

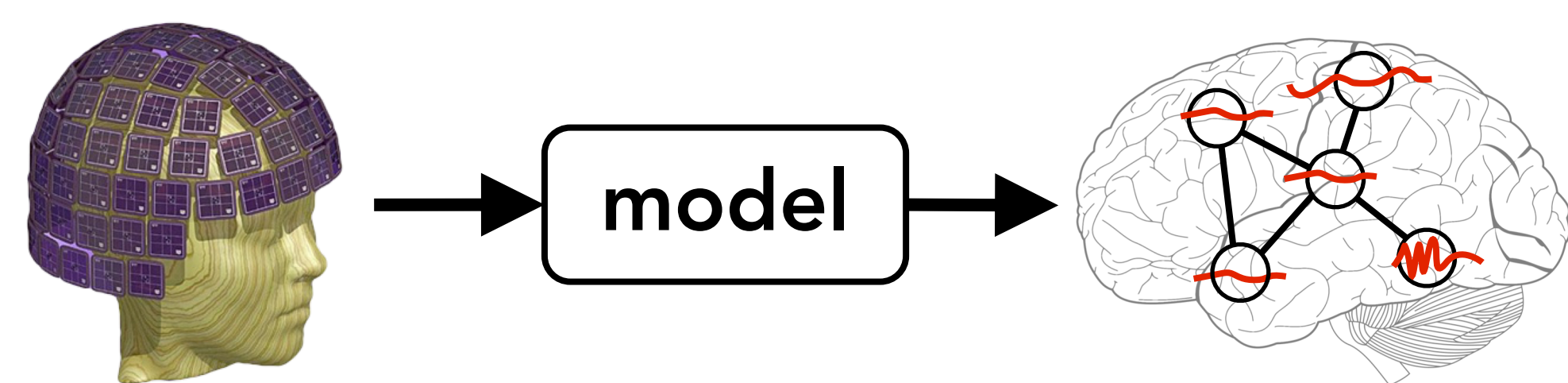
A Hierarchical State-Space Model with Gaussian Process Dynamics for Functional Connectivity Estimation

Rahul Nadkarni (rahuln@cs.washington.edu), Nicholas J. Foti (nfoti@uw.edu), Adrian KC Lee (akclee@uw.edu), Emily B. Fox (ebfox@uw.edu)

