

CS-XXX: Graduate Programming Languages

Lecture 19 — Type-and-Effect Systems

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Type-and-effect systems

New topic: An elegant framework to extend type systems to track “things that may happen” (effects) during evaluation

Plain-old type systems have judgments like $\Gamma \vdash e : \tau$ to mean:

- ▶ e won’t get stuck
- ▶ If e produces a value, that value has type τ

Adding *effects* reuses the “plumbing” of typing rules to compute something about “how e executes”

- ▶ There are many things we may want to conservatively approximate
 - ▶ Example: What exceptions might get thrown
- ▶ All effect systems are very similar, especially treatment of functions
 - ▶ Example: All values have no effect since their “computation” does nothing

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First a type system

(In this example, exceptions raise constant strings s)

$$\begin{array}{l}
 \begin{array}{c}
 \tau ::= \text{bool} \mid \tau \rightarrow \tau \mid \tau * \tau \\
 e ::= x \mid \text{true} \mid \text{false} \mid \lambda x. e \mid e e \mid (e, e) \mid e.1 \mid e.2 \\
 \quad \mid \text{if } e \ e e \mid \text{raise } s \mid \text{try } e \text{ handle } s \ e
 \end{array} \\
 \frac{\Gamma \vdash e : \tau}{\Gamma \vdash x : \Gamma(x)} \quad \frac{\Gamma \vdash \text{true} : \text{bool}}{} \quad \frac{\Gamma \vdash \text{false} : \text{bool}}{} \\
 \frac{\Gamma, x : \tau_1 \vdash e : \tau_2}{\Gamma \vdash \lambda x. e : \tau_1 \rightarrow \tau_2} \quad \frac{\Gamma \vdash e_1 : \tau_2 \rightarrow \tau_1 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash e_1 \ e_2 : \tau_1} \\
 \frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash (e_1, e_2) : \tau_1 * \tau_2} \quad \frac{\Gamma \vdash e : \tau_1 * \tau_2}{\Gamma \vdash e.1 : \tau_1} \quad \frac{\Gamma \vdash e : \tau_1 * \tau_2}{\Gamma \vdash e.2 : \tau_2} \\
 \frac{\Gamma \vdash e_1 : \text{bool} \quad \Gamma \vdash e_2 : \tau \quad \Gamma \vdash e_3 : \tau}{\Gamma \vdash \text{if } e_1 \ e_2 \ e_3 : \tau} \\
 \frac{\Gamma \vdash e_1 : \tau \quad \Gamma \vdash e_2 : \tau}{\Gamma \vdash \text{raise } s : \tau} \quad \frac{\Gamma \vdash \text{try } e_1 \text{ handle } s \ e_2 : \tau}{\Gamma \vdash \text{try } e_1 \text{ handle } s \ e_2 : \tau}
 \end{array}$$

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Add effects

$$\begin{array}{l}
 \epsilon ::= \dots \text{sets of strings...} \\
 \tau ::= \text{bool} \mid \tau \xrightarrow{\epsilon} \tau \mid \tau * \tau \\
 e ::= x \mid \text{true} \mid \text{false} \mid \lambda x. e \mid e e \mid (e, e) \mid e.1 \mid e.2 \\
 \quad \mid \text{if } e \ e e \mid \text{raise } s \mid \text{try } e \text{ handle } s \ e
 \end{array}$$

