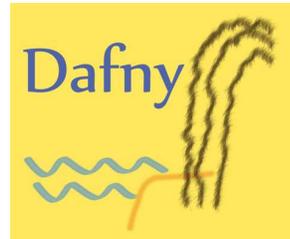


Investigating Safety of a Radiotherapy Machine Using System Models with Pluggable Checkers

**Combining Formal Models
with Concrete Evidence**

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Jacky



alloy **RO**SETTE

SLAM
`il=node->(); i++; visit_procs_end(*node){`

TLA+

Z3

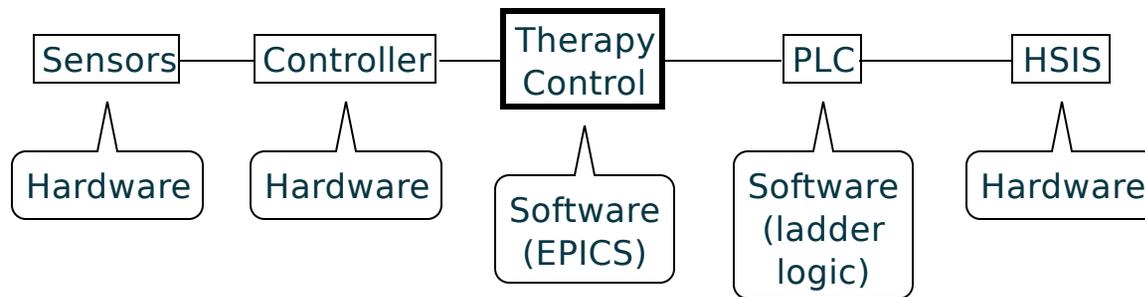
CNTS Safety Property



Prescription Safety:

If any setting exceeds the prescribed tolerances then the beam will shut off.

CNTS Architecture



Prescription Safety:

If the gantry angle exceeds the prescribed tolerances then the beam will shut off.