Goal

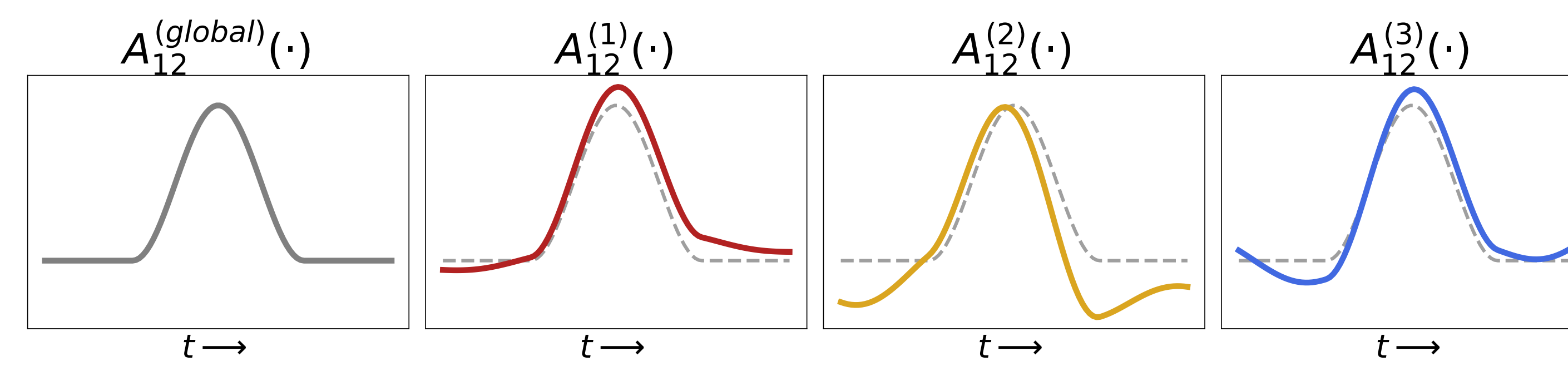
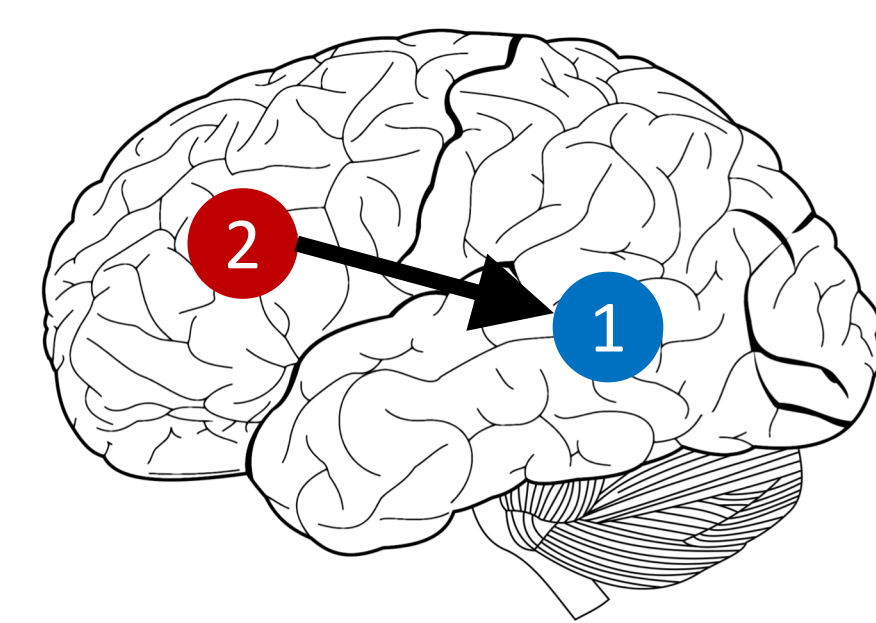
- We present an approach for learning directed, dynamic functional interactions between brain regions across multiple subjects from magnetoencephalography (MEG) data
- We pool subjects' data to learn a group-level connectivity structure while also modeling interesting subject-specific differences
- Our method incorporates Gaussian processes to model functional connections that are smoothly time-varying while capturing estimation uncertainty

Problem setup



- Obtain MEG sensor recordings y from multiple subjects performing a task
- Observation model – which includes forward model (lead field matrix) C and sensor noise covariance R – is known (i.e., can be calculated) for each subject
- Goal is to infer time-varying, directed functional interactions between a specified set of brain regions of interest (ROIs) using sensor recordings and observation model for each subject

Description of model



Example of global time-varying connection with subject-specific variation

$$A_{ij}^{(global)}(\cdot) \sim \mathcal{GP}(I_{ij}, k_0)$$

$$A_{ij}^{(s)}(\cdot) \sim \mathcal{GP}(A_{ij}^{(global)}(\cdot), k_1), s = 1, \dots, \# \text{ subjects}$$

$$x_{t+1}^{(s)} = A^{(s)}(t) x_t^{(s)} + \epsilon_t^{(s)}, \epsilon_t^{(s)} \sim \mathcal{N}(0, Q) \leftarrow \text{ROIs}$$

$$y_t^{(s)} = C^{(s)} x_t^{(s)} + \eta_t^{(s)}, \eta_t^{(s)} \sim \mathcal{N}(0, R^{(s)}) \leftarrow \text{sensors}$$

$\mathcal{GP}(m, k)$ is a Gaussian process with mean function m and covariance function k . We use the squared exponential kernel:

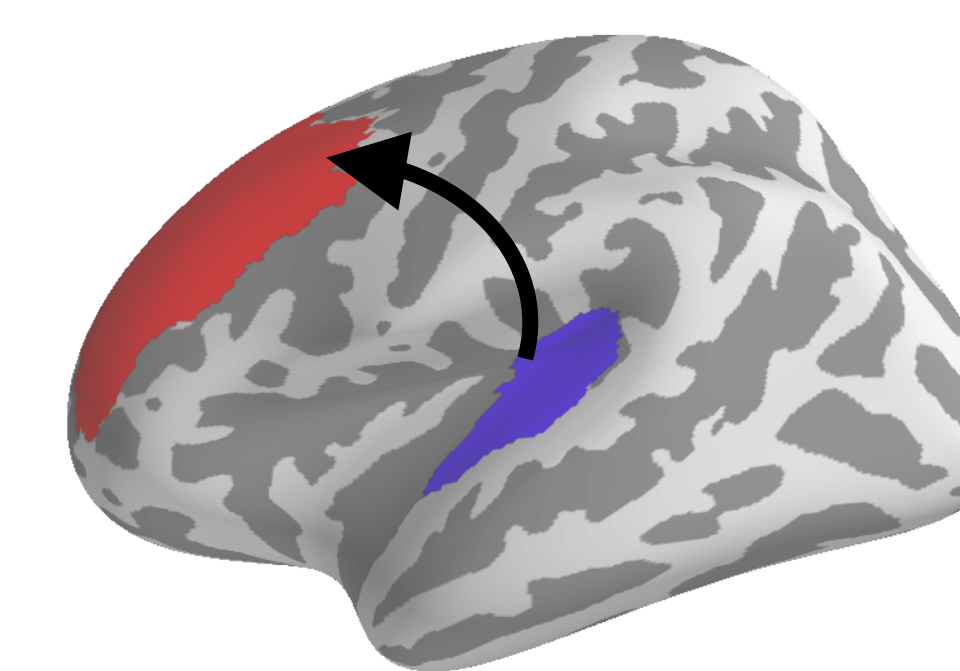
$$k(t_i, t_j) = \sigma^2 \exp(-d(t_i - t_j)^2)$$

- Sensor values $y_t^{(s)}$ and observation model $C^{(s)}, R^{(s)}$ known for each subject
- ROI dynamics $A^{(s)}(t)$, $A^{(global)}(t)$ and noise Q unknown, inferred via Gibbs sampling
- Entries of $A(t)$ indicate strength of directed interaction between regions over time

