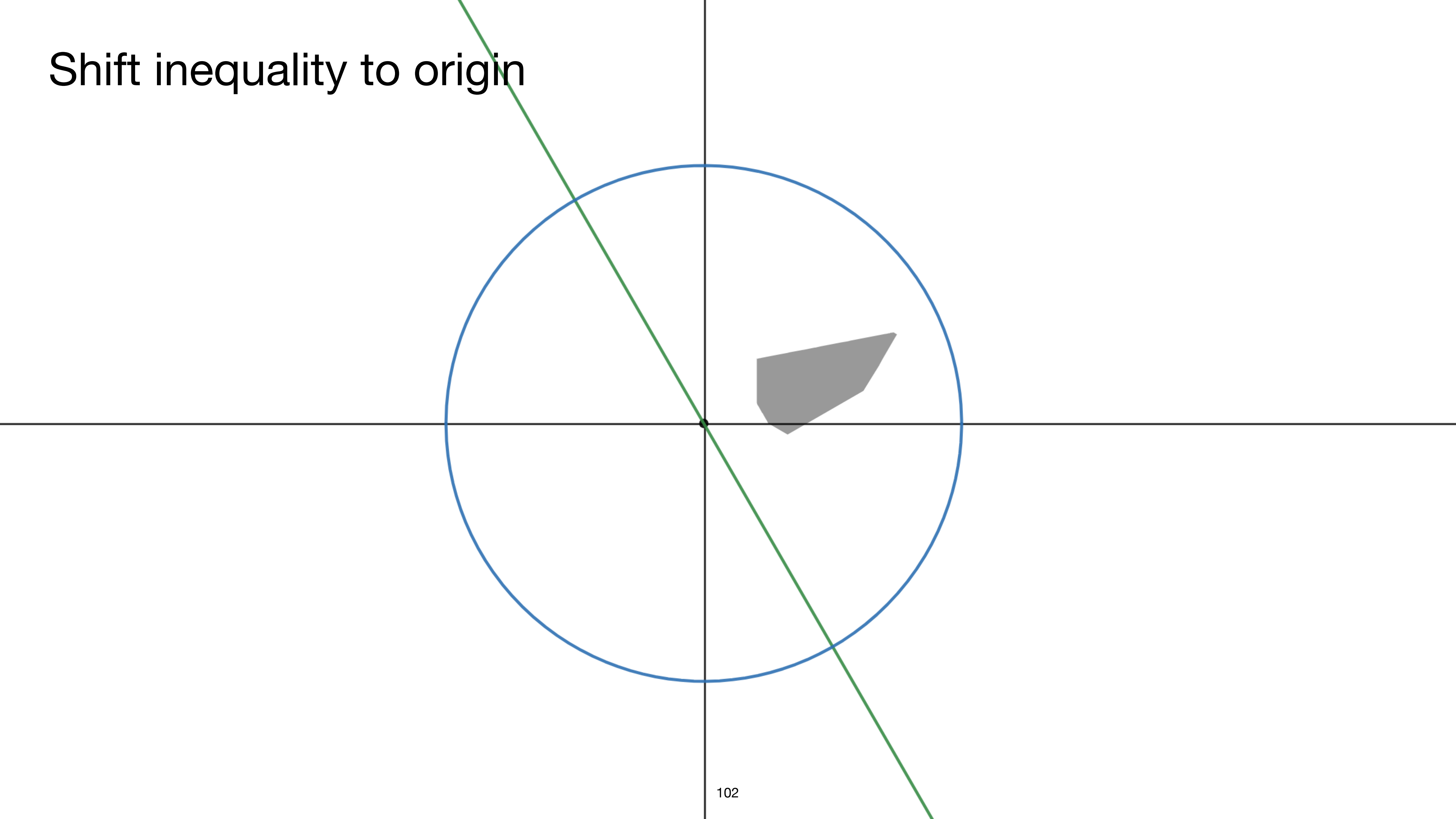
Check 0



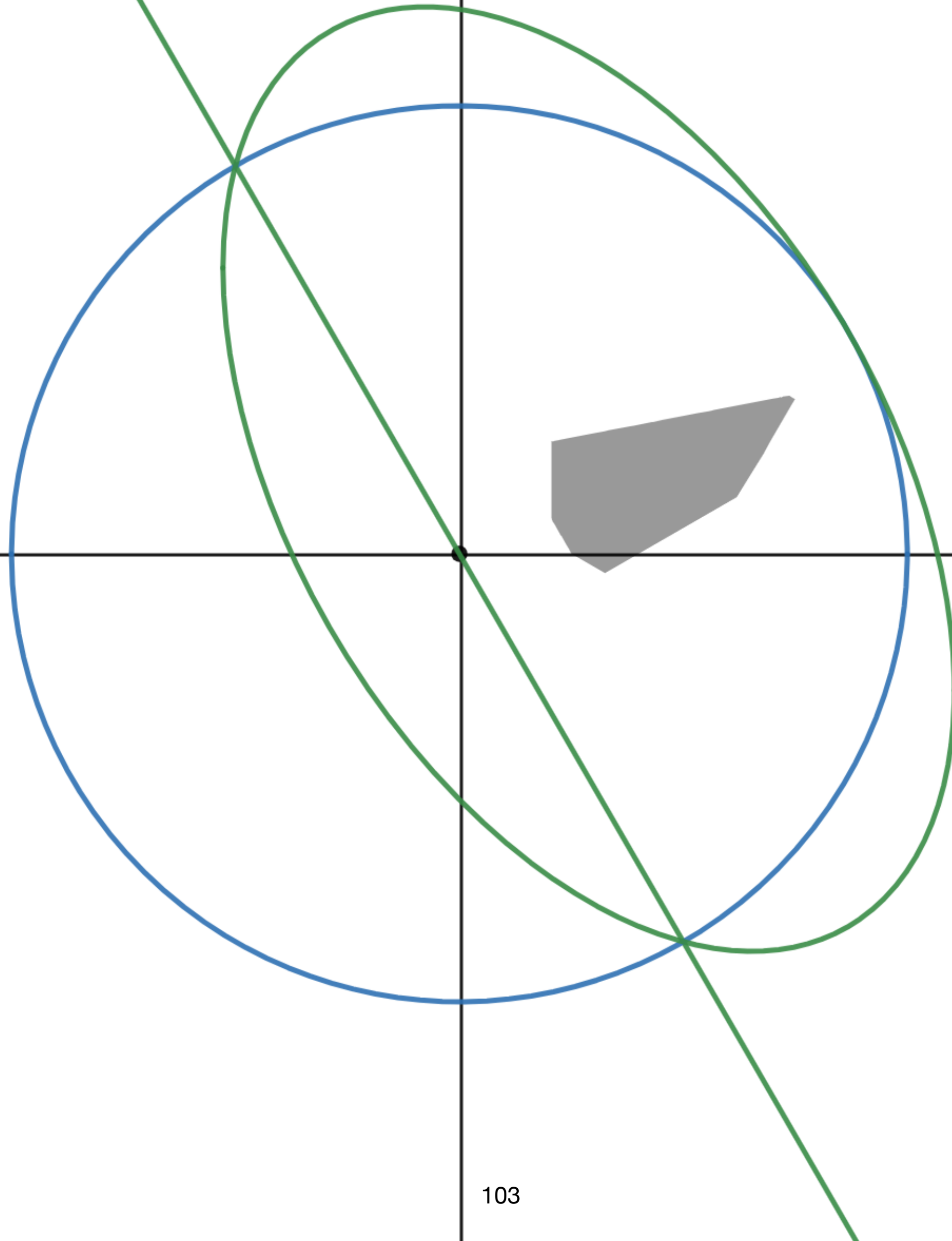
Find violated inequality



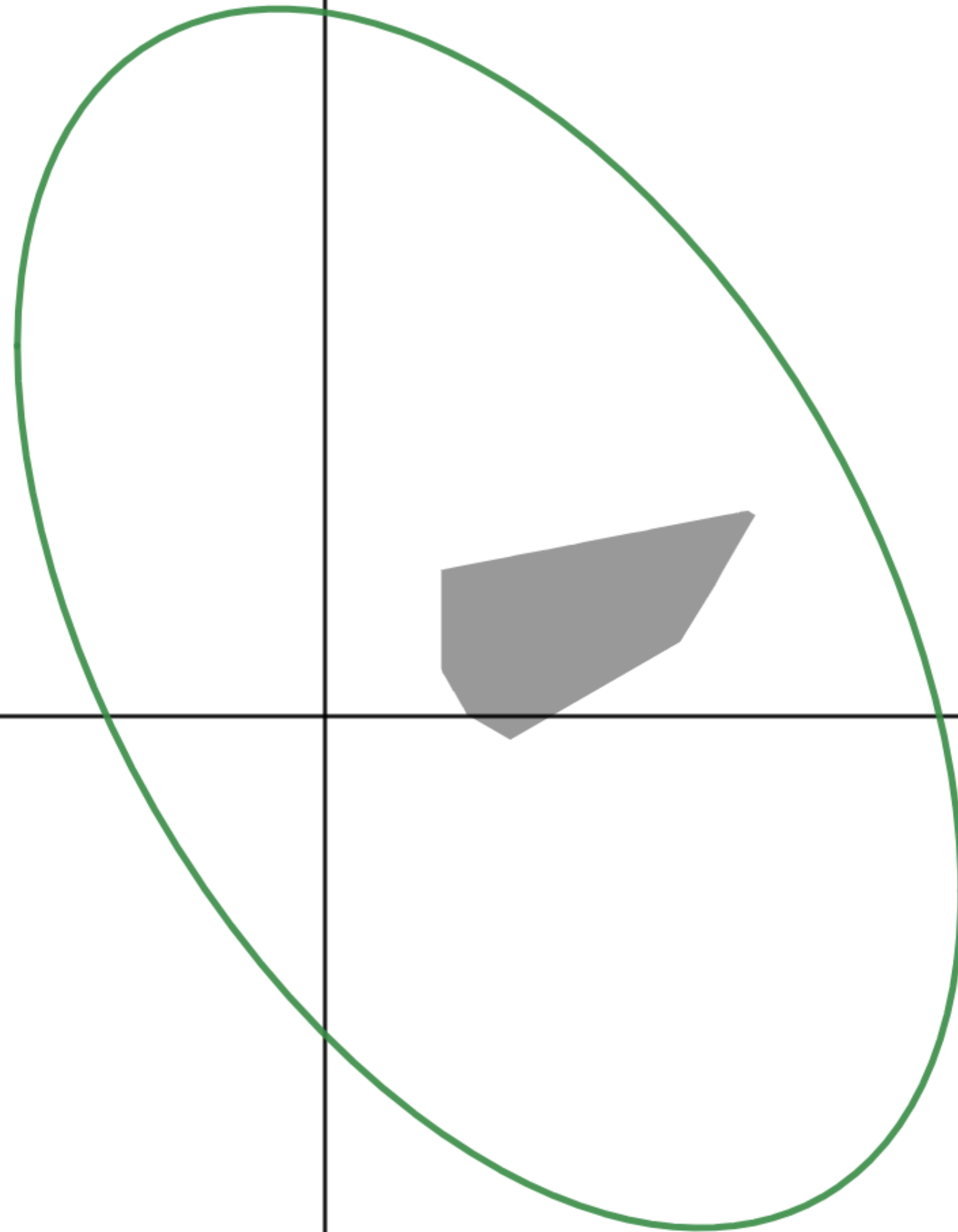
Shift inequality to origin



Find ellipsoid containing  
half-sphere

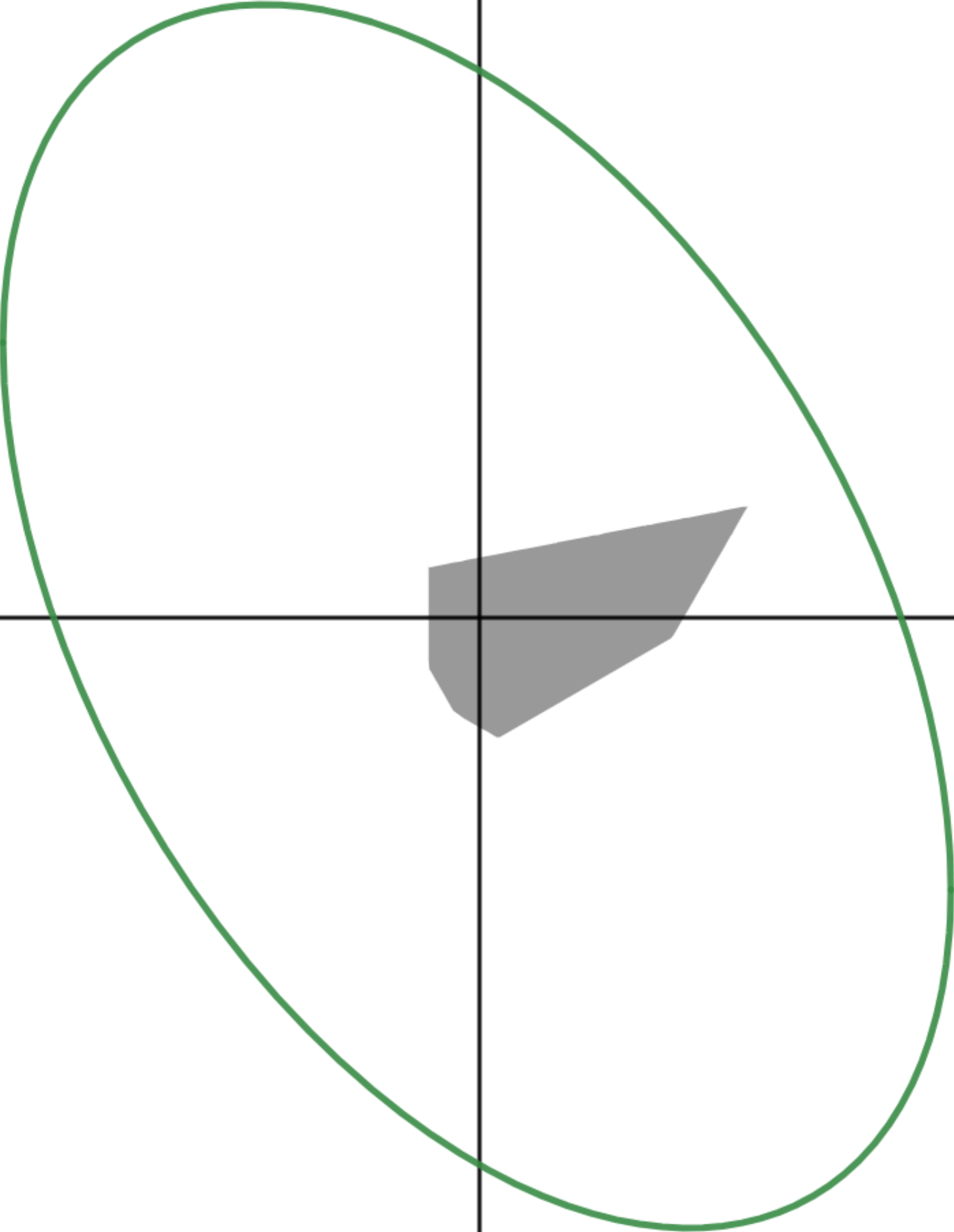