Formal Modeling

```

pred ControllersAreCorrect[] {
  evidence[Expert,
    "-.file" -> "cnts-sc/rx/inspections.yaml" +
    "-.claim" -> "assume-controllers-ok",
    ManualInspection] =>

  {
    ((all c: Controller | c.observd = MachineState) and
    (all req : PollRequest |
      (let resp = request.req |
        one resp and
        resp in req.next and
        resp.request = req and
        resp.to = req.from and
        resp.from = req.to and
        resp.settings = (resp.from.monitored)<:(resp.observd.actual) and
        resp.observd in resp.from.observd and
        happensMostRecentlyBefore[resp.observd, req, resp.from.observd])))
  }

  -- TC correctly updates MOD1:Waveform:Calc for every PollResponse it receives
  -- from the given embedded controller.
pred TCProcessesPollResponsesCorrectly(controller : Controller) {
  all resp: TC.receivedMsgs & PollResponse & from.controller |
  one tcdb : TC.db & resp.next |
  -- All variables corresponding to observd machine settings are set correctly.
  resp.settings in tcdb.actual and

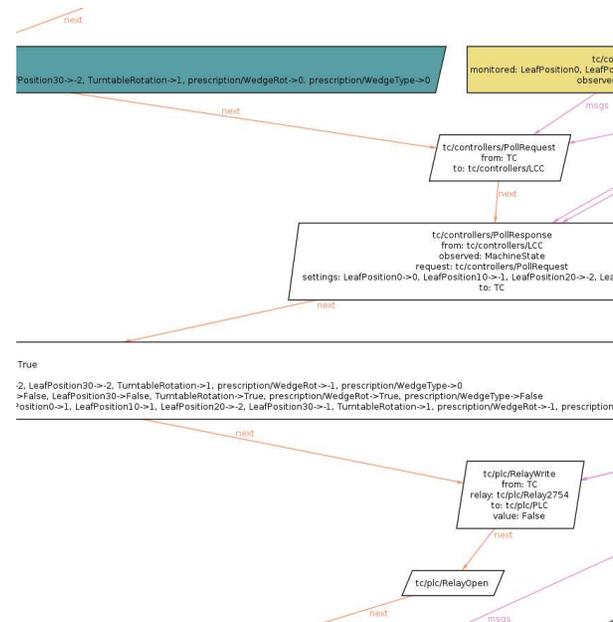
  -- The therapy sum interlock bit is 0 if the actual setting value is outside of the
  -- tolerance and the override flag is not raised for that setting.
  ((some setting : controller.monitored |
    tcdb.actual[setting] not in tcdb.tolerated[setting] and
    tcdb.override[setting] = False) =>
    tcdb.MOD1_WaveForm_Calc_1 = False) and

  -- The waveform output record gets processed as part of the update.
  tcdb.MOD1_IntlkCnOutWArray_Processed = True
}

-- If PLC relay 2754 is opened, then coil 1623 is immediately deenergized,
-- which is immediately conveyed to HSI3 through a CoilChange message.
pred Coil1623DeenergizedWhenRelay2754Open [] {
  evidence[PLC_Analysis,
    "-.mode" -> "all-paths-to-coil-contain-relay" +
    "-.network.file" -> "plc-code/cyclotron/mod1.stu" +
    "-.coil" -> "%M1623" +
    "-.relay" -> "%M2754",
    Proof] =>

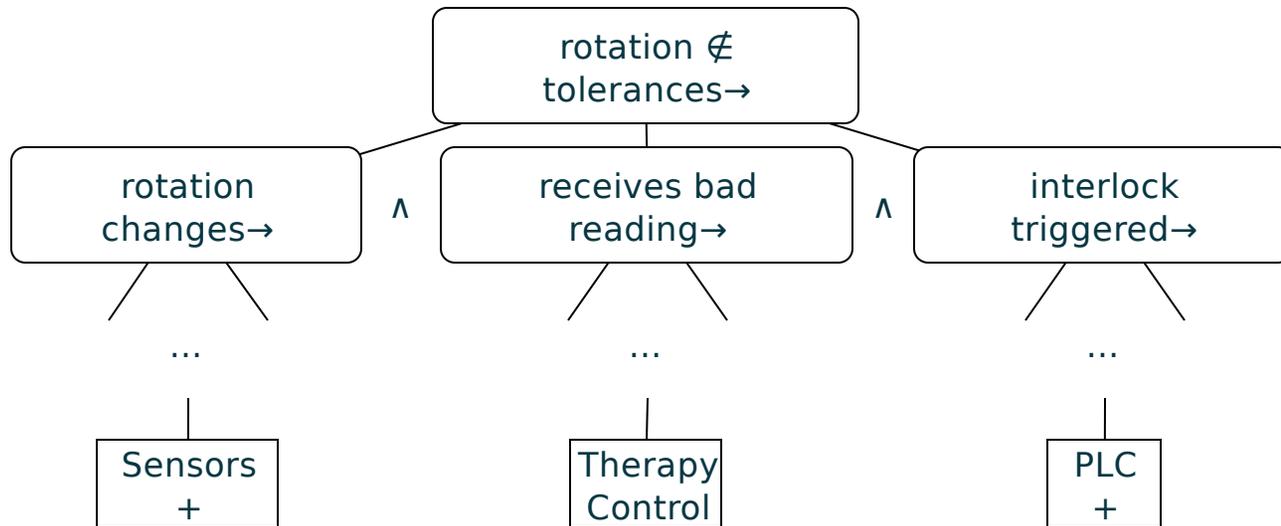
  {
    all relayOpen: Relay2754.state & RelayOpen |
    some coilState: Coil1623.state & CoilDeenergized, coilChange : PLC.sentMsgs & CoilChange |
    coilState in relayOpen.next and
    coilChange in coilState.next and
    coilChange.coil = Coil1623 and
    coilChange.state = coilState
  }
}

