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VeRSA

Verifiable Registries with Efficient Client Audits from RSA Authenticated Dictionaries

Nirvan TyagiBen FischAndrew ZitekJoseph BonneauStefano Tessaro

Applications: certificate transparency, key transparency, binary transparency, etc.



e.g. public key identities software binary checksums domain name routing info



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Previous approaches: Trusted third-party auditors [CONIKS'15, SEEMLess'19, Mog'20]

New digests published over time



Trusted third-party auditors verify **version-only** invariant is preserved between digests. Invariant allows efficient detection of unexpected changes by user.

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[CONIKS '15, SEEMless '19, Mog '20, Verdict '21]



To obtain succinct invariant proofs over a range of digests, we compress the Merkle paths proof into a generic-circuit SNARK, which enables SNARK recursion/aggregation.

[CONIKS '15, SEEMless '19, Mog '20, Verdict '21]

must be included.



Our work: Invariant proofs for RSA KV commitments

[AR Asiacrypt '20]





Constant-size and constant-verif invariant proof! Using variant of proof of knowledge of integer exponentiation [Wesolowski '19][BBF '19]





Our work: Invariant proofs for RSA KV commitments



Constant circuit size independent of number of key updates.

Contribution 1

New RSA key-value commitment with succinct proofs that invariant is preserved over ranges of digests

Contribution 2

Checkpointing technique to ensure user views remain eventually consistent even when auditing distinct ranges of digests

- When auditing a range, users additionally audit logarithmic checkpoints within range
- Two users are guaranteed to eventually share checkpoints and will be able to detect inconsistencies if they exist

Inconsistent user views: Oscillation attacks



[Mog²0]



- An invariant proof is verified for a sequence of "checkpoints". The number of checkpoints between two digests is logarithmic in the size of the range.



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Alice								
Bob	0	0 (0	00		

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Alice



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Shared checkpoints between overlapping ranges guaranteed to exist – see paper!

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Implementation and performance evaluation

- RSA key-value commitment and invariant proofs
- R1CS constraints for RSA algorithms in arkworks ecosystem for zkSNARKs
- Open source: github.com/nirvantyagi/versa

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Comparison to Merkle Tree baseline: Server with 32 CPU cores + 512 GB memory

- Client verification costs: similar
 - Proofs < 20kB, verify in < 100ms
- **Update proof throughput:** 10x-400x higher
 - Prototype achieves 60-90 updates/second on a single server
- Lookup proof costs: substantially worse
 - VeRSA limited to registries of ~millions of entries due to $O(n^2)$ costs
 - Millions of entries can be handled with O(nlogn) batch computation costs

Potential application: binary transparency

Characteristics:

- Medium overall registry size
- Relatively high update frequency
- Moderate latency is acceptable (~30 minutes)

Examples:

- Ubuntu package repo: 106k packages, mean 3.4 versions/year
- Apple iOS app store: 2.1M apps, mean 52.5 versions/year

Conclusion

- VeRSA: New design for verifiable registry enabling efficient client-auditing
 - New RSA key-value commitments and constant-size invariant proofs
 - New client auditing approach that maintains eventual consistency
- Suitable for binary transparency applications with medium-size registries
 - Bottleneck: RSA lookup proof computation
- Open source: github.com/nirvantyagi/versa

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Backup slides

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Invariant proofs: RSA key-value commitments [AR'20]

Digest
$$d_i = (d_{i,1}, d_{i,2}) = (g^{(\prod_j H(k_j)^{ver_j}) \cdot (\sum_j val_j / H(k_j))}, g^{\prod_j H(k_j)^{ver_j}})$$

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 $d_i \longrightarrow d_{i+1} = (d_{i+1,1}, d_{i+1,2}) = (d_{i,1}^{H(k_2)} d_{i,2}^{\delta}, d_{i,2}^{H(k_2)})$
where $\delta = val'_2 - val_2$

Invariant proofs: RSA key-value commitments

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Digest $d_i = (d_{i,1}, d_{i,2}) = \left(g^{(\prod_j H(k_j)^{ver_j}) \cdot (\sum_j val_j/H(k_j))}, g^{\prod_j H(k_j)^{ver_j}}\right)$

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$$d_i \longrightarrow d_{i+1} : d_{i+1} = (d_{i+1,1}, d_{i+1,2}) = \left(d_{i,1}^Z d_{i,2}^{\Delta}, d_{i,2}^Z\right)$$
where $\Delta = (\prod_j H(k_j)) \cdot (\sum_j \delta_j/H(k_j))$

$$Z = \prod_j H(k_j) \quad \text{for } j \in \{1, 2, 3\}$$

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Committed joint view



Bob

Committed joint view



Committed joint view



Committed joint view





Committed joint view





Committed joint view





Checkpointing allows users to implicitly create an ordered consistent view that trails the current time step.



Checkpoints are determined by the minimum number of subtrees that span the range in the superimposed binary tree -- guaranteed to be logarithmic in range size^{§8}