

#### Distributed MST Construction

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### Distributed MST

- Last week:
  - Started studying synchronous version of distributed MST algorithm
- Today:
  - Finish discussing synchronous version
  - Study algorithm in asynchronous model
- Both algorithms are based on MST construction algorithm by Gallager, Humblet, and Spira



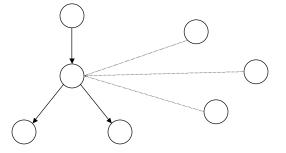
#### **Basic Node Execution**

- Each node maintains state regarding its edges
  - Knows their weights
  - Classifies them into one of three bins:
    - Unexplored, tree branch, rejected
    - Initially all edges are unexplored
    - When an edge is discovered to be an intra-fragment edge, it is considered "rejected"
  - It knows which edge leads to parent
  - All other "branch" edges lead to children
- Beginning:
  - Consider all edges to be unexplored
  - Sort the edges according to increasing weight



#### Basic Node Execution (contd.)

- When a node receives a search for MWOE from the leader:
  - Makes note of the leader and parent
  - Propagates search query along all other branch edges
  - Starts exploring each of its unexplored edges in sorted order
    - If other endpoint in the same fragment, edge is "rejected"
    - Finds MWOE from its node
  - Waits for MWOE results from children and reports to parent





#### Overall Algorithm (synchronous version)

- In each phase of the algorithm
  - Leader of each fragment does:
  - 1) Broadcasts "search" for MWOE
    - 1) Nodes propagate broadcast
    - 2) Synchronize before beginning test for outgoingness
  - 2) Waits for results to be convergecasted
  - 3) If no MWOE, terminate
  - 4) Leader sends a "connect" message down the tree across MWOE
    - 1) Marks the MWOE edge as a "branch"
    - 2) If "connect" has gone across the same edge in both directions, elect one of the two endpoints as leader
  - Synchronize, repeat



#### Analysis of a single phase

- How to synchronize?
  - Use counters, wait for counter to reach a certain value
  - Implies algorithm is synchronous and non-uniform
- Potential points of synchronization:
  - Broadcast is received by everyone after "n" ticks
  - Nodes might explore a maximum of "n" neighbors
    - Node finds MWOE in "2\*n" ticks
  - Convergecast can take at most "n" ticks
  - New leader is elected within another "n" ticks



### Analysis of Algorithm

- How many phases does the algorithm go through?
- What is the message complexity?



#### **Announcements**

- Sample C-TCP code:
  - Does not transmit the "\0" at the end of the buffer
  - Multithreaded server:
    - Can still use "select" mechanism to identify when a connection dies
- Original GHS paper:

http://lambda.cs.yale.edu/cs425/doc/ghs.pdf



#### Asynchronous Algorithm

- Cannot use local clocks (counters) to synchronize
- How do we fashion an asynchronous algorithm?



#### Asynchronous Algorithm

- Fragment identifier now contains the following:
  - Leader of the fragment
  - Level of the fragment
- Fragments combine in two ways:
  - Two fragments at the same level "merge" to form a fragment of the next level
  - A lower-numbered fragment can be "absorbed" by a higher level fragment
    - Does not change the level of the higher-numbered fragment
    - Does not change the leader of the higher-numbered fragment
    - Lower-numbered fragment inherits level, leader of the other fragment



# Asynchronous Algorithm: Balanced growth

- When a node n1 queries n2
- n1) (n2)
- If level(n1) < level(n2)</p>
  - n1 and n2 should be in different fragments
  - n2 "accepts" the outgoingness "test"
- If level(n1) == level(n2)
  - Check the leader identities
    - If leaders are different, "test" is accepted
    - If leaders are same, "test" is rejected
- If level(n1) > level(n2)
  - Possible that n1 and n2 belong to the same fragment
  - Even if they are determined to be on different fragments, we allow only "merges" and "absorbs"
  - Wait for level(n2) >= level(n1)



#### Asynchronous Algorithm

- Leader of each fragment does:
  - 1) Broadcasts "search" for MWOE
    - 1) Nodes propagate broadcast
      - 2) Nodes begin test for outgoingness immediately
  - 2) Waits for results to be convergecasted
  - 3) If no MWOE, terminate
  - 4) Leader sends a "connect" message down the tree across MWOE
    - 1) If "connect" goes from lower level to higher level:
      - Mark edge as "branch" for both endpoints
    - 2) When "connect" goes across MWOE for the first time between two fragments at the same level
      - Mark edge as "branch" for both endpoints
    - 3) When "connect" goes across MWOE in both directions:
      - Elect a leader, increment level of the new fragment



#### **Proving Correctness**

- Safety property:
  - No cycles
  - Relies on the correctness of the "outgoingness" test
- Liveness properties:
  - System is making progress
  - We have introduced "wait" as part of the "test" procedure
  - Fortunately, there are no cyclic-wait dependencies
    - Therefore, no deadlocks
    - Eventually, lowest-numbered fragment does make progress



#### Analysis of Algorithm

- Initially "n" fragments
- Number of fragments as level increases by one:
  - Decreases by at least a factor of two
- Maximum level number: log(n)
- Time complexity:
  - At time 0, all fragments are at level 0
  - By time n, none of the level-0 fragments exist
  - At time t, let lowest-numbered fragment be at level k
  - By time t+n, all level k fragments have been promoted
  - Total time: O(n log(n))



## Message Complexity

- Remains the same as synchronous algorithm
- Number of "test" and number of "accept/reject" messages:
  - m each
- At each level, number of broadcast, convergecast messages: O(n)
- Total number of messages: O(nlog(n) + m)



#### Algorithm Wrapup

- Powerful distributed algorithm
  - Elects a leader
  - Computes a spanning tree
  - Finds the minimum weight spanning tree
  - All at a message complexity of O(nlogn + m)
    - Recall that nlogn was a lower bound on messages
    - Cannot do better than O(m): need to explore all edges
- Time complexity:
  - Improved later to min(n, (D + d)\*logn)
  - D: diameter of the MST
  - d: maximum node-degree of input graph