Inference

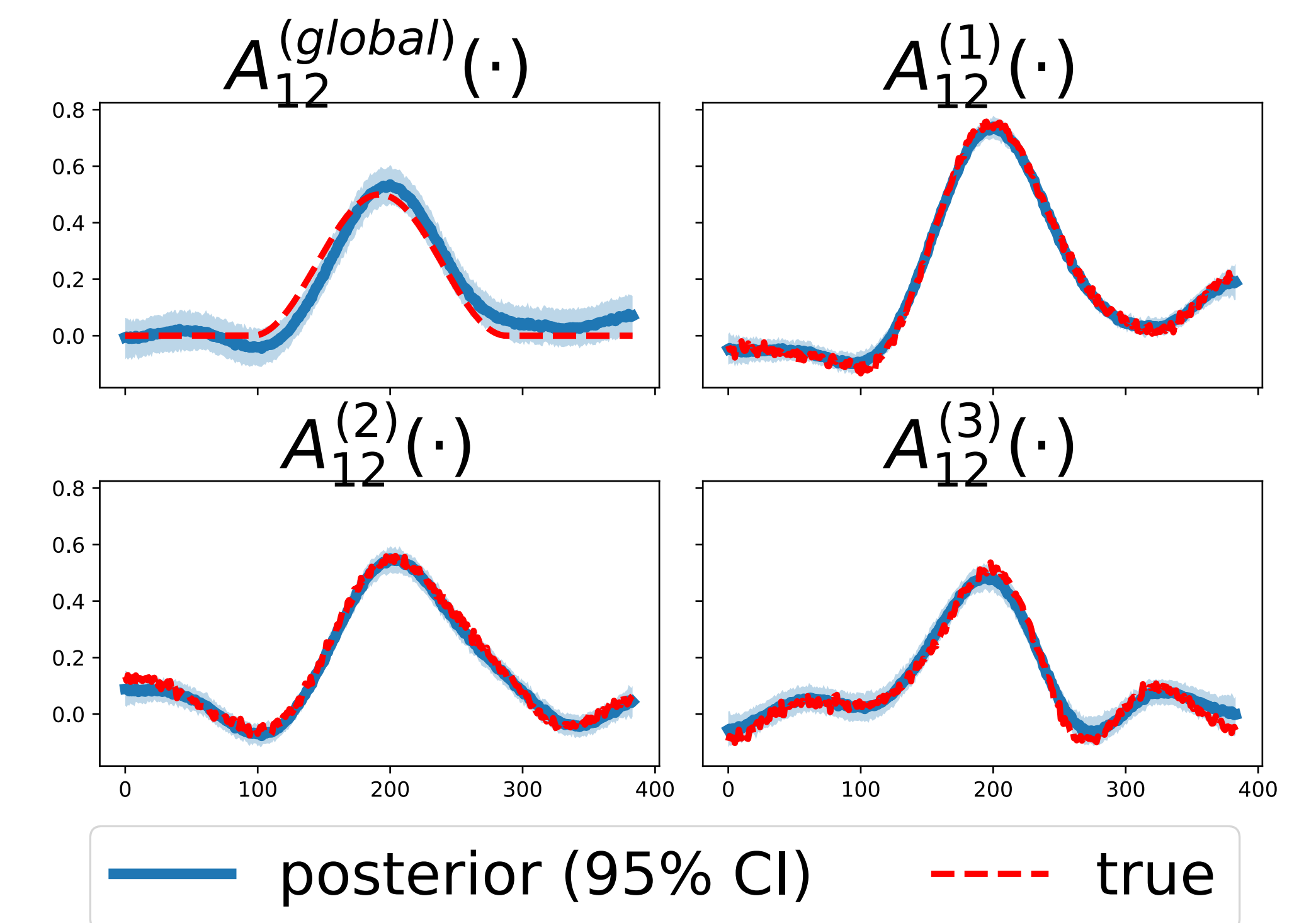
- Gibbs sampling with iterative approximation methods for efficient sampling from posterior of $A^{(s)}(t)$
 - Conjugate gradient (CG): $\Sigma, x \rightarrow$ approximation to $\Sigma^{-1}x$ used for $\mu_A = \mathbb{E}[A_{ij}^{(s)}(\cdot) | \text{rest}]$
 - Lanczos algorithm: $\Sigma^{-1}, x \rightarrow$ approximation to $\Sigma^{1/2}x$ Used to sample from $\mathcal{N}(0, \Sigma)$
 - Given $\Sigma_A^{-1} = [\text{Cov}(A_{ij}^{(s)}(\cdot) | \text{rest})]^{-1}$: CG to construct μ_A Lanczos to generate $\epsilon_A \sim \mathcal{N}(0, \Sigma_A)$ Construct sample $\mu_A + \epsilon_A$

Simulation experiments



- Sensor data simulated from hierarchical model for 3 subjects and 2 ROIs (above), using real MEG forward model $C^{(s)}$ and sensor noise covariance $R^{(s)}$ for each subject
- Simulated dynamics $A^{(global)}(t)$ constructed to include a time-varying interaction from one ROI (blue) directed towards the other (red)

Results



- Hierarchical model is able to learn global dynamic connectivity structure (top left) as well as subject-specific variation (other subplots)
- Bayesian inference allows the model to capture uncertainty in the time-varying connectivity (blue band shows 95% CI)

Future directions

- Application to real MEG data recorded from multiple subjects performing an auditory attention task (analysis ongoing)
- Incorporating subject-specific auxiliary data (e.g., behavioral and cognitive assessments, audiological test results, subjective questionnaire answers)