

Miniature Implantable Computers for Functional Electrical Stimulation and Recording of Neuromuscular Activity

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Overview

- Motivation
- Objectives
- Biological background
- Neurochip architecture
- Experiments on insect flight
- Summary and conclusions

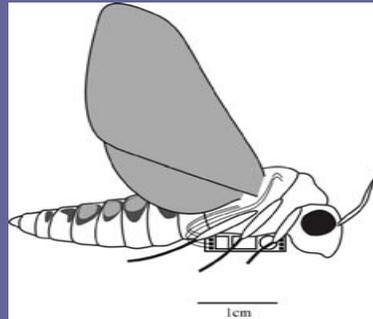
Motivation

- Biological motor control and learning
- Neurophysiology of freely-behaving organisms
- Bio-computer interfaces
- Autonomous implantable computers

Objectives



Hawkmoth (*Manduca sexta*)



insect flight

insect intelligence

flight control &
design

flight energetics

Background



Manduca tracking a
robotic flower

- Nocturnal hover flyer
- Visually-guided tracking
- Can carry ~1g
- Use abdomen for center of gravity shifts

Background

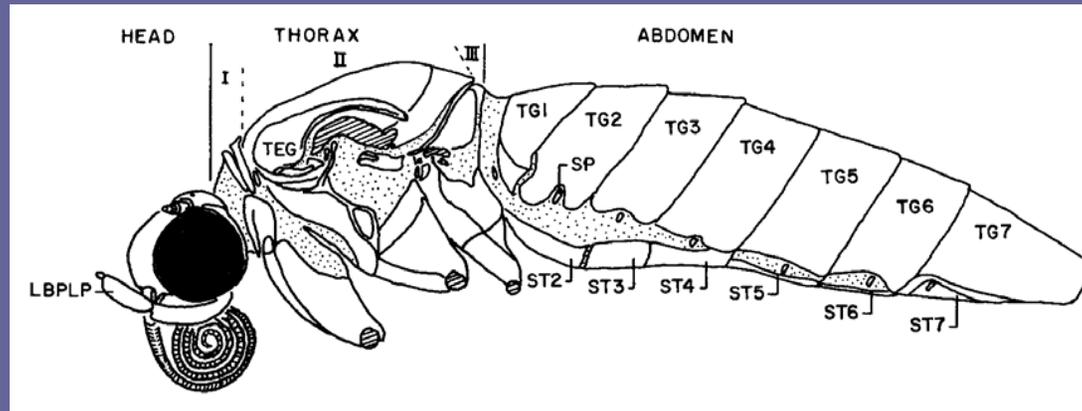
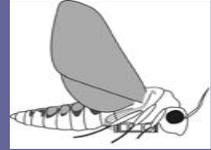
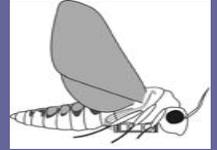


Figure from J.L. Eaton's "Lepidopteran Anatomy"

- Simple musculature
- Unmyelinated nerves allowing low-voltage stimulation

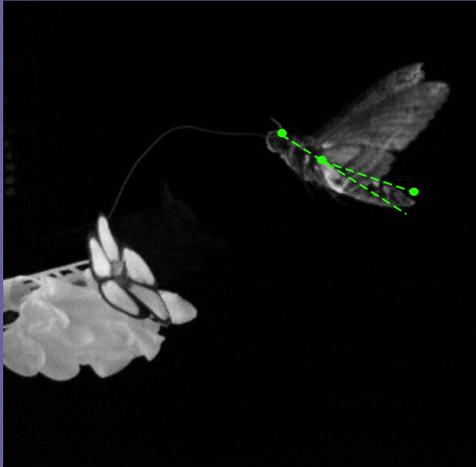
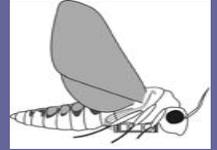
Abdominal Flexion Constrained Flight



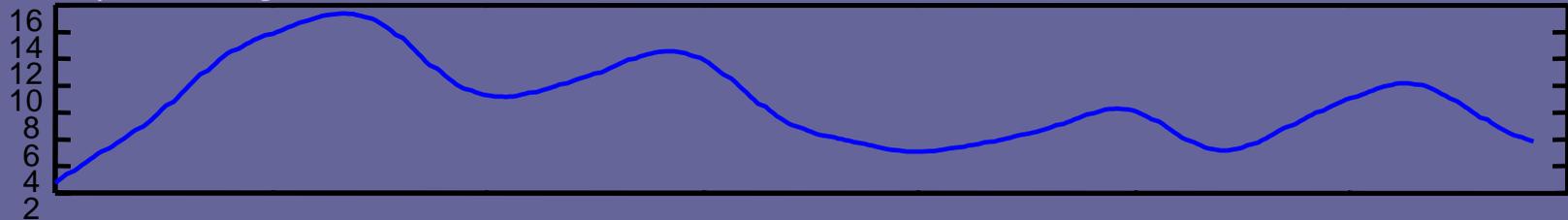
- Flexion and visual feedback
- Used during hover, forward-flight maneuvers
- And for predator avoidance

Abdominal Flexion

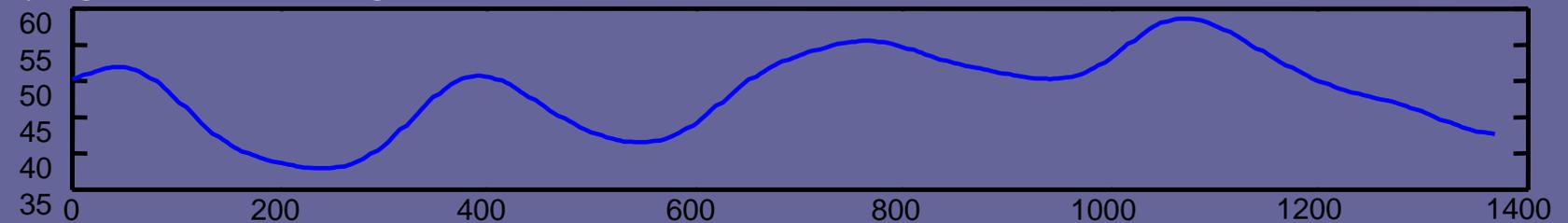
Free Flight



dorsal body flexion (degrees)



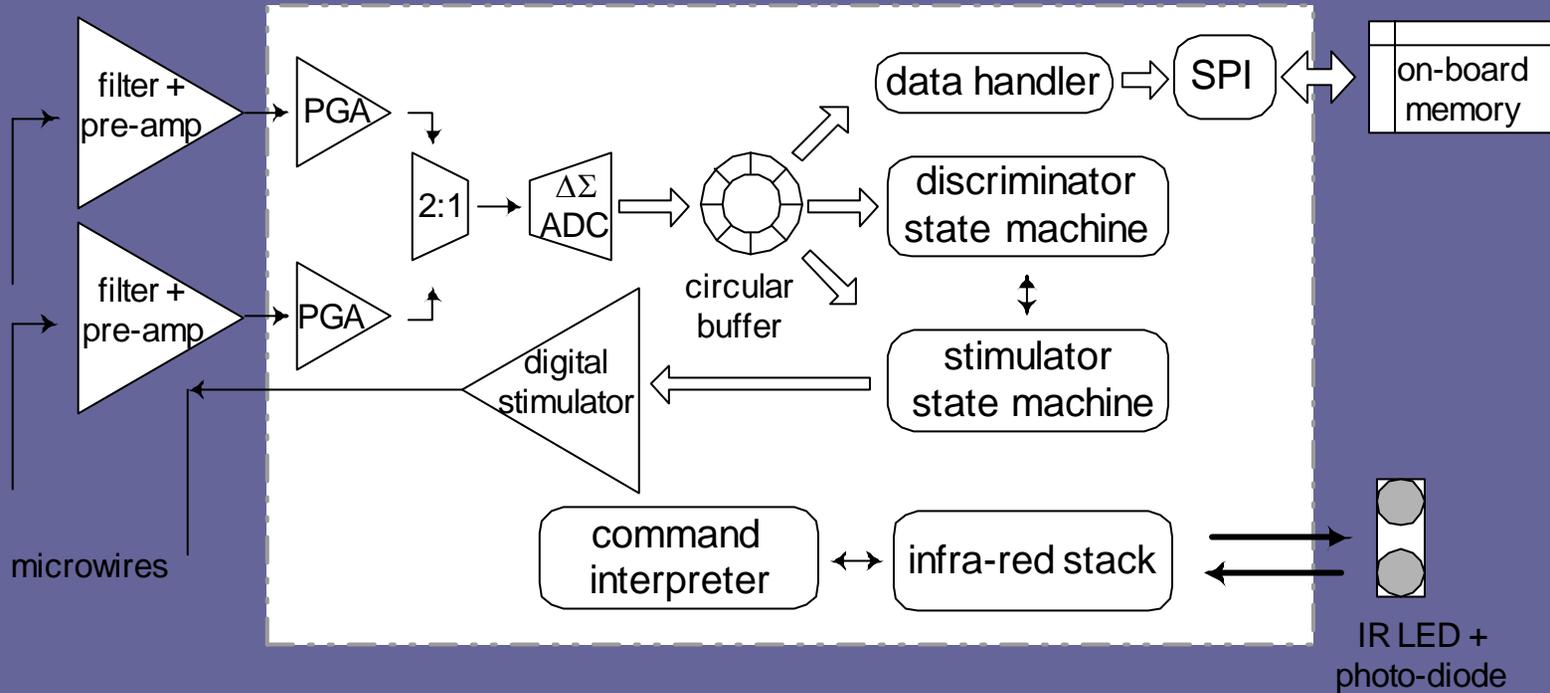
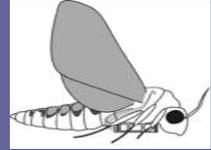
body angle from horizontal (degrees)



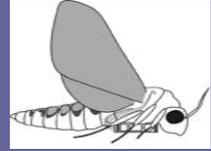
JM

from Stacey Combes

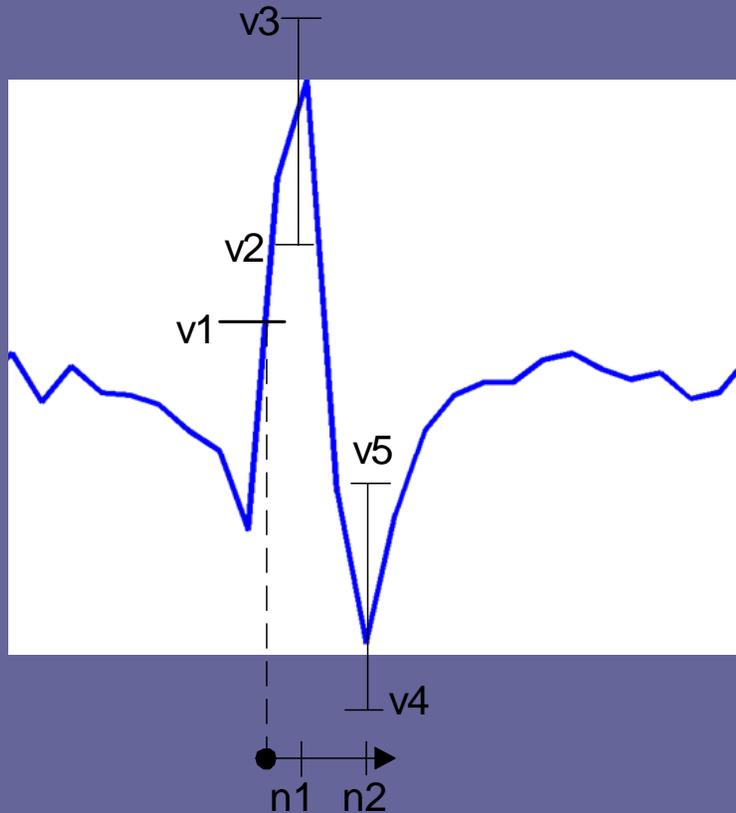
Neurochip Architecture



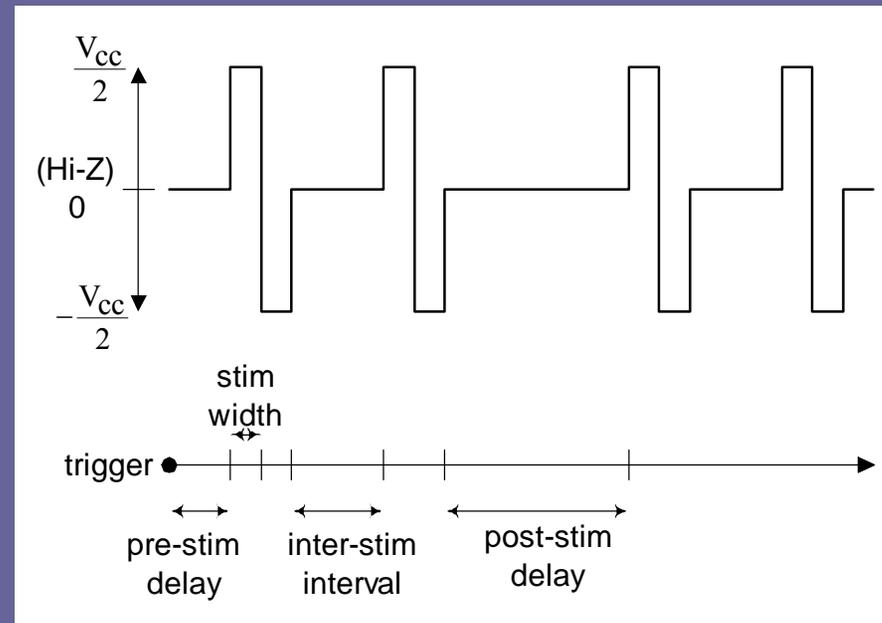
Neurochip Architecture



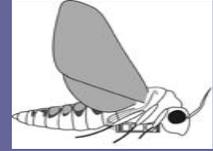
Dual time-amplitude discriminator



Biphasic digital stimulator



Neurochip Prototypes



1st Generation



(top)

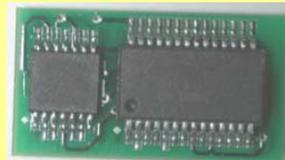


(bottom)

1cm x 3cm x 0.5cm
1.47g (without battery)



2nd Generation



(top)



(bottom)

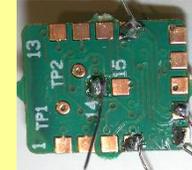
1cm x 1.9cm x 0.4cm
0.85g (without battery)



3rd Generation

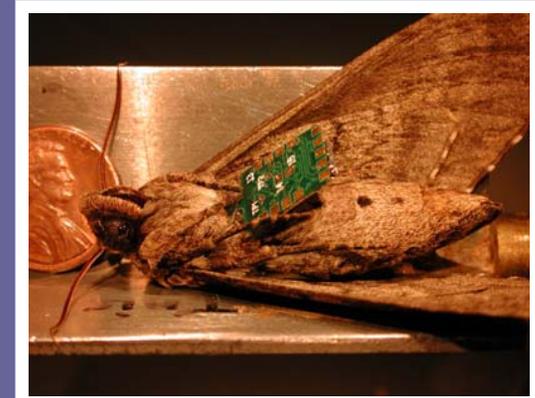


(top)



(bottom)

1cm x 1.25cm x 0.25cm
0.25g (without battery)

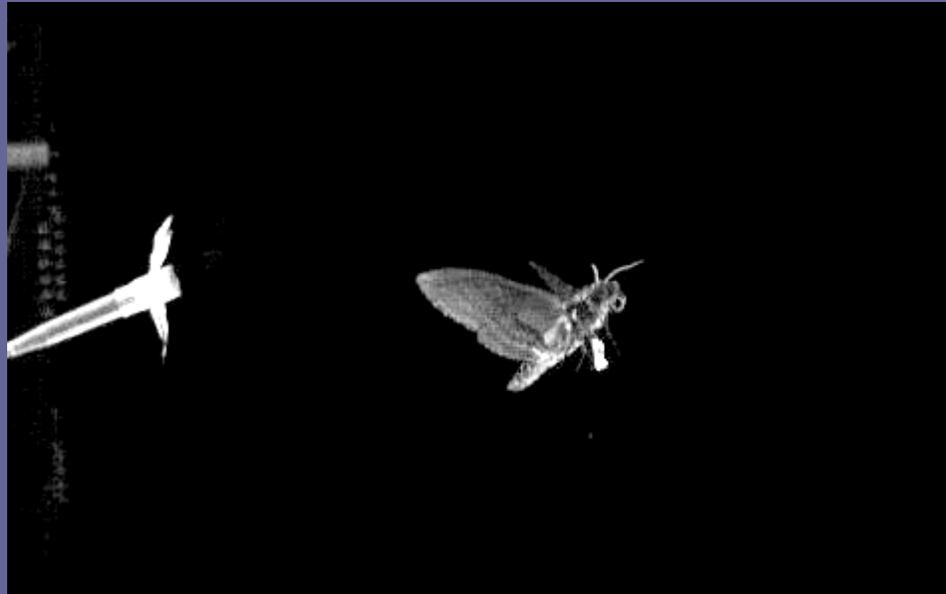


4th Generation



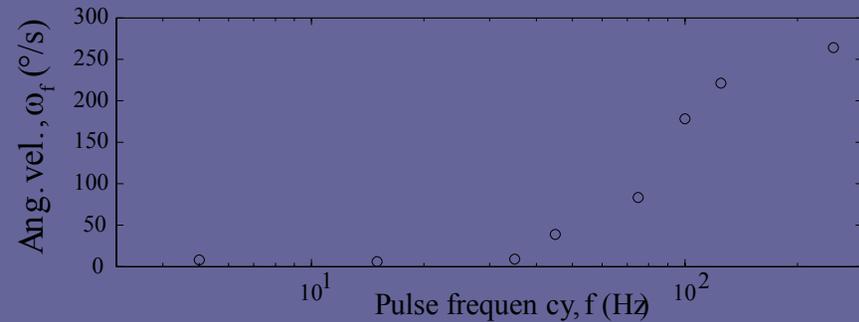
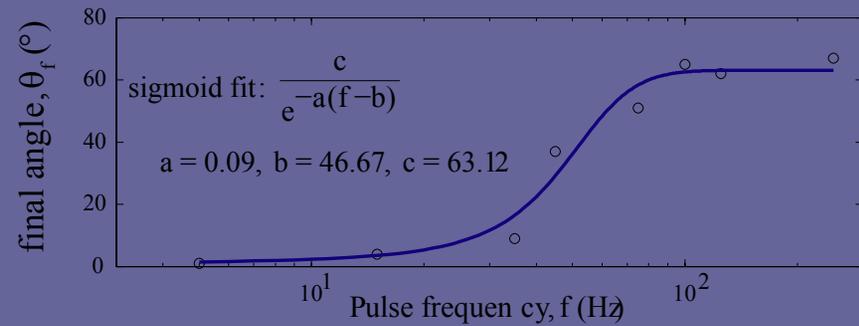
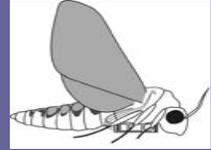
0.9cm x 1cm
0.6g

Neurochip Prototypes



Neurochip Experiments

Abdominal flexion: Tuning curves



$f = 35\text{Hz}$



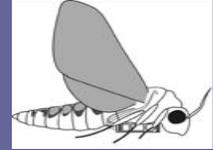
$f = 45\text{Hz}$



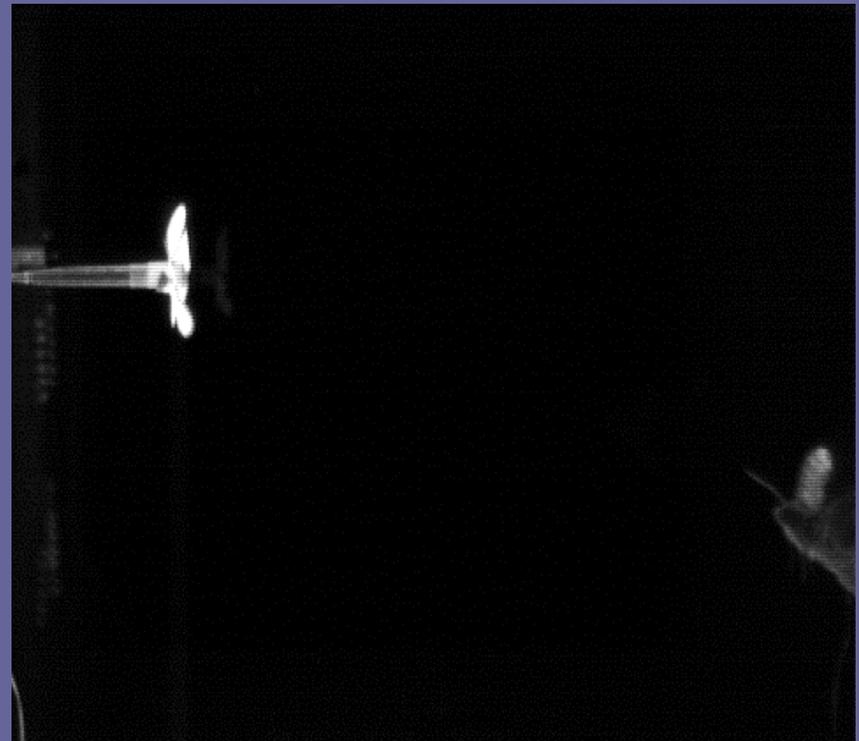
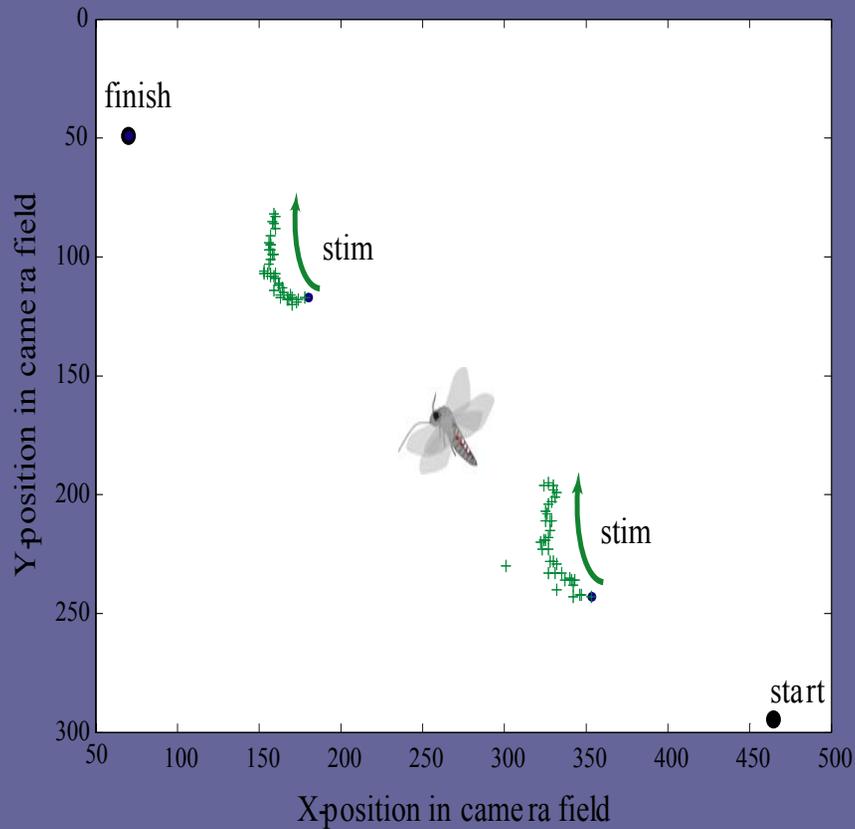
$f = 75\text{Hz}$



Neurochip Experiments



Stimuli: 1ms pulse @ 100Hz



Summary

- Feasibility of miniature flight computers
- Tuning characteristics of abdominal flexion to pure digital stimulation
- In-flight stimulation to affect flight path deviations

Acknowledgements

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