```



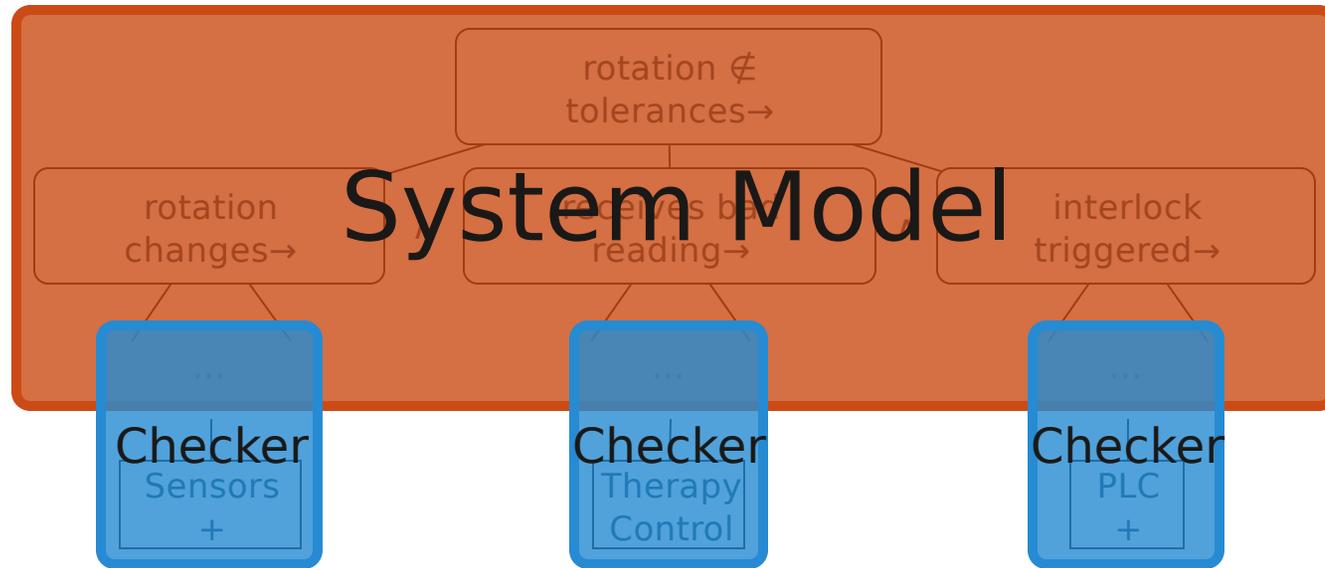
- + Automatically check safety of the model
- Difficult to ensure the model matches the system

Safety Property Decomposition



- + Easy to integrate any type of evidence
- No support for automated checking

Our Approach



- + Automated checking of safety properties
- + Can incorporate any type of evidence
- ★ Bonus: Building the model eases checker development

Outline

Background

 Modelling with Evidence

 Pluggable Checker Development

Results



The Alloy Model

Given:

- When the sensor reading changes, the controller outputs the new reading.
- When the therapy control program processes an event, if the current rotation reading is out of tolerances, it sets the Therapy Sum Interlock value to 0.
- When PLC relay #2754 is opened, PLC coil #1623 is deenergized.
- ...

Is it the case that:

- When the gantry rotation angle moves out of the prescribed tolerances, the beam shuts off.

```
pred ControllersAreCorrect[] {
  evidence[Expert,
    "-.file" -> "cmts/ss/ra/inspections.yaml" +
    "-.claim" -> "assume-controllers-ok",
    ManualInspection] =>
  {
    ((all c: Controller | c.observd = MachineState) and
    (all req : PollRequest |
      (let resp = request.req |
        one resp and
        resp.in req.next and
        resp.request = req and
        resp.to = req.from and
        resp.from = req.to and
        resp.settings = (resp.from.monitored <=> (resp.observd.actual)) and
        resp.observd.in resp.from.observd and
        happensMostRecentlyBefore(resp.observd, req, resp.from.observd)))
    )
  }

  -- TC correctly updates MOD1WaveformCalc for every PollResponse it receives
  -- from the given embedded controller.
  pred [ProcessPollResponsesCorrectly[controller : Controller] {
    all resp: TC.receivedMsgs & PollResponse & from.controller |
      one tcdb : TC.db & resp.next |
        -- All variables corresponding to observed machine settings are set correctly.
        resp.settings.in tcdb.actual and

        -- The therapy sum interlock bit is 0 if the actual setting value is outside of the
        -- tolerance and the override flag is not raised for that setting.
        (some setting : controller.monitored |
          tcdb.actual[setting] not in tcdb.tolerated[setting] and
          tcdb.override[setting] = False) =>
          tcdb.MOD1WaveformCalc_1 = False) and

        -- The waveform output record gets processed as part of the update.
        tcdb.MOD1IntlkOutArray_Processed = True
      )
  }

  -- If PLC relay 2754 is opened, then coil 1623 is immediately deenergized,
  -- which is immediately conveyed to HSI5 through a CoilChange message.
  pred Coil1623DeenergizedWhenRelay2754Open [] {
    evidence[PLC_Analysis,
      "-.mode" -> "all-paths-to-coil-contain-relay" +
      "-.network.file" -> "plc-code/cyclotron/mod1.stu" +
      "-.coil" -> "M1623" +
      "-.relay" -> "M2754",
      Proof] =>
    {
      all relayOpen: Relay2754.state & RelayOpen |
        some coilState: Coil1623.state & CoilDeenergized, coilChange : PLC.sentMsgs & CoilChange |
          coilState.in relayOpen.next and
          coilChange.in coilState.next and
          coilChange.coil = Coil1623 and
          coilChange.state = coilState
        )
    }
  }

  -- BeamShutsOffDueTo0Setting (
  some ms : MachineState |
    system and
    ms.actual not in Prescription.tolerated and
    not badSettingOverride[ms] and
    (some on : Beam.state & BeamOn | happensBefore[on, ms]) and
    (some off : Beam.state & BeamOff | happensBefore[ms, off]) and
    (all tcdb : TCdb | happensBefore[BeamOn, tcdb] and happensBefore[tcdb, BeamOff]) and
    (all tcdb : TCdb | lone tcdb.next & PollResponse)
  ) for 3 but 10 Event, 2 Int
}
```

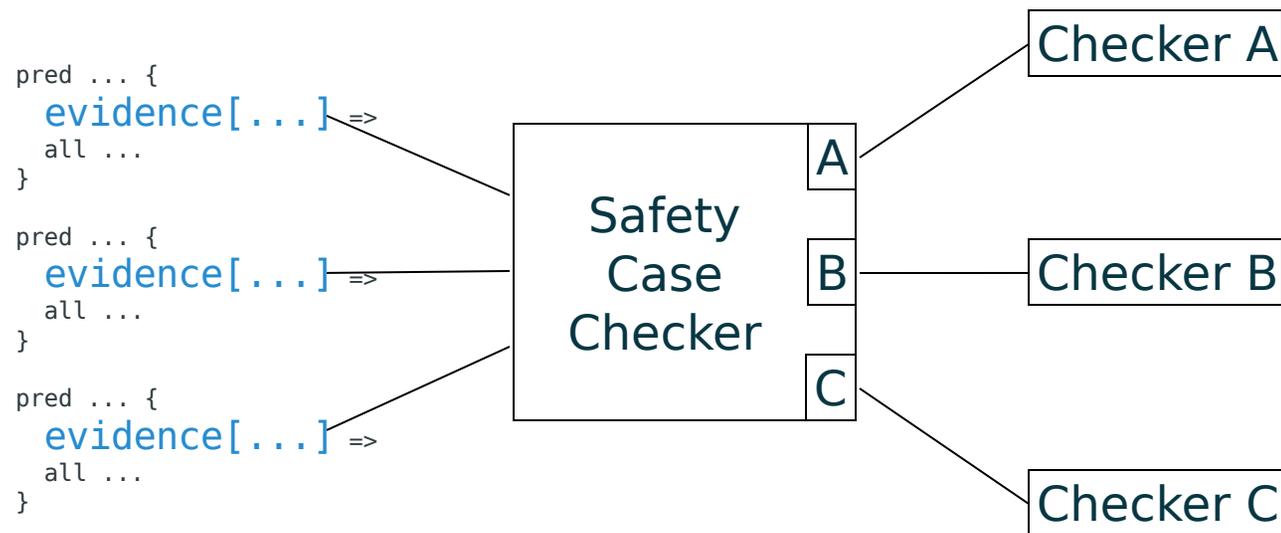
Integrating Evidence



```
pred TCRotationCheckCorrect [] {
  evidence[EPICS_SE, "--prop" -> "tc_intlk"] =>
  all reading: TC.receivedMsgs |
    reading.value not in Rx.tolerated =>
    some interlock: TC.sentMsgs & reading.next
      interlock.ok = false
}
```



Integrating Evidence



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CNTS Checkers

- EPICS linter
- EPICS verifier
- PLC checker
- EPICS-PLC connection checker
- Expert assertion checker



EPICS Verifier

Starting from an arbitrary program state,
when the therapy control program processes an event,
if the current rotation reading is out of tolerances,
it sets the Therapy Sum Interlock value to 0.

```
(define (tc_intlk)
  (process_IsoGantryActual)

  ; ...

  (assert (=>
    (> (abs (- prescribed actual)) tolerance)
    (= beam-interlock 0))))
```

EPICS Verifier



- Input/output
- Field links
- **Dynamic link modification**
- Calculation
- Array calculation
- **String manipulation**
- Process-on-init
- **Timer callbacks**
- ...

Properties:

```
.. TC correctly updates MDI:Waveform:Calc for every PollResponse it receives
pred a
.. TC correctly updates MDI:Waveform:Calc for every PollResponse it receives
.. from the given embedded controller.
pred TCProcessesPollResponsesCorrectly(controller : Controller) {
  all resp: TC.receiveMsgs & PollResponse & from.controller {
    one tcd : TC.db & resp.next {
      .. All variables corresponding to observed machine settings are set
      resp.settings in tcd.actual and

      .. The therapy sum Interlock bit is 0 if the actual setting value is
      .. tolerance and the override flag is not raised for that setting.
      ((some setting : controller.monitored {
        tcd.actual[setting] not in tcd.tolerated[setting] and
        tcd.override[setting] = False =>
        tcd.MDI_Waveform_Calc_1 = False) and

      .. The waveform output record gets processed as part of the update.
      tcd.MDI_IntLKnOutMArray_Processed = True
    }
  }
}
```

Implementation:

```
record(calc, "${ROOM}Iso"):$SUBSYSTEM:$SETTING:Calc){
  fcd
  record(calc, "${ROOM}Iso"):$SUBSYSTEM:$SETTING:Calc){
    fcd
    fcd
    record(calc, "${ROOM}Iso"):$SUBSYSTEM:$SETTING:Calc){
      field(INPA, "${ROOM}Iso"):$SUBSYSTEM:$SETTING:Prescribed")
      field(INPB, "${ROOM}Iso"):$SUBSYSTEM:$SETTING:Actual")
      field(INPC, "${ROOM}Iso"):$SUBSYSTEM:$SETTING:Tolerance")
      field(INPD, "${ROOM}Iso"):$Session:Mode") # 0 ZMAN Therapy, 1 QMAN Experiment
      field(CALC, "D72:$(CALC)") # always READY in Experiment mode, Gantry CALC is 35
      field(FLNK, "${ROOM}Iso"):$SUBSYSTEM:$SETTING:CalcAlarm")
    }
  }
}
```

Not all language features are relevant to the properties!

EPICS-PLC Connection Checker



```
mod1_intlk_outputs.db:
  record(waveform, MOD1:IntlkCnOutWArray) {
    record(DTYP, "asynInt32ArrayOut")
    field(INP, "@asyn(therapyIntlkOut_Word 0)MODBUS_DATA")
    field(FTVL, "LONG")
    field(NELM, "6")
  }
```

```
st.cmd:
  drvModbusAsynConfigure("therapyIntlkOut_Word",
    "therapyIntlkWrite", 9, 15, 2752, 6, 0, 1, "Modicon")
```

mod1.stu:



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Results

We found real bugs:

Bad gantry rotation check

Arithmetic error; *beam may fail to shut off*

Array indexing discrepancy

Off-by-one error; *beam may fail to shut off*

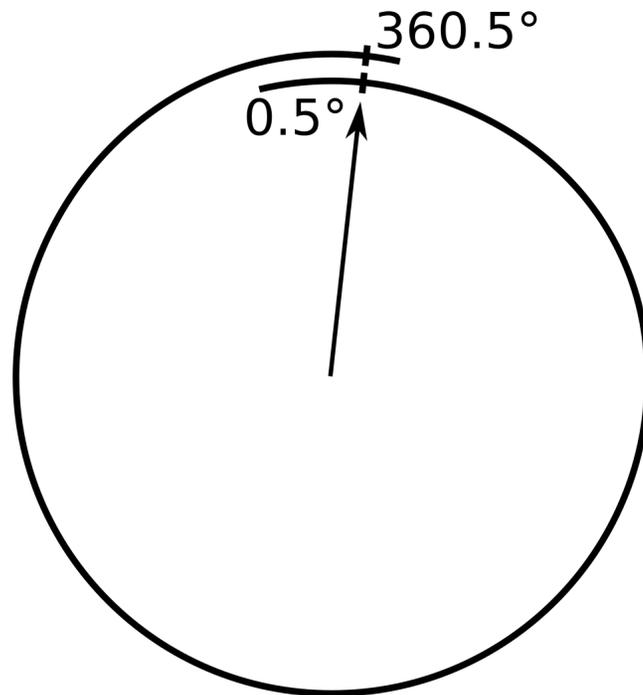
Broken dataflow links

System reads undefined values; *errors may not be reported*

Missing PLC relay

Initial system model did not correspond to reality

Gantry Rotation Bug



Gantry Rotation Bug

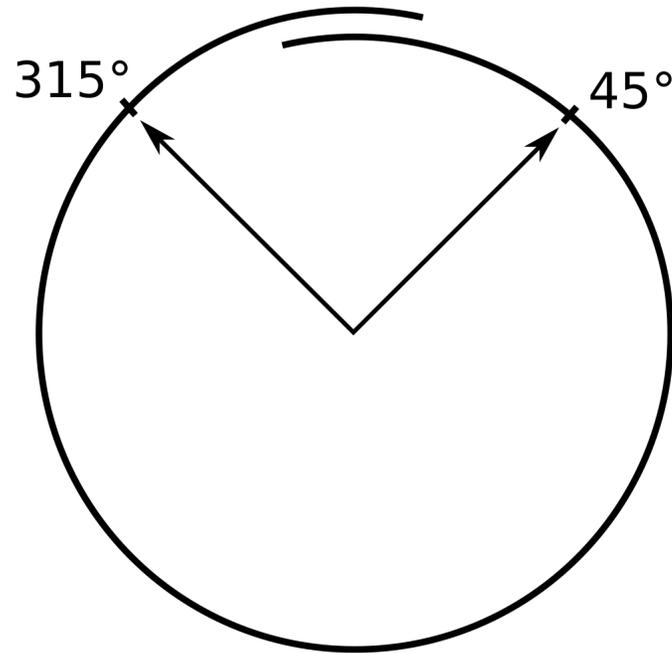
"We found a bug..."

- Something is wrong with the handling of gantry rotation
- The safety property can be violated

EPICS Verifier counterexample:

```
(("Gantry:Rotation:Prescribed" 315)  
 ("Gantry:Rotation:Actual" 45)  
 ...)
```

Gantry Rotation Bug



Gantry Rotation Bug

"We found a bug..."

- Something is wrong with the handling of gantry rotation
- The safety property can be violated

EPICS Verifier counterexample:

```
(( "Gantry:Rotation:Prescribed" 315)  
  ("Gantry:Rotation:Actual" 45)  
  ...)
```

"There appears to be an error on line 29 of
gantry_couch.substitutions..."

- We verified a real CNTS safety property using a system model and pluggable checkers
- Modeling helped guide and simplify checker development
- We found real bugs in a safety-critical system