Find ellipsoid containing  
half-sphere

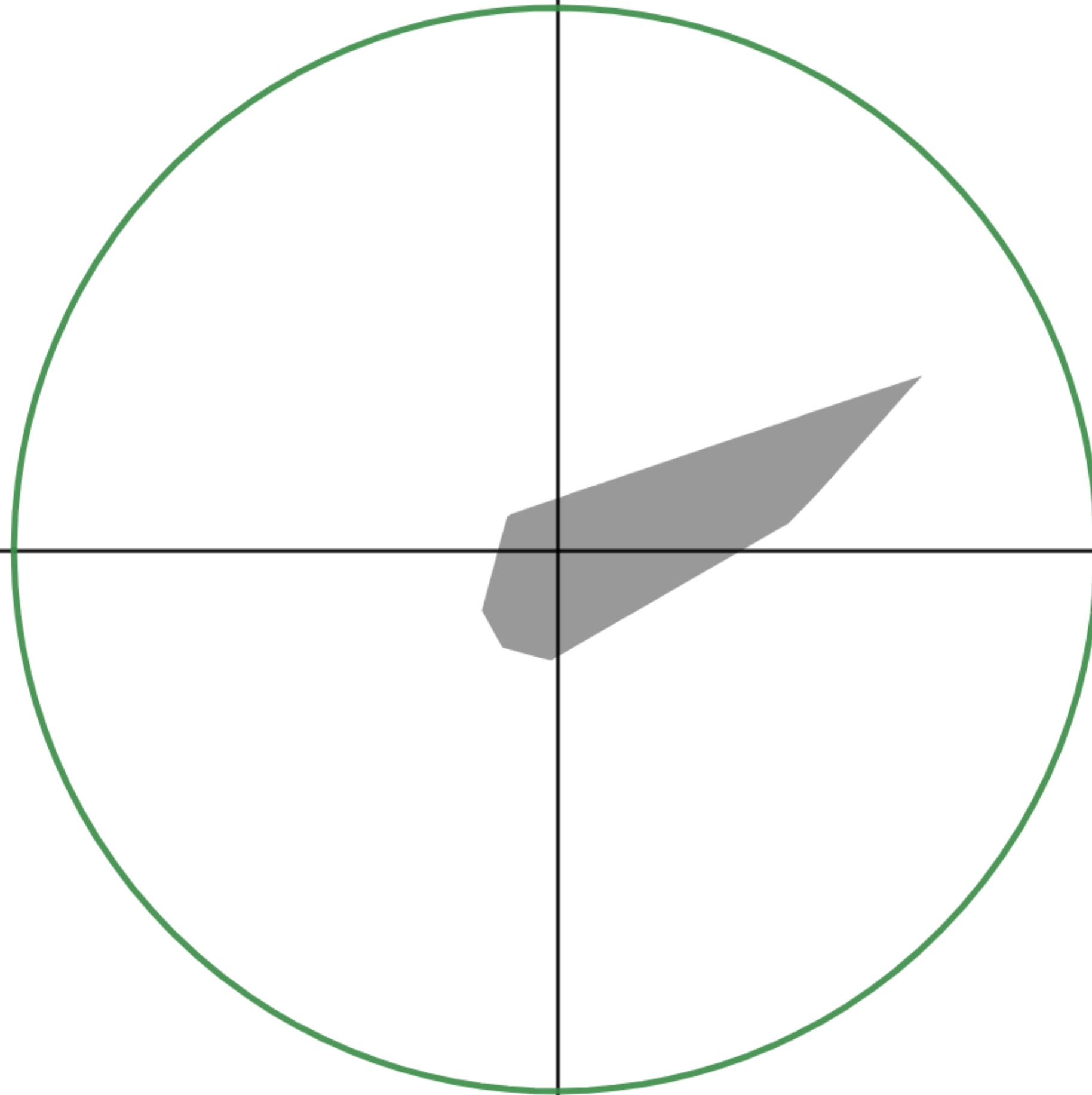




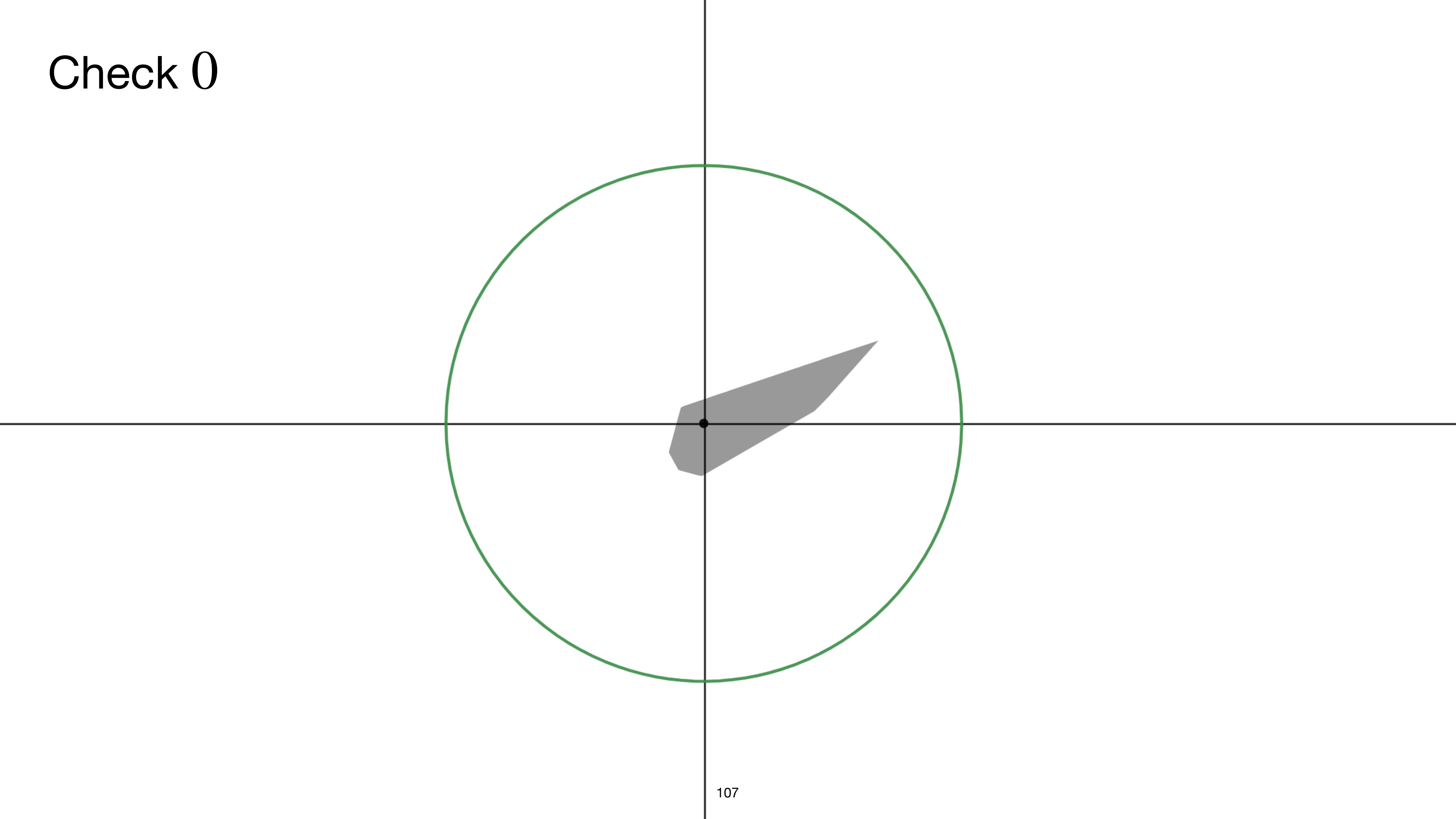
Shift to center



Stretch to get sphere



Check 0



# Ellipsoid method

Is there  $x$   
with  
 $c^T x \geq d$   
 $Ax \leq b$   
 $x \geq 0$

**Algorithm to find element of non-empty  $P$ :**

1. Let  $E$  be circle of radius  $R$  containing polytope  $P$ .
2. If  $0 \in P$ , output 0.
3. Otherwise half-circle containing  $P$ , and ellipsoid  $E'$  containing half-circle.
4. Scale and shift  $E'$  to get  $E$ , and find element of  $P$  using new  $E$ .

**Key Lemma:**  $\text{vol}(E')/\text{vol}(E) \leq e^{\frac{-1}{2(n+1)}}$

**Corollary:**  $\text{vol}(P)/\text{vol}(E') \geq e^{\frac{1}{2(n+1)}} \cdot \text{vol}(P)/\text{vol}(E)$

**Corollary:** After  $t$  rounds,  
 $\text{vol}(P)/\text{vol}(E') \geq e^{\frac{t}{2(n+1)}} \cdot \text{vol}(P)/\text{vol}(E)$

**Corollary:** The algorithm must terminate in  $\text{poly}(\text{input length})$  steps.

$$E: \sum_i x_i^2 \leq 1$$

$E'$ : ellipsoid containing right half-ball

$$\left(\frac{n+1}{n}\right)^2 \left(x_1 - \frac{1}{n+1}\right)^2 + \frac{n^2-1}{n^2} \cdot \sum_{i>2} x_i^2 \leq 1$$

**Claim:**  $E'$  contains right half-ball.

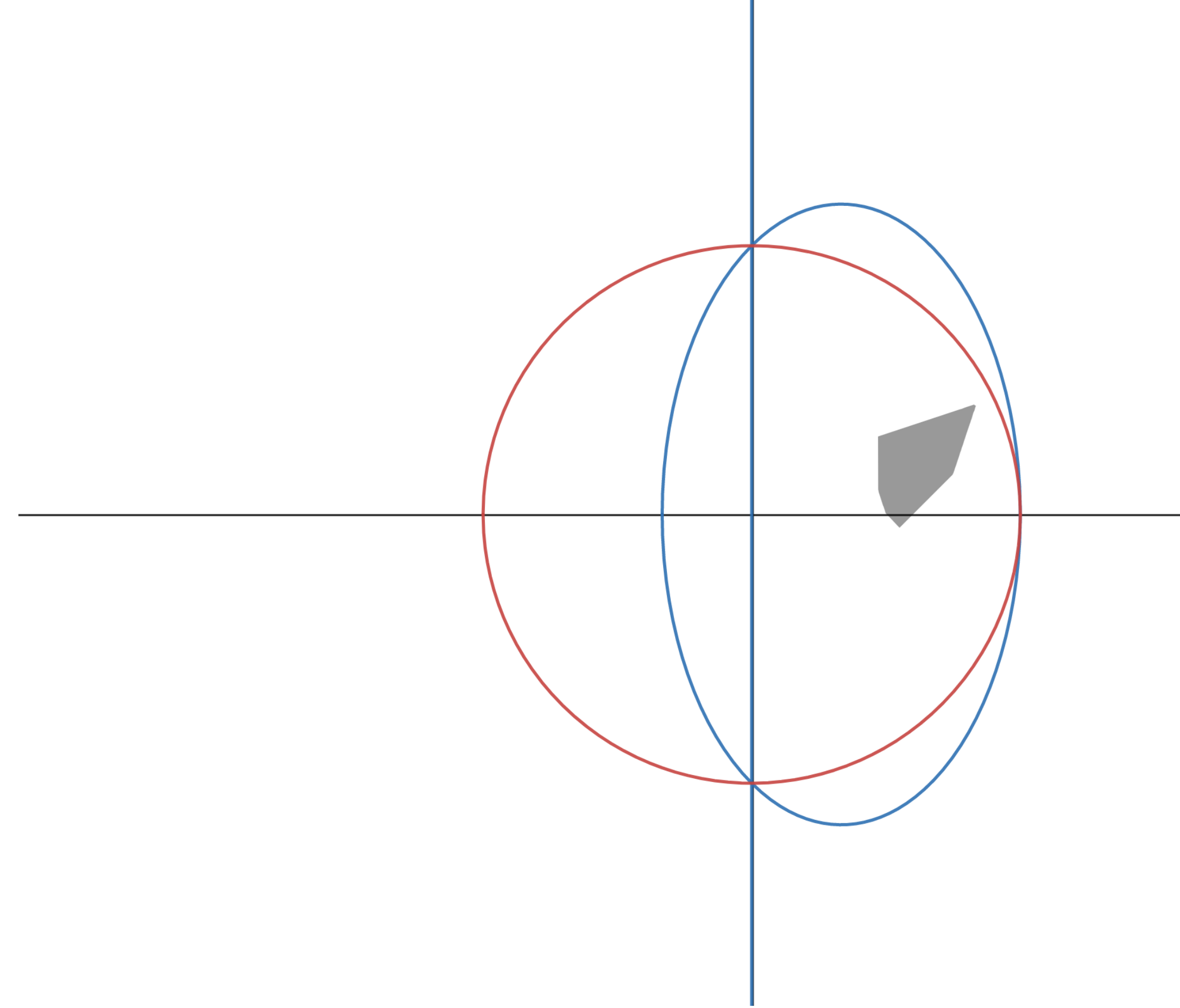
If  $x \in E$ ,  $x_1 \geq 0$ , then

$$\begin{aligned} & \left(\frac{n+1}{n}\right)^2 \left(x_1 - \frac{1}{n+1}\right)^2 + \frac{n^2-1}{n^2} \cdot \sum_{i>2} x_i^2 \\ &= \left(\frac{(n+1)x_1 - 1}{n}\right)^2 + \frac{n^2-1}{n^2} \cdot \sum_{i>2} x_i^2 \end{aligned}$$

$$= \frac{(n^2 + 2n + 1)x_1^2 - 2(n+1)x_1 + 1}{n^2} + \frac{n^2-1}{n^2} \cdot \sum_{i>2} x_i^2$$

$$= \frac{(2n+2)x_1^2 - (2n+2)x_1}{n^2} + \frac{1}{n^2} + \frac{n^2-1}{n^2} \cdot \sum_i x_i^2 = \frac{(2n+2)x_1(x_1-1)}{n^2} + \frac{1}{n^2} + \frac{n^2-1}{n^2} \cdot \sum_i x_i^2 \leq \frac{1}{n^2} + \frac{n^2-1}{n^2} \leq 1.$$

using  $0 \leq x_1 \leq 1$  and  $\sum_i x_i^2 \leq 1$



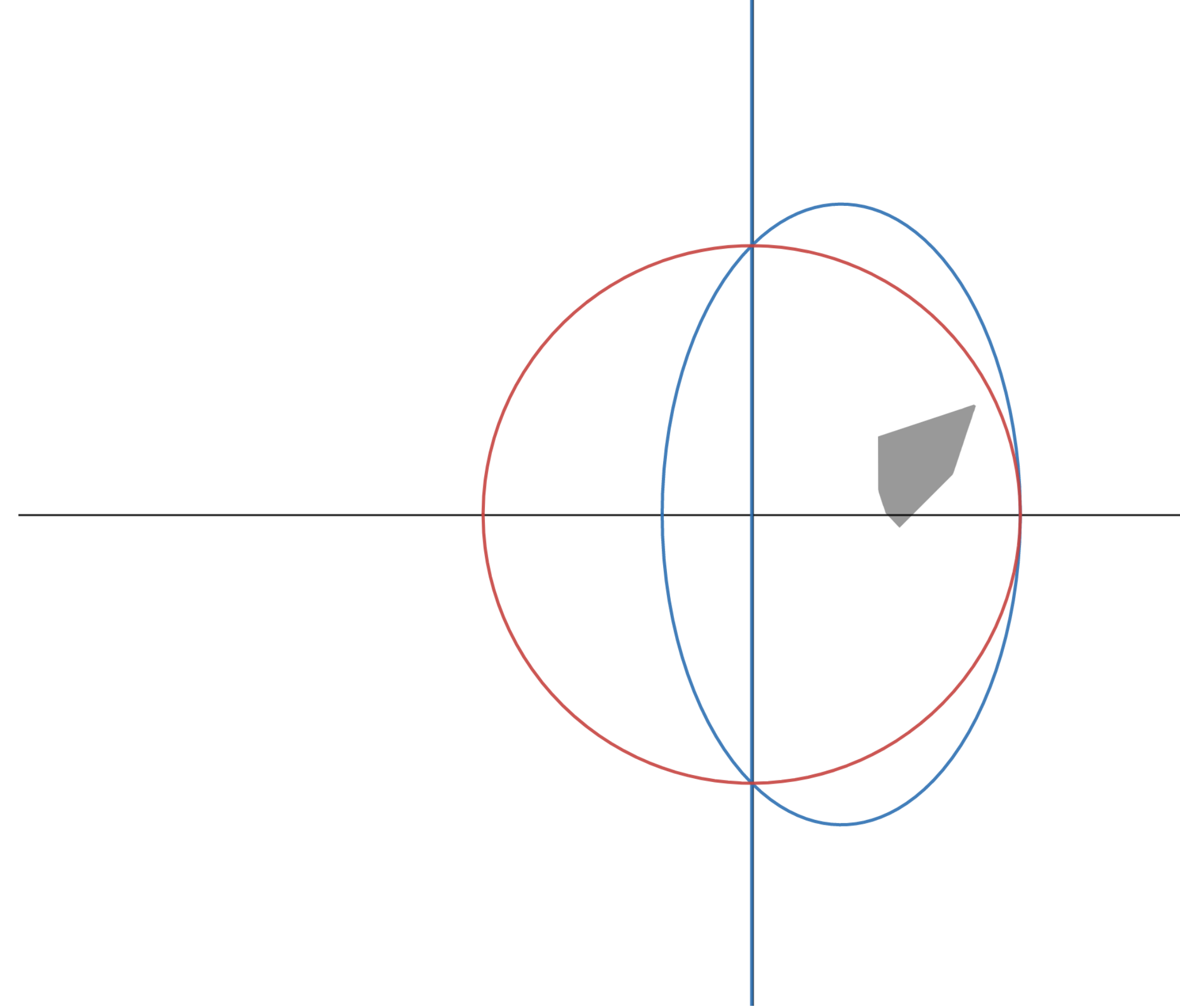
$$\textbf{Claim: } \text{vol}(E')/\text{vol}(E) \leq e^{\frac{-1}{2(n+1)}}$$

$$E: \sum_i x_i^2 \leq 1$$

$$E': \left(\frac{n+1}{n}\right)^2 \left(x_1 - \frac{1}{n+1}\right)^2 + \frac{n^2-1}{n^2} \cdot \sum_{i>2} x_i^2 \leq 1$$

$$\text{vol}(E')/\text{vol}(E)$$

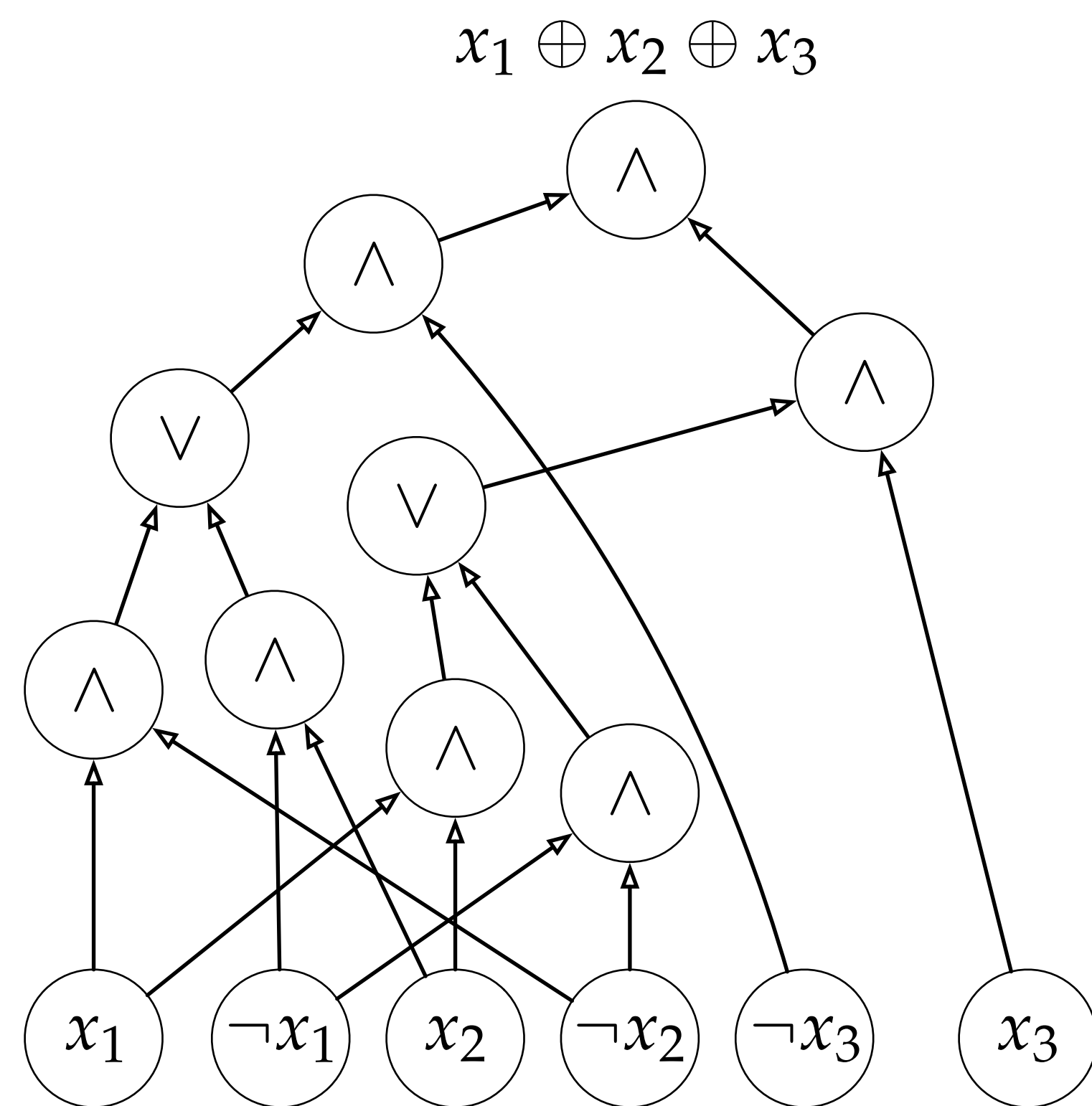
$$\begin{aligned} &= \frac{n}{n+1} \cdot \left(\sqrt{\frac{n^2}{n^2-1}}\right)^{n-1} \\ &= \left(1 - \frac{1}{n+1}\right) \cdot \left(1 + \frac{1}{n^2-1}\right)^{(n-1)/2} \stackrel{\text{using } 1+z \leq e^z}{\leq} e^{-\frac{1}{n+1}} \cdot e^{\frac{(n-1)/2}{n^2-1}} = e^{-\frac{1}{n+1}} \cdot e^{\frac{1}{2(n+1)}} = e^{\frac{-1}{2(n+1)}} \end{aligned}$$



# **Why is linear programming so powerful?**

**In a sense, every algorithm can be expressed as  
linear program!**

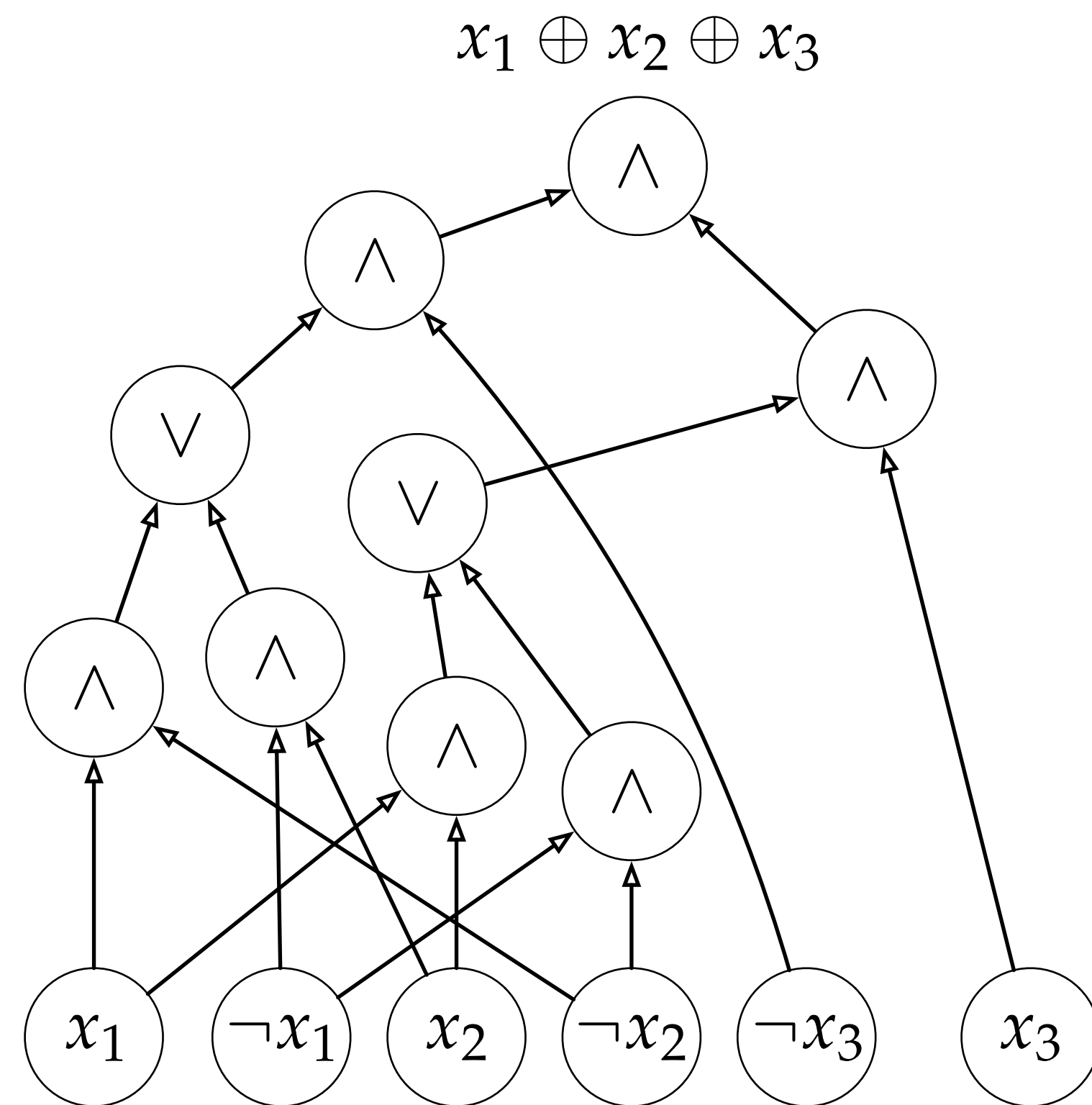
# Boolean circuits





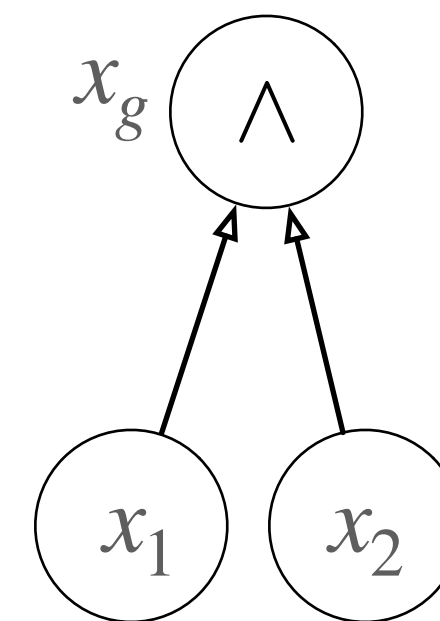
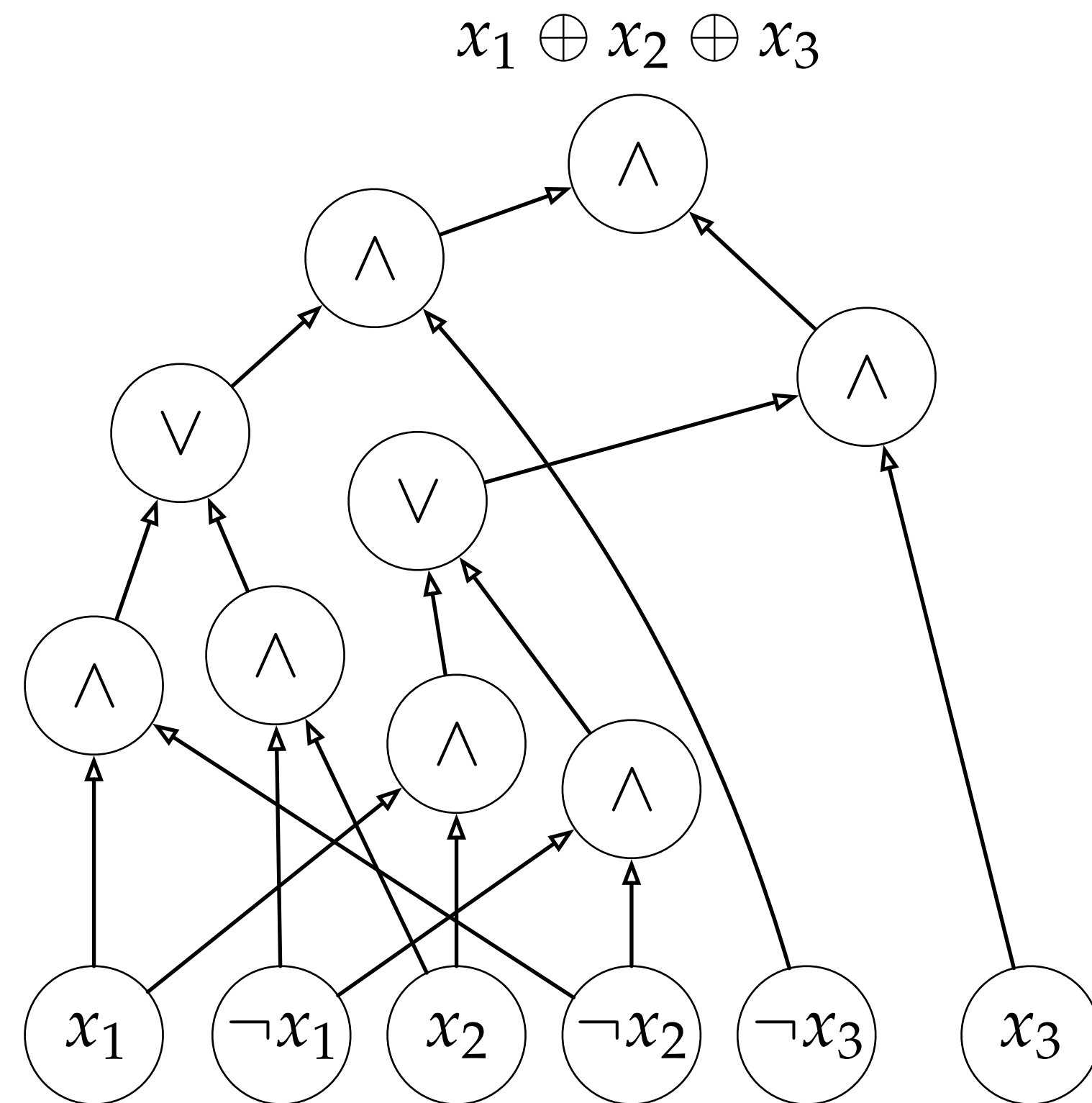
# Boolean circuits

**Fact:** If  $f : \{0,1\}^n \rightarrow \{0,1\}$  can be computed in time  $T$ , then it can be computed by a circuit of size  $O(T \log T)$ .

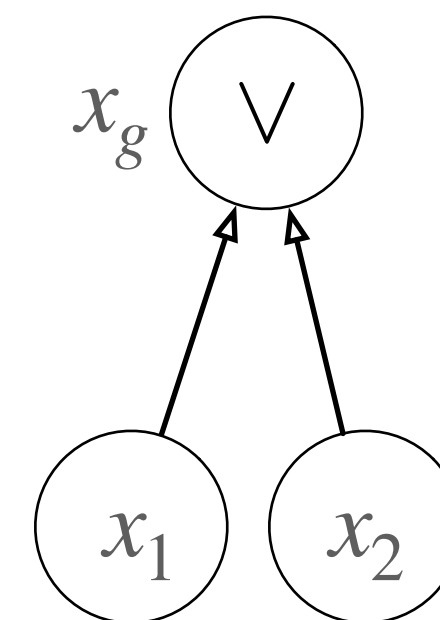


# Boolean circuits

**Fact:** If  $f : \{0,1\}^n \rightarrow \{0,1\}$  can be computed in time  $T$ , then it can be computed by a circuit of size  $O(T \log T)$ .



$$\begin{aligned} x_g &\leq x_1 \\ x_g &\leq x_2 \\ x_g &\geq x_1 + x_2 - 1 \end{aligned}$$



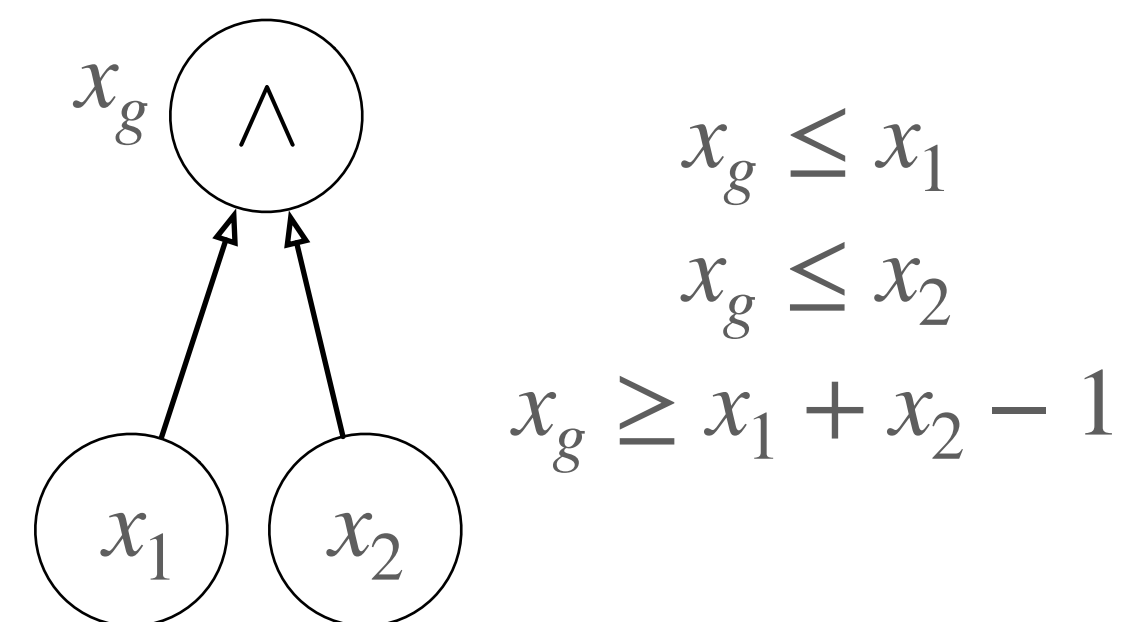
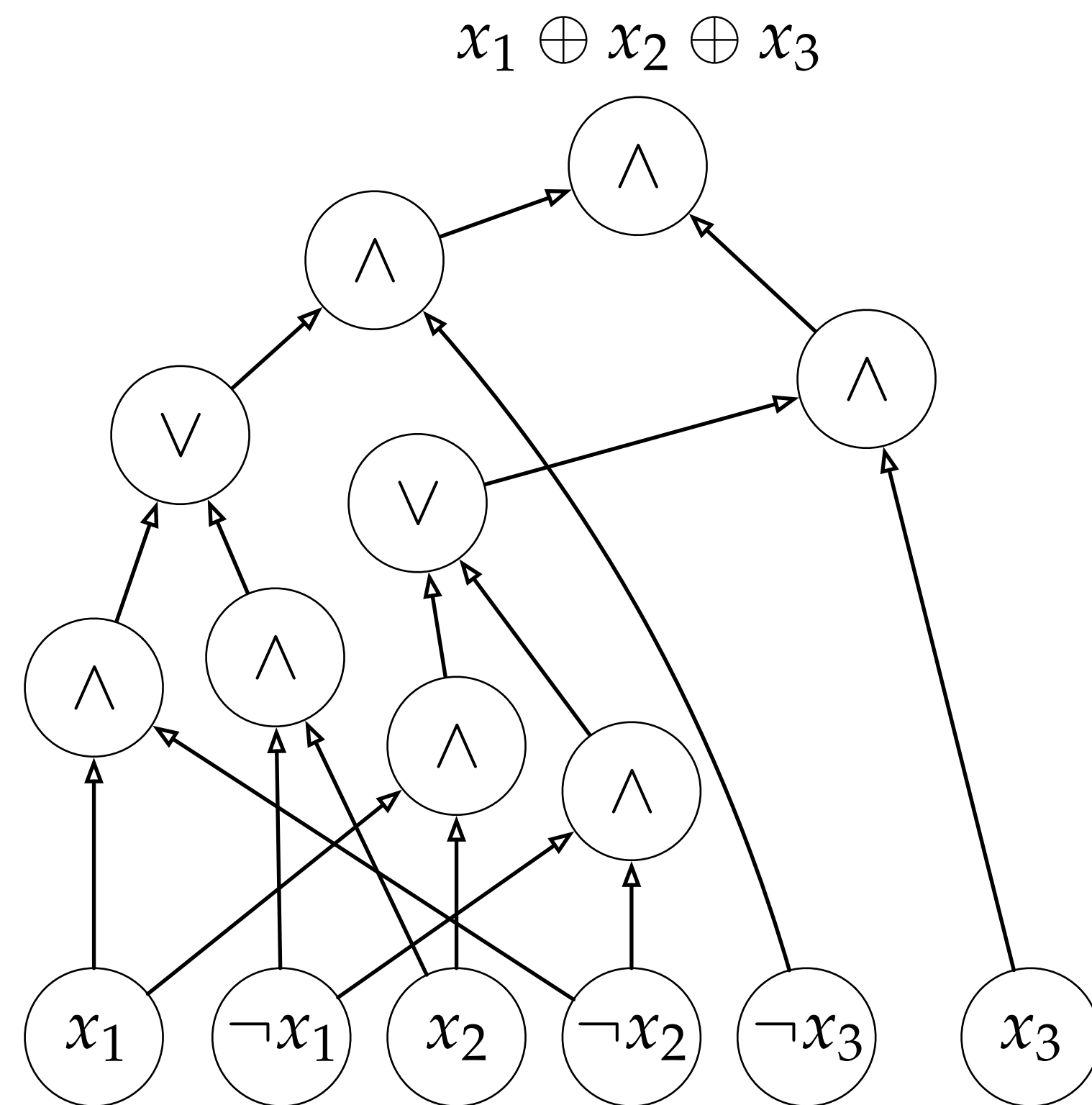
$$\begin{aligned} x_g &\geq x_1 \\ x_g &\geq x_2 \\ x_g &\leq x_1 + x_2 \end{aligned}$$

$$\neg x_g = 1 - x_g$$

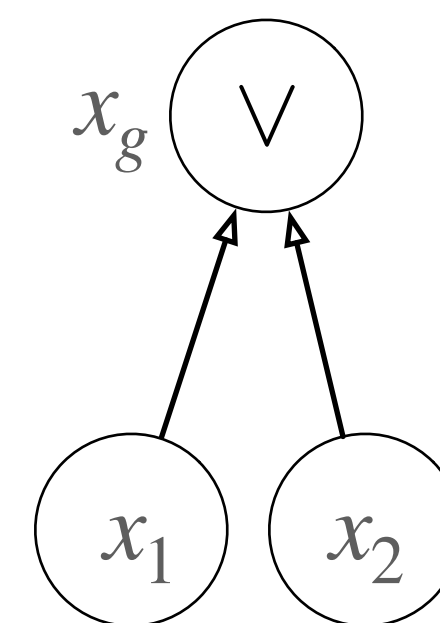
$$0 \leq x \leq 1$$

# Boolean circuits

**Fact:** If  $f : \{0,1\}^n \rightarrow \{0,1\}$  can be computed in time  $T$ , then it can be computed by a circuit of size  $O(T \log T)$ .



$$\begin{aligned} x_g &\leq x_1 \\ x_g &\leq x_2 \\ x_g &\geq x_1 + x_2 - 1 \end{aligned}$$



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$$\neg x_g = 1 - x_g$$

$$0 \leq x \leq 1$$

Computing  $f$  is equivalent to finding  $x$  satisfying these constraints!

# Approximation Algorithms from Linear Programs

**Vertex cover:**

$$\text{minimize } \sum_v x_v$$

subject to

for all  $v$ ,

$$0 \leq x_v \leq 1,$$

for all  $e = \{u, v\}$

$$x_u + x_v \geq 1$$

**Claim:** Any feasible solution that is a vertex of the polytope must have  $x_v \in \{0, 1/2, 1\}$ .

**Pf:**

Consider the solutions:

$$y_v = \begin{cases} x_v & \text{if } x_v \in \{0, 1/2, 1\} \\ x_v + \epsilon & \text{if } x_v > 1/2 \\ x_v - \epsilon & \text{otherwise.} \end{cases}$$

$$z_v = \begin{cases} x_v & \text{if } x_v \in \{0, 1/2, 1\} \\ x_v - \epsilon & \text{if } x_v > 1/2 \\ x_v + \epsilon & \text{otherwise.} \end{cases}$$

$y, z$  are valid solutions to the program. If  $x_v \notin \{0, 1/2, 1\}$ , then  $y \neq z$ , yet  $x = (y + z)/2$ , so  $x$  cannot be a vertex.

# Approximation Algorithms from Linear Programs

**Vertex cover:**

$$\text{minimize } \sum_v x_v$$

subject to

for all  $v$ ,

$$0 \leq x_v \leq 1,$$

for all  $e = \{u, v\}$

$$x_u + x_v \geq 1$$

**Claim:** Any feasible solution that is a vertex of the polytope must have  $x_v \in \{0, 1/2, 1\}$ .

**Consequence:** Let  $x$  be a solution that is a vertex of the polytope. If we pick the set of vertices

Let  $S = \{v : x_v > 0\}$ , this is a valid vertex cover that is at most twice as large as the best one!

# Approximation Algorithms from Linear Programs

**Set cover:**

$$\text{minimize } \sum_S x_S$$

subject to

for all  $S$ ,

$$0 \leq x_S,$$

for all  $i \in \{1, \dots, n\}$

$$\sum_{i \in S} x_S \geq 1$$

**Dual program:**

$$\text{maximize } \sum_i y_i$$

subject to

for all  $i$ ,

$$0 \leq y_i,$$

for all  $S$

$$\sum_{i \in S} y_i \leq 1$$

# Approximation Algorithms from Linear Programs

**Dual program:**

$$\text{maximize } \sum_i y_i$$

subject to

for all  $i$ ,

$$0 \leq y_i,$$

for all  $S$

$$\sum_{i \in S} y_i \leq 1$$

**Recall greedy algorithm:**

In each step, pick the set that covers the most remaining elements.

Let  $z_i = 1/k$ , if  $i$  was covered in a group of  $k$  elements.

Let  $H_r = 1 + 1/2 + \dots + 1/r$ .

**Claim:**  $z/H_n$  is a valid solution to dual.

**Pf:**

Without loss of generality, suppose  $S = \{1, 2, \dots, k\}$ , and the elements are covered in order. Then we see:

$$\begin{aligned} \sum_{i \in S} z_i &\leq (1/k + 1/(k-1) + \dots + 1) \\ &\leq H_n. \end{aligned}$$

# Approximation Algorithms from Linear Programs

**Dual program:**

$$\text{maximize } \sum_i y_i$$

subject to

$$\text{for all } i, \\ 0 \leq y_i,$$

$$\text{for all } S \\ \sum_{i \in S} y_i \leq 1$$

**Recall greedy algorithm:**

In each step, pick the set that covers the most remaining elements.

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Let  $H_r = 1 + 1/2 + \dots + 1/r$ .

**Claim:**  $z/H_n$  is a valid solution to dual.

Consequence:

The dual has value at least the size of greedy solution  $/H_n$ . Since  $H_n \leq O(\log n)$ , the greedy is within  $O(\log n)$  of the optimal solution.