$$\begin{array}{c}
 \frac{\Gamma \vdash e : \tau; \epsilon}{\Gamma \vdash x : \Gamma(x); \emptyset} \quad \frac{\Gamma \vdash \text{true} : \text{bool}; \emptyset}{\Gamma \vdash \text{false} : \text{bool}; \emptyset} \\
 \frac{\Gamma, x : \tau_1 \vdash e : \tau_2; \epsilon}{\Gamma \vdash \lambda x. e : \tau_1 \xrightarrow{\epsilon} \tau_2; \emptyset} \quad \frac{\Gamma \vdash e_1 : \tau_2 \xrightarrow{\epsilon_3} \tau_1; \epsilon_1 \quad \Gamma \vdash e_2 : \tau_2; \epsilon_2}{\Gamma \vdash e_1 \ e_2 : \tau_1; \epsilon_1 \cup \epsilon_2 \cup \epsilon_3} \\
 \frac{\Gamma \vdash e_1 : \tau_1; \epsilon_1 \quad \Gamma \vdash e_2 : \tau_2; \epsilon_2 \quad \Gamma \vdash e : \tau_1 * \tau_2; \epsilon \quad \Gamma \vdash e : \tau_1 * \tau_2; \epsilon}{\Gamma \vdash (e_1, e_2) : \tau_1 * \tau_2; \epsilon_1 \cup \epsilon_2} \quad \frac{\Gamma \vdash e.1 : \tau_1; \epsilon}{\Gamma \vdash e.2 : \tau_2; \epsilon} \\
 \frac{\Gamma \vdash e_1 : \text{bool}; \epsilon_1 \quad \Gamma \vdash e_2 : \tau; \epsilon_2 \quad \Gamma \vdash e_3 : \tau; \epsilon_3}{\Gamma \vdash \text{if } e_1 \ e_2 \ e_3 : \tau; \epsilon_1 \cup \epsilon_2 \cup \epsilon_3} \\
 \frac{\Gamma \vdash e_1 : \tau; \epsilon_1 \quad \Gamma \vdash e_2 : \tau; \epsilon_2}{\Gamma \vdash \text{raise } s : \tau; \{s\}} \quad \frac{\Gamma \vdash \text{try } e_1 \text{ handle } s \ e_2 : \tau; (\epsilon_1 - \{s\}) \cup \epsilon_2}{\Gamma \vdash \text{try } e_1 \text{ handle } s \ e_2 : \tau; (\epsilon_1 - \{s\}) \cup \epsilon_2}
 \end{array}$$

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Key facts

Soundness: If $\cdot \vdash e : \tau; \epsilon$ and e raises uncaught exception s , then $s \in \epsilon$

- ▶ Corollary to Preservation and Progress (once you define the operational semantics for exceptions)

All effect systems work this way:

- ▶ Values effectless
- ▶ Functions have *latent effects*
- ▶ Conservative due to control-flow (if and try/handle)
- ▶ Often some way to *mask effects* (here, catch an exception)

Only a couple rules special to this effect system

- ▶ Also, not always sets and \cup

More general rules

Every effect system also substantially more expressive via appropriate subsumption:

- ▶ Typing rule for subeffecting (also useful for Preservation)
- ▶ Subtyping of function types is covariant in latent effects

$$\frac{\Gamma \vdash \tau : e; \epsilon \quad \epsilon \subseteq \epsilon'}{\Gamma \vdash \tau : e; \epsilon'} \quad \frac{\tau_3 \leq \tau_1 \quad \tau_2 \leq \tau_4 \quad \epsilon \subseteq \epsilon'}{\tau_1 \xrightarrow{\epsilon} \tau_2 \leq \tau_3 \xrightarrow{\epsilon'} \tau_4}$$

Not shown: Also want effect polymorphism (type variables ranging over effects) for higher-order functions like map

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Other examples

- ▶ Definitely terminates (true) or possibly diverges (false)
 - ▶ Give **fix** e effect *false*
 - ▶ Give values effect *true*
 - ▶ Treat \cup as *and*
 - ▶ No change to rules for functions, pairs, conditionals, etc.
- ▶ What type casts might occur
- ▶ Are certain variables always accessed in critical sections
- ▶ Does code obey a locking protocol
- ▶ Does code only access memory regions that haven't been deallocated
- ▶ ...

Really a general way to lift static analysis to higher-order functions

- ▶ Key is recognizing "from a mile away" when an effect system is